

Probability Lecture III (August, 2006)

1 Some Properties of Random Vectors and Matrices

We generalize univariate notions in this section.

Definition 1 Let $\mathbf{U} = ||U_{ij}||_{k \times l}$, a matrix of random variables. Suppose $E|U_{ij}| < \infty$ for all i, j . Define the expectation of \mathbf{U} by

$$E(\mathbf{U}) = (E(U_{ij}))_{k \times l}.$$

The following are some properties of random vectors:

Let \mathbf{U} , respectively \mathbf{V} , denote a random k , respectively l , vector.

1. If $\mathbf{A}_{m \times k}$, $\mathbf{B}_{m \times l}$ are nonrandom and $E\mathbf{U}$, $E\mathbf{V}$ are defined, then

$$E(\mathbf{AU} + \mathbf{BV}) = \mathbf{A}E(\mathbf{U}) + \mathbf{B}E(\mathbf{V}).$$

Definition 2 For a random vector \mathbf{U} , suppose $EU_i^2 < \infty$ for $i = 1, \dots, k$ or equivalently $E(|\mathbf{U}|^2) < \infty$, where $|\cdot|$ denotes Euclidean distance. Define the variance of \mathbf{U} , often called the variance-covariance matrix, by

$$\begin{aligned} \text{Var}(\mathbf{U}) &= E(\mathbf{U} - E(\mathbf{U}))(\mathbf{U} - E(\mathbf{U}))^T \\ &= (\text{Cov}(U_i, U_j))_{k \times k} \end{aligned}$$

a symmetric matrix.

2. If \mathbf{A} is $m \times k$ as before,

$$\text{Var}(\mathbf{AU}) = \mathbf{A} \text{Var}(\mathbf{U}) \mathbf{A}^T.$$

Note that $\text{Var}(\mathbf{U})$ is $k \times k$, $\text{Var}(\mathbf{AU})$ is $m \times m$.

3. Let $\mathbf{c}_{k \times 1}$ denote a constant vector. Then

$$\text{Var}(\mathbf{U} + \mathbf{c}) = \text{Var}(\mathbf{U}).$$

$$\text{Var}(\mathbf{c}) = (0)_{k \times k}.$$

4. The variance of any random vector is *nonnegative definite symmetric matrix*.

To see this, note that if $\mathbf{a}_{k \times 1}$ is constant we can apply $\text{Var}(\mathbf{AU}) = \mathbf{A} \text{Var}(\mathbf{U}) \mathbf{A}^T$ to obtain

$$\begin{aligned} \text{Var}(\mathbf{a}^T \mathbf{U}) &= \text{Var}(\sum_{j=1}^k a_j U_j) \\ &= \mathbf{a}^T \text{Var}(\mathbf{U}) \mathbf{a} = \sum_{i,j} a_i a_j \text{Cov}(U_i, U_j). \end{aligned}$$

Because the variance of any random variable is nonnegative and \mathbf{a} is arbitrary, we conclude from the above equalities that $\text{Var}(\mathbf{U})$ is a *nonnegative definite symmetric matrix*.

Definition 3 Define the moment generating function (m.g.f.) of $\mathbf{U}_{k \times 1}$ for $\mathbf{t} \in R^k$ by

$$M(\mathbf{t}) = M_{\mathbf{U}}(\mathbf{t}) = E(e^{\mathbf{t}^T \mathbf{U}}) = E(e^{\sum_{j=1}^k t_j U_j}).$$

5. If $\mathbf{U}_{k \times 1}$, $\mathbf{V}_{k \times 1}$ are independent then

$$M_{\mathbf{U} + \mathbf{V}}(\mathbf{t}) = M_{\mathbf{U}}(\mathbf{t}) M_{\mathbf{V}}(\mathbf{t}).$$

2 The Bivariate Normal Distribution

The family of k -variate normal distributions arises on theoretical grounds when we consider the limiting behavior of sums of independent k -vectors of random variables. In this section we focus on the case $k = 2$ where all properties can be derived relative easily.

A planar vector (X, Y) has a *bivariate normal distribution* if, and only if, there exist constants $a_{ij}, 1 \leq i, j \leq 2, \mu_1, \mu_2$, and independent standard normal random variables Z_1, Z_2 such that

$$\begin{aligned} X &= \mu_1 + a_{11}Z_1 + a_{12}Z_2 \\ Y &= \mu_2 + a_{21}Z_1 + a_{22}Z_2. \end{aligned}$$

In matrix notation, if $\mathbf{A} = (a_{ij}), \mu = (\mu_1, \mu_2)^T, \mathbf{X} = (X, Y)^T, \mathbf{Z} = (Z_1, Z_2)^T$, the definition is equivalent to

$$\mathbf{X} = \mathbf{AZ} + \mu. \quad (1)$$

Two important properties follow from the definition.

Proposition 4 *The marginal distributions of the components of a bivariate normal random vector are (univariate) normal or degenerate (concentrate on one point).*

Note that the converse of the proposition is not true (See problem B.4.10 in Bickel and Doksum [2001]). Also, note that

$$E(X) = \mu_1 + a_{11}E(Z_1) + a_{12}E(Z_2) = \mu_1, \quad E(Y) = \mu_2$$

and define

$$\sigma_1 = \sqrt{\text{Var } X}, \quad \sigma_2 = \sqrt{\text{Var } Y}.$$

Then X has $\mathcal{N}(\mu_1, \sigma_1^2)$ and Y a $\mathcal{N}(\mu_2, \sigma_2^2)$ distribution.

Proposition 5 *If we apply an affine transformation $\mathbf{g}(x) = \mathbf{C}x + \mathbf{d}$ to a vector \mathbf{X} , which has a bivariate normal distribution, then $\mathbf{g}(\mathbf{X})$ also has such a distribution.*

This is clear because

$$\mathbf{CX} + \mathbf{d} = \mathbf{C}(\mathbf{AZ} + \mu) + \mathbf{d} = (\mathbf{CA})\mathbf{Z} + (\mathbf{C}\mu + \mathbf{d}). \quad (2)$$

We define the *variance-covariance matrix* of (X, Y) (or of the distribution of (X, Y)) as the matrix of central second moments

$$\Sigma = \begin{pmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{pmatrix}, \quad (3)$$

where

$$\rho = \text{Cor}(X, Y) = \frac{\text{Cov}(X, Y)}{\sigma_1\sigma_2}.$$

This symmetric matrix is in many ways the right generalization of the variance to two dimensions.

Theorem 6 *Suppose that $\sigma_1\sigma_2 \neq 0$ and $|\rho| < 1$. Then the density of \mathbf{X} is*

$$p_{\mathbf{X}}(\mathbf{x}) = \frac{1}{2\pi\sqrt{\det \Sigma}} \exp\left(-\frac{1}{2}(\mathbf{x} - \mu)^T \Sigma^{-1}(\mathbf{x} - \mu)\right). \quad (4)$$

Remark 7 *From (3) we see that Σ is nonsingular iff $\sigma_1\sigma_2 \neq 0$ and $|\rho| < 1$. Bivariate normal distribution with $\sigma_1\sigma_2 \neq 0$ and $|\rho| < 1$ are referred to as nondegenerate, whereas others are degenerate.*

Remark 8 When $\rho = 0$, $p_{\mathbf{X}}(\mathbf{x})$ becomes the joint density of two independent normal variables. Thus, in the bivariate normal case, correlation zero is equivalent to independence.

Exercise 9 Given nonnegative constants σ_1, σ_2 , a number ρ such that $|\rho| < 1$ and numbers μ_1, μ_2 , construct a random vector $(X, Y)^T$, where

$$X = \mu_1 + \sigma_1 Z_1, \quad Y = \mu_2 + \sigma_2(\rho Z_1 + \sqrt{1 - \rho^2} Z_2)$$

Check that $(X, Y)^T$ has a bivariate normal distribution with vector of means $(\mu_1, \mu_2)^T$ and variance-covariance matrix Σ as given in (3).

3 Convergence in Probability v.s. in Distribution

3.0.1 Chebyshev's inequality

If X is any random variable and a is a constant, then

$$P(|X| \geq a) \leq \frac{E(X^2)}{a^2}.$$

3.1 Convergence in Probability

Definition 10 If a sequence of random variables, $\{Z_n\}$, is such that $P(|Z_n - \alpha| > \varepsilon)$ approaches zero as n approaches infinity, for any $\varepsilon > 0$ and where α is some scalar, then Z_n is said to converge in probability to α .

Definition 11 A sequence of random vectors $\mathbf{Z}_n \equiv (Z_{n1}, Z_{n2}, \dots, Z_{nd})^T$ converges in probability to $\mathbf{Z} \equiv (Z_1, Z_2, \dots, Z_d)^T$ iff

$$|\mathbf{Z}_n - \mathbf{Z}| \xrightarrow{\mathcal{P}} 0$$

or equivalently $Z_{nj} \xrightarrow{\mathcal{P}} Z_j$ for $1 \leq j \leq d$.

3.1.1 A Law of Large Numbers

Theorem 12 Example 13 Let $X_1, X_2, \dots, X_i, \dots$ be a sequence of independent random variables with $E(X_i) = \mu$ and $\text{Var}(X_i) = \sigma^2$. Let $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$. Then, for any $\varepsilon > 0$,

$$P(|\bar{X}_n - \mu| > \varepsilon) \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

Proof. We first find $E(\bar{X}_n)$ and $\text{Var}(\bar{X}_n)$:

$$E(\bar{X}_n) = \frac{1}{n} \sum_{i=1}^n E(X_i) = \mu$$

Since the X_i are independent,

$$\text{Var}(\bar{X}_n) = \frac{1}{n^2} \sum_{i=1}^n \text{Var}(X_i) = \frac{\sigma^2}{n}$$

The desired result now follows immediately from Chebyshev's inequality, which states that

$$P(|\bar{X}_n - \mu| > \varepsilon) \leq \frac{\text{Var}(\bar{X}_n)}{\varepsilon^2} = \frac{\sigma^2}{n\varepsilon^2} \rightarrow 0, \quad \text{as } n \rightarrow \infty$$

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3.2 Convergence in Distribution

Definition 14 Let X_1, X_2, \dots be a sequence of random variables with cumulative distribution functions F_1, F_2, \dots , and let X be a random variable with distribution function F . We say that X_n converges in distribution to X if

$$\lim_{n \rightarrow \infty} F_n(x) = F(x)$$

at every point at which F is continuous.

Definition 15 A sequence $\{\mathbf{Z}_n\}$ of random vectors converges in law (in distribution) to \mathbf{Z} , written $\mathbf{Z}_n \rightarrow \mathbf{Z}$, iff

$$h(\mathbf{Z}_n) \xrightarrow{\mathcal{L}} h(\mathbf{Z})$$

for all functions $h : \mathbf{R}^d \rightarrow \mathbf{R}$, h continuous.

3.2.1 Central Limit Theorem

Theorem 16 The Multivariate Central Limit Theorem. Let $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_n$ be independent and identically distributed random k vectors with $E|\mathbf{X}_1|^2 < \infty$. Let $E(\mathbf{X}_1) = \mu$, $\text{Var}(\mathbf{X}_1) = \Sigma$, and let $\mathbf{S}_n = \sum_{i=1}^n \mathbf{X}_i$. Then, for every continuous function $g : \mathbf{R}^k \rightarrow \mathbf{R}$,

$$g\left(\frac{\mathbf{S}_n - n\mu}{\sqrt{n}}\right) \xrightarrow{\mathcal{L}} g(\mathbf{Z})$$

where $\mathbf{Z} \sim \mathcal{N}_k(\mathbf{0}, \Sigma)$.

3.2.2 The O_P , \asymp , and o_P Notation

The following asymptotic order in probability notation is useful.

$$\begin{aligned} \mathbf{U}_n &= o_P(1) \text{ iff } \mathbf{U}_n \xrightarrow{P} 0 \\ \mathbf{U}_n &= O_P(1) \text{ iff } \forall \epsilon > 0, \exists M < \infty \text{ such that } \forall n \quad P[|\mathbf{U}_n| \geq M] \leq \epsilon \\ \mathbf{U}_n &= o_P(\mathbf{V}_n) \text{ iff } \frac{|\mathbf{U}_n|}{|\mathbf{V}_n|} = o_P(1) \\ \mathbf{U}_n &= O_P(\mathbf{V}_n) \text{ iff } \frac{|\mathbf{U}_n|}{|\mathbf{V}_n|} = O_P(1) \\ \mathbf{U}_n &\asymp_p \mathbf{V}_n \text{ iff } \mathbf{U}_n = O_P(\mathbf{V}_n) \text{ and } \mathbf{V}_n = O_P(\mathbf{U}_n). \end{aligned}$$

Note that

$$O_P(1)o_P(1) = o_P(1), \quad O_P(1) + o_P(1) = O_P(1),$$

and $\mathbf{U}_n \xrightarrow{\mathcal{L}} \mathbf{U} \implies \mathbf{U}_n = O_P(1)$.

Example 17 Suppose $\mathbf{Z}_1, \mathbf{Z}_2, \dots, \mathbf{Z}_n$ are iid as \mathbf{Z}_1 with $E|\mathbf{Z}_1|^2 < \infty$. Set $\mu = E|\mathbf{Z}_1|$, then $\bar{\mathbf{Z}}_n = \mu + O_p(n^{-\frac{1}{2}})$ by the central limit theorem.

Exercise 18 Let X_i be the last digit of D_i^2 , where D_i is a random digit between 0 and 9. For instance, if $D_i = 7$ then $D_i^2 = 49$ and $X_i = 9$. Let $\bar{X}_n = (X_1 + \dots + X_n)/n$ be the average of a large number n of such last digits, obtained from independent random digits D_1, \dots, D_n .

- a) Predict the value of \bar{X}_n for large n .
- b) Find a number ϵ such that for $n = 10,000$ the chance that your prediction is off by more than ϵ is about 1 in 200.
- c) Find approximately the least value of n such that your prediction of \bar{X}_n is correct to within 0.01 with probability at least 0.99.
- d) Which can be predicted more accurately for large n : the value of \bar{X}_n , or the value of $\bar{D}_n = (D_1 + \cdots + D_n)/n$?
- e) If you just had to predict the first digit of \bar{X}_{100} , what digit should you choose to maximize your chance of being correct, and what is that chance?

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