

## Outline

- 1) Syllabus
- 2) Measure theory basics

# Measure theory basics

Measure theory is a rigorous grounding for probability theory [subject of 205A]

Simplifies notation & clarifies concepts, especially around integration & conditioning [Pset 0]

Given a set  $X$ , a measure  $\mu$  maps subsets  $A \subseteq X$  to non-negative numbers  $\mu(A) \in [0, \infty]$

Example  $X$  countable (e.g.  $X = \mathbb{Z}$ )

Counting measure  $\#(A) = \# \text{ points in } A$

Example  $X = \mathbb{R}^n$

Lebesgue measure  $\lambda(A) = \int_A \dots \int dx_1 \dots dx_n$   
 $= \text{Volume}(A)$

Standard Gaussian distribution:

$$\begin{aligned} P(A) &= \mathbb{P}(Z \in A) \quad \text{where } Z \sim N(0, 1) \\ &= \int_A \phi(x) dx \quad \phi(x) = \frac{e^{-x^2/2}}{\sqrt{2\pi}} \end{aligned}$$

NB Because of pathological sets,  $\lambda(A)$  can only be defined for certain subsets  $A \subseteq \mathbb{R}^n$  [HW 0, Prob. 3]

In general, the domain of a measure  $\mu$  is a collection of subsets  $\mathcal{F} \subseteq 2^X$  (power set)

$\mathcal{F}$  must be a  $\sigma$ -field meaning it satisfies certain closure properties (not important for us)

Ex:  $X$  countable,  $\mathcal{F} = 2^X$

Ex:  $X = \mathbb{R}^n$ ,  $\mathcal{F} = \text{Borel } \sigma\text{-field } \mathcal{B}$

$\mathcal{B} = \text{smallest } \sigma\text{-field including all open rectangles}$   
 $(a_1, b_1) \times \dots \times (a_n, b_n) \quad a_i < b_i \quad \forall i$

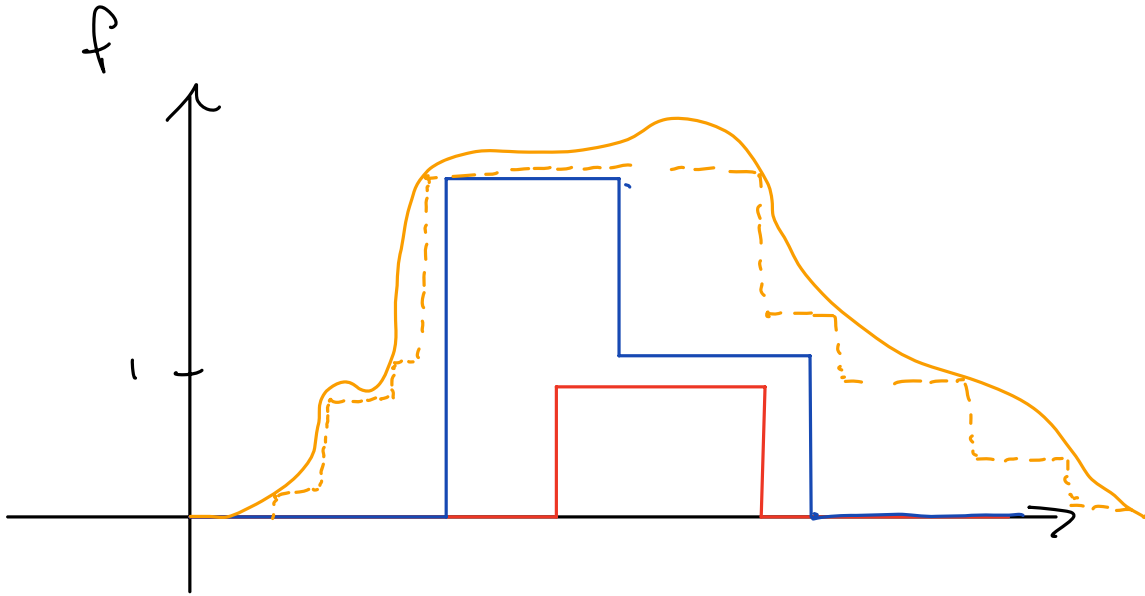
Given a measurable space  $(X, \mathcal{F})$  a measure is a map  $\mu: \mathcal{F} \rightarrow [0, \infty]$  with

$$\mu\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mu(A_i) \quad \text{for disjoint } A_1, A_2, \dots \in \mathcal{F}$$

$\mu$  probability measure if  $\mu(X) = 1$

Measures let us define integrals that put weight  $\mu(A)$  on  $A \subseteq X$

Define  $\int 1_{\{x \in A\}} d\mu(x) = \mu(A)$ , extend to other functions by linearity & limits:



Indicator  $\int 1_{\{x \in A\}} d\mu(x) = \mu(A)$

Simple Function  $\int \left( \sum c_i 1_{\{x \in A_i\}} \right) d\mu(x) = \sum c_i \mu(A_i)$

"Nice enough" (measurable) function  $\int f(x) d\mu(x)$  approximated by simple functions

Examples:

Counting:  $\int f d\# = \sum_{x \in X} f(x)$

Lebesgue:  $\int f d\lambda = \int \dots \int f(x) dx_1 \dots dx_n$

Gaussian:  $\int f dP = \int f(x) \phi(x) dx = \mathbb{E}[f(Z)]$

To evaluate  $\int f dP$  rewrite as  $\int f \phi dx$ .   
 density [can't always do this]   
 eg. Binom

# Densities

$\lambda$  and  $P$  above are closely related. Want to make this precise.

Given  $(X, \mathcal{F})$ , two measures  $P, \mu$

We say  $P$  is absolutely continuous wrt  $\mu$

if  $P(A) = 0$  whenever  $\mu(A) = 0$

Notation:  $P \ll \mu$  or we say  $\mu$  dominates  $P$

If  $P \ll \mu$  then (under mild conditions) we can always define a density function

$p: X \rightarrow [0, \infty)$  with

$$P(A) = \int_A p(x) d\mu(x)$$

$$\int f(x) dP(x) = \int f(x) p(x) d\mu(x)$$

Sometimes written  $p(x) = \frac{dP}{d\mu}(x)$ , called  
Radon - Nikodym derivative

Useful to turn  $\int f dP$  into  $\int f p d\mu$  if we know how to calculate integrals  $d\mu$

If  $P$  prob.,  $\mu$  Lebesgue:

$p(x)$  called prob. density fcn (pdf)

If  $P$  prob.,  $\mu$  counting:

$p(x)$  called prob. mass fcn (pmf)

# Probability Space, Random Variables

Typically, we set up a problem with multiple random variables having various relationships to one another, convenient to think of them as functions of an abstract "outcome"  $\omega$

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space

$\omega \in \Omega$  called outcome

$A \in \mathcal{F}$  called event

$\mathbb{P}(A)$  called probability of A

A random variable is a function  $X: \Omega \rightarrow \mathcal{X}$

We say  $X$  has distribution  $Q$  ( $X \sim Q$ )

$$\text{if } \mathbb{P}(X \in B) = \mathbb{P}(\{\omega: X(\omega) \in B\}) \\ = Q(B)$$

More generally, could write events involving many R.V.s:

$$\mathbb{P}(X > Y > Z \geq 0) = \mathbb{P}(\{\omega: \dots\})$$

The expectation is an integral w.r.t.  $\mathbb{P}$

$$\mathbb{E}[f(X, Y)] = \int_{\Omega} f(X(\omega), Y(\omega)) d\mathbb{P}(\omega)$$

To do real calculations we must eventually boil  
 $\mathbb{P}$  or  $\mathbb{E}$  down to concrete integrals/sums/etc.

If  $\mathbb{P}(A) = 1$  we say  $A$  occurs almost surely

More in Keener ch. 1, much more in Stat 205A