Evaluating treatment efficacy in vaccine clinical trials with two-phase designs via stochastic-interventional causal effects

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Immune Correlates of HIV-1 and COVID-19

The Fights Against HIV-1 and COVID-19

- The HIV-1 epidemic:
 - 1.5 million new infections occurring annually worldwide;
 - new infections outpace patients starting antiretroviral therapy;
 - HIV Vaccine Trials Network's (HVTN) 505 trial evaluated a novel antibody boost vaccine (Hammer et al. 2013).
- The COVID-19 epi pan endemic (Antia and Halloran 2021):
 - 270 331 619 million total cases have been detected globally;
 - new variants emerging, with vaccine uptake globally slowing;
 - COVID-19 Prevention Network's (CoVPN) COVE trial focused on Moderna's (mRNA-1273) vaccine (Baden et al. 2021).

Evaluating Vaccines for HIV-1 and COVID-19

- 505: How would HIV-1 infection risk have differed had the boost vaccine modulated immunogenic responses differently?
- COVE: How would COVID-19 disease rate have differed for alternative vaccine-induced immunogenic response profiles?
- Question: How can [HIV-1, COVID-19] vaccines be improved through modulating immunogenic response profiles?

Why Measure and Analyze Immune Correlates?

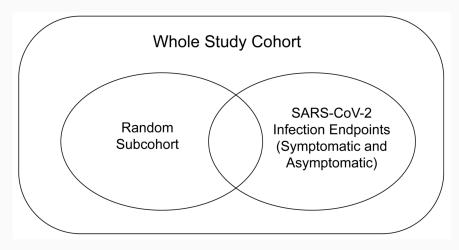
- Two, interrelated goals of vaccine correlates analyses are to
 - identify/validate possible surrogate endpoints (Prentice 1989);
 - understand protective mechanisms of vaccines.
- If an immune correlate is established to reliably predict VE, subsequent efficacy trials may use it as a primary endpoint.
- This may accelerate the approval of
 - existing vaccines in different populations (e.g., in children);
 - new vaccines within the same class.

Measuring Correlates: Two-Phase Designs

- Often, use case-cohort design (Prentice 1986), a special case of two-phase sampling (Breslow et al. 2003).
- Phase 1: measure baseline, vaccination, endpoint on everyone.
- Phase 2: given baseline, vaccine, endpoint, select members of immune response subcohort with (possibly known) probability.
 - 505: second-phase sample with 100% of HIV-1 cases and matching of non-cases (n = 189 per Janes et al. 2017)).
 - *COVE*: stratified random subcohort ($n \approx 1600$) and all SARS-CoV-2 infection and COVID-19 disease endpoints.

A Simple Two-Phase Design: Case-Cohort

Assaying >30k samples is expensive, statistically unnecessary.



Case-cohort design, per Prentice (1986), as applied to COVE.

Two-phase Sampling Masks the Complete Data Structure

- Complete (unobserved) data $X = (L, A, S, Y) \sim P_0^X \in \mathcal{M}$:
 - L (baseline covariates): sex, age, BMI, behavioral HIV risk,
 - A (treatment): randomized assignment to vaccine/placebo,
 - S (exposure): immune response profile for relevant markers,
 - Y (outcome of interest): infection status at trial's end.
- Observed data $O = (B, BX) = (L, B, BS, Y) \sim P_0 \in \mathcal{M}$.
 - $B \in \{0,1\}$ indicates inclusion in the second-phase sample.
 - $\pi_0 := \mathbb{P}(B=1 \mid Y, L)$ must be *known by design* or estimated.
 - Implicitly conditioning on the vaccine arm: $O = \{X \mid A = 1\}$.

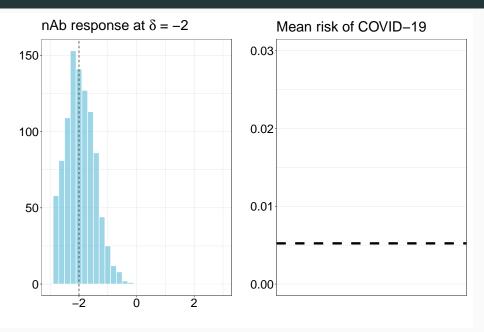
Causal Effects for Quantitative Exposures

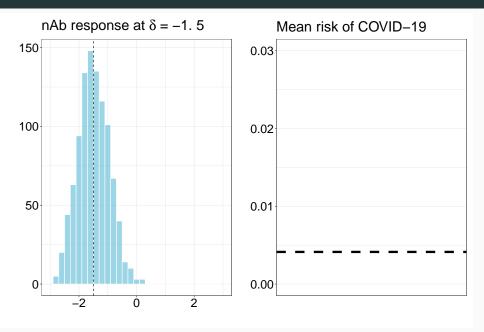
Static Interventions Aren't Enough

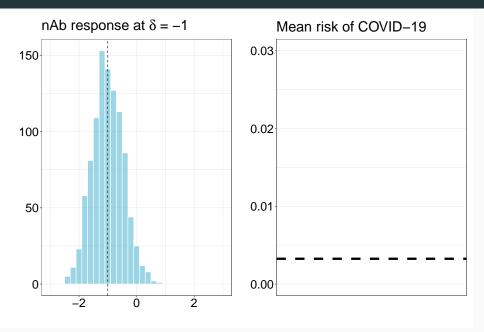
 Describe the manner in which X is hypothetically generated by a nonparametric structural equation model (Pearl 2009):

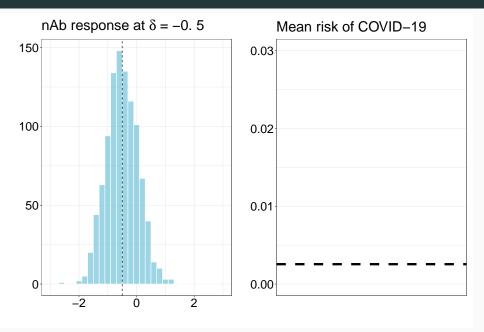
$$L = f_L(U_L); A \sim \text{Bern}(0.5); S = f_S(A, L, U_S); Y = f_Y(S, A, L, U_Y)$$

- Implies a model for the distribution of counterfactual random variables induced by interventions on the system.
- A static intervention replaces f_S with a specific value s in its conditional support S | L.
- This requires specifying a priori a particular value of exposure under which to evaluate the outcome — but what value?









Stochastic Interventions Define the Causal Effects of Shifts

- Stochastic interventions modify the value S would naturally assume by shifting the natural exposure distribution.
- Díaz and van der Laan (2012; 2018)'s shift interventions¹

$$d(s, l) = \begin{cases} s + \delta, & s + \delta < u(l) & \text{(if plausible)} \\ s, & s + \delta \ge u(l) & \text{(otherwise)} \end{cases}$$

• Our estimand is $\psi_{0,\delta}:=\mathbb{E}_{P_0^\delta}\{Y_{d(S,L)}\}$, which is identified by

$$\psi_{0,\delta} = \int_{\mathcal{L}} \int_{\mathcal{S}} \mathbb{E}_{P_0} \{ Y \mid S = d(s, l), L = l \}$$
$$g_{0,S}(s \mid L = l) q_{0,L}(l) d\mu(s) d\nu(l)$$

¹Haneuse and Rotnitzky (2013) introduced modified treatment policies.

Interpreting the Causal Effects of Shift Interventions

- Consider a data structure: $(Y_s, s \in S)$.
- Let $Y_s = \beta_0 + \beta_1 s + \epsilon_s$, with error $\epsilon_s \sim N(0, \sigma_s^2) \ \forall s \in S$.
- For the counterfactual outcomes $(Y_{s'+\delta}, Y_{s'})$, their difference $Y_{s'+\delta} Y_{s'}$ may be expressed (for some $s' \in S$)

$$\mathbb{E}Y_{s'+\delta} - \mathbb{E}Y_{s'} = [\beta_0 + \beta_1(s'+\delta) + \mathbb{E}\epsilon_{s'+\delta}] - [\beta_0 + \beta_1s' + \mathbb{E}\epsilon_{s'}]$$
$$= \beta_1\delta$$

• A unit shift for $s' \in S$ (i.e., $\delta = 1$) causes a counterfactual difference in Y of magnitude β_1 .

Stochastic-Interventional Vaccine Efficacy

Causal parameter based on vaccine efficacy (VE) estimands:

$$\begin{aligned} \mathsf{SVE}(\delta) &= 1 - \frac{\mathbb{E}[\mathbb{P}(Y=1 \mid S=d(s,\mathit{I}),A=1,L=\mathit{I})]}{\mathbb{P}(Y(0)=1)} \\ &= 1 - \frac{\psi_{0,\delta}}{\mathbb{P}(Y(0)=1)} \end{aligned}$$

- $\mathbb{P}(Y(0) = 1)$: counterfactual infection risk in the placebo arm under randomization, $\mathbb{P}(Y(0) = 1) \equiv \mathbb{P}(Y = 1 \mid A = 0)$.
- Summarizes VE via stochastic interventions across δ , per the CoVPN immune correlates SAP² (Gilbert et al. 2021a;b).

²SAP published at https://doi.org/10.6084/m9.figshare.13198595.

Efficient Estimation in Two-Phase Designs

Estimation of the Counterfactual Mean $\psi_{0,\delta}$

An estimator $\psi_{n,\delta}$ of $\psi_{0,\delta} \coloneqq \Psi(P_0)$ is efficient if and only if

$$\psi_{n,\delta} - \psi_{0,\delta} = n^{-1} \sum_{i=1}^{n} D^{\star}(P_0)(O_i) + o_P(n^{-1/2})$$
,

where $D^*(P)$ is the efficient influence function (EIF) of $\psi_{0,\delta}$ with respect to the nonparametric model \mathcal{M} at a distribution P.

The EIF of $\psi_{0,\delta}$ is indexed by two key *nuisance parameters*

$$\overline{Q}_{Y}(S,L) := \mathbb{E}_{P}(Y \mid S,L)$$
 outcome mechanism $g_{S}(S \mid L) := p(S \mid L)$ generalized propensity score

Flexible, Efficient, Doubly Robust Estimation

• The efficient influence function of $\psi_{0,\delta}$ with respect to $\mathcal M$ is

$$D_F^{\star}(P_0)(o) = \frac{g_{0,S}(d^{-1}(s,l) \mid l)}{g_{0,S}(s \mid l)} (y - \overline{Q}_{0,Y}(s,l)) + \overline{Q}_{0,Y}(d(s,l),l) - \psi_{0,\delta}.$$

The one-step bias-corrected estimator:

$$\psi_n^+ = \frac{1}{n} \sum_{i=1}^n \overline{Q}_{n,Y}(d(S_i, L_i), L_i) + D_n^*(O_i).$$

■ The TML estimator updates initial estimates of \overline{Q}_n by tilting:

$$\psi_n^{\star} = \frac{1}{n} \sum_{i=1}^n \overline{Q}_{n,Y}^{\star}(d(S_i, L_i), L_i).$$

Both doubly robust: flexible modeling for nuisance estimation.

Augmented Estimators for Two-Phase Sampling Designs

 Rose and van der Laan (2011) suggested inverse probability of censoring weighted (IPCW) loss functions:

$$\mathcal{L}(P_0^X)(O) = \frac{B}{\pi_0(Y, L)} \mathcal{L}(P_0^X)(X)$$

- When the sampling mechanism $\pi_0(Y, L)$ is known by design, this procedure yields a reasonably reliable estimator.
- When data-adaptive regression must be used that is, when $\pi_0(Y, L)$ is not known by design³— this is insufficient.

³Sampling of non-cases in HVTN 505 used matching (Janes et al. 2017).

Efficiency and Multiple Robustness (Hejazi et al. 2020)

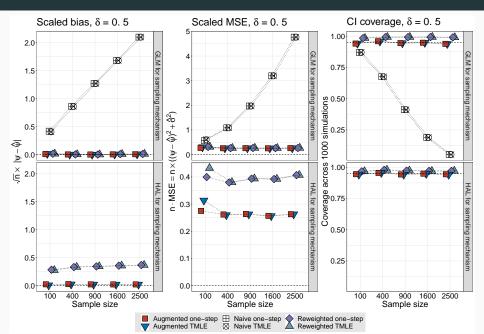
• Then, the IPCW augmentation must be applied to the EIF⁴:

$$D^{*}(P_{0}^{X})(o) = \frac{b}{\pi_{0}(y, l)} D_{F}^{*}(P_{0}^{X})(x) - \left(1 - \frac{b}{\pi_{0}(y, l)}\right)$$
$$\mathbb{E}(D_{F}^{*}(P_{0}^{X})(x) \mid B = 1, Y = y, L = l).$$

- Expresses observed data EIF $D^*(P_0^X)(o)$ via complete data EIF $D_F^*(P_0^X)(x)$; inclusion of second term improves efficiency.
- An emergent multiple robustness property combinations of $\{g_0(S \mid L), \overline{Q}_0(S, L)\} \times \{\pi_0(Y, L), \mathbb{E}(D_F^*(P_0^X)(x) \mid B = 1, Y, L)\}.$
- Our txshift R package implements our estimators of $\psi_{0,\delta}$.

⁴A very general version appears to have been presented in Robins et al. (1994).

Comparing Reweighted and Augmented Estimators



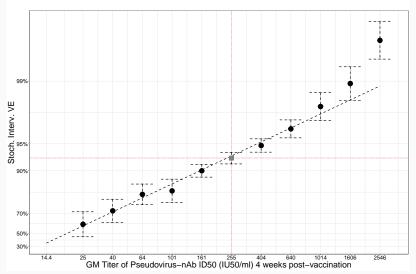
SVE Prediction of HIV-1 Risk thru CD8+ Immune Response

TML estimates of mean counterfactual HIV-1 infection risk under shifted CD8+ polyfunctionality with pointwise confidence intervals and summarization via working marginal structural model (\$\hat{\beta}_{TMI,F} = -0.013) 0.10 0.08 ----Risk of HIV-1 infection 0.00 90.0 0.02 0.00 -2 Posited change in standardized CD8+ polyfunctionality (sd units)

HIV-1 risk change across CD8+ response (txshift R package).

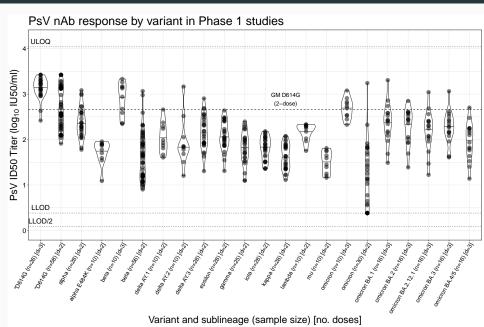
SVE Prediction of mRNA-1273 VE thru PsV nAb Correlate

Stoch. Interv. VE vs. COVID-19 (4 weeks post-vaccination with 100 days follow-up)



Bridging VE Using Immune Correlates

Pooled Phase 1 Studies: PsV nAb Responses Across Variants



SVE Bridging of mRNA-1273 VE thru PsV nAb Correlate

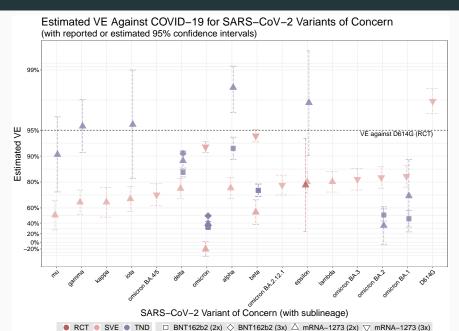
Stoch. Interv. VE vs. COVID-19 (4 weeks post-vaccination with 100 days follow-up) working MSM summary: ($\hat{\beta}_{TMLE} = 0.166$, p-value = 0) 99% Stoch. Interv. VE HOD 70% 50% 30% 10% 2.42 101 GM Titer of Pseudovirus-nAb ID50 (IU50/mI) 4 weeks post-vaccination iota omicron BA.4/5 [d=3] epsilon omicron BA.2 [d=3] [mRNA-1273 dosage] omicron BA.2.12.1 [d=3] omicron BA.3 [d=3] D614G alpha

SVE Predictions vs. Test-Negative Designs (TND) Estimates

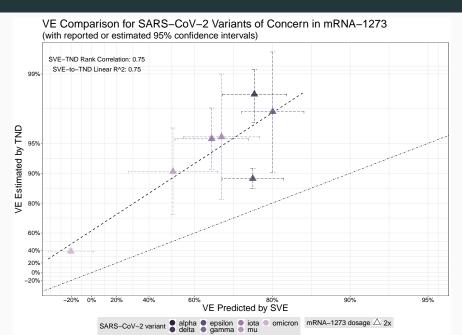
- Compared δ -calibrated SVE predictions to TND VE estimates.
- Inclusion/exclusion criteria for TND-based VE estimates⁵:
 - VE estimated by direct measurement of SARS-CoV-2 variants.
 - Reported VE estimates for mRNA vaccines (BNT162b2 or mRNA-1273), studying VE 2–6 months post-2nd or 3rd dose.
 - Flexible in choice of dosing interval (for 2nd or 3rd dose), with some studies extending to 12 weeks between doses.
- Aimed to study concordance of SVE predictions and TND estimates of VE following most recent vaccine dose.
- TND-based estimates established as biased (overestimating).

⁵Comparison of TND studies performed in collaboration with Dr. Lindsay Carpp.

Comparison of SVE Predictions and TND Estimates of VE



Concordance of SVE Predictions and TND Estimates of VE



Summary of SVE for Prediction and Immunobridging

- SVE prediction shows sharp changes in VE with shifts to the GM titer of the PsV nAb correlate in vaccinees.
- Bridging VE across variants indicates VE drops but stabilizes at 50%, if the model based on ancestral D614G strain holds.
 - Post-2nd dose: For most variants (excepting omicron), the VE estimate ranges from 50% (mu) to 80% (epsilon).
 - Post-3rd dose: For omicron lineages, VE estimate lies within 80%–92% across five subvariants (lowest VE vs. BA.2.12.1).
- SVE predictions and TND estimates of VE well-correlated.
 - TND studies are prone to bias, tending to overestimate VE.
 - SVE predictions may be underestimates, since the PsV nAb correlate is an *imperfect* causal *mediator* of the total VE.

Zooming Out

Going "Off-Road": Real-World Complexities

- We considered the case of O = (L, A, BS, Y, B), but what about O = (V, L, A, BS, Y, B) or O = (L, A, Z, BS, Y, B)?
 - Z: unmeasured baseline confounder (e.g., prior infection)
 - $A \in \{0,1\}$: randomized treatment assignment
 - Z: post-treatment confounder (e.g., unblinded risky behavior)
 - S: candidate immune correlates (causal mediators)
 - *Y*: symptomatic SARS-CoV-2 (or HIV-1) infection
 - B := f(Y, L): selection into two-phase sample
- And what about survival endpoints, $O = (L, A, BS, \Delta, \widetilde{T}, B)$?
 - $T = \min(T_F, T_C)$: possibly right-censored time to failure
 - $\Delta = \mathbb{I}(T_F < T_C)$: indicator of failure endpoint occurrence
 - Could making B a function of T improve sampling efficiency?

The Big Picture

- Stochastic interventions provide a framework for formulating novel policies based on natural treatment conditions.
- These modified treatment policies address causal questions about realistic interventions on quantitative treatments.
- Large-scale vaccine trials rely upon two-phase designs but need to (very carefully!) adjust for the resultant sampling bias.
- Efficient estimators with double/multiple robustness can safely answer such questions while incorporating machine learning.
- Open source software for such statistical analyses is critical for the methods to have any impact on real-world studies.

Thank you

Thanks for listening. Any questions?

♣ https://nimahejazi.org

O https://github.com/nhejazi

Appendix

Immune Correlates of Protection (Plotkin and Gilbert 2012)

- Correlate of Protection (CoP): immune marker statistically predictive of vaccine efficacy, not necessarily mechanistic.
- Mechanistic CoP (mCoP): immune marker that is causally and mechanistically responsible for protection.
- Nonmechanistic CoP (nCoP): immune marker that is predictive but not a causal agent of protection.
- A CoP is a candidate surrogate endpoint (Prentice 1989) primary endpoint in future trials if reliably predictive.

From the Causal to the Statistical Target Parameter

Assumption 1: Stable Unit Treatment Value (SUTVA)

- $Y_i^{d(s_i,l_i)}$ does not depend on $d(s_j,l_j)$ for $i=1,\ldots,n$ and $j \neq i$, or lack of interference (Cox 1958)
- $Y^{d(s,l)} = Y$ in the event S = d(s,l), for i = 1, ..., n

Assumption 2: No Unmeasured Confounding

$$S \perp Y^{d(s,l)} \mid L = l$$
, for $i = 1, \ldots, n$

Assumption 3: *Positivity*

 $s \in \mathcal{S} \implies d(s, l) \in \mathcal{S}$ for all $l \in \mathcal{L}$, where \mathcal{S} denotes the support of S conditional on L = l for all i = 1, ..., n

Literature: Díaz and van der Laan (2012; 2018)

- Proposal: Evaluate outcome under an altered intervention distribution e.g., $P_{\delta}(g_{0,S})(S=s\mid L)=g_{0,S}(s-\delta(L)\mid L)$.
- Identification conditions for a statistical parameter of the counterfactual outcome $\psi_{0,\delta}$ under such an intervention.
- Show that the causal quantity of interest $\mathbb{E}_{P_0^{\delta}}\{Y_{d(S,L)}\}$ is identified by a functional of the distribution of O, i.e.,

$$\psi_{0,\delta} = \int_{\mathcal{L}} \int_{\mathcal{S}} \mathbb{E}_{P_0} \{ Y \mid S = d(s, l), L = l \}$$
$$g_{0,S}(s \mid L = l) \cdot q_{0,L}(l) d\mu(s) d\nu(l)$$

Literature: Haneuse and Rotnitzky (2013)

- Proposal: Characterization of stochastic interventions as modified treatment policies (MTPs).
- Assumption of piecewise smooth invertibility allows for the post-intervention distribution of any MTP to be recovered:

$$g_{0,S}(s \mid l; \delta) = \sum_{j=1}^{J(l)} \mathbb{I}_{\delta,j}\{h_j(s, l), l\}g_0\{h_j(s, l) \mid l\}h_j'(s, l)$$

 MTPs account for the natural value of exposure S yet may be interpreted as imposing an altered intervention mechanism.

A Linear Modeling Perspective

- Briefly consider a simple data structure: X = (Y, S); we seek to model the outcome Y as a function of S.
- Linear model: consider $Y_i = \beta_0 + \beta_1 S_i + \epsilon_i$, with error $\epsilon_i \sim N(0,1)$.
- Letting δ be a change in S, $Y_{S+\delta}-Y_S$ may be expressed

$$\mathbb{E}Y_{S+\delta} - \mathbb{E}Y_S = [\beta_0 + \beta_1(\mathbb{E}S + \delta)] - [\beta_0 + \beta_1(\mathbb{E}S)]$$
$$= \beta_0 - \beta_0 + \beta_1\mathbb{E}S - \beta_1\mathbb{E}S + \beta_1\delta$$
$$= \beta_1\delta$$

• So, a *unit shift* in S (i.e., $\delta=1$) induces a change in the difference in outcomes of magnitude β_1 .

Slope in a Semiparametric Model

• Consider the stochastic intervention $g_{\delta}(\cdot \mid L)$:

$$\mathbb{E}Y_{g_{\delta}} = \int_{L} \int_{s} \mathbb{E}(Y \mid S = s, L)g(s - \delta \mid L)dsdP_{0}(L)$$
$$= \int_{L} \int_{z} \mathbb{E}(Y \mid S = z + \delta, L)g(z \mid L)dzdP_{0}(L),$$

defining the change of variable $z = s - \delta$.

• For a semiparametric model, $\mathbb{E}(Y \mid S = z, L) = \beta z + \theta(L)$:

$$\mathbb{E}Y_{g_{\delta}} - \mathbb{E}Y = \int_{L} \int_{z} \left[\mathbb{E}(Y \mid S = z + \delta, L) - \mathbb{E}(Y \mid S = z, L) \right]$$
$$g(z \mid L) dz dP_{0}(L)$$
$$= \left[\beta(z + \delta) + \theta(L) \right] - \left[\beta z + \theta(L) \right]$$
$$= \beta \delta$$

Flexible Conditional Density Estimation of $g_{0,S}$

Díaz and van der Laan (2011)'s conditional density estimator:

$$g_{n,\alpha}(s \mid L) = \frac{\mathbb{P}(s \in [\alpha_{t-1}, \alpha_t) \mid L)}{\alpha_t - \alpha_{t-1}}.$$

- Re-expressed as hazard regressions in repeated measures data.
- Tuning parameter $t \approx \text{bandwidth in kernel density estimation}$.
- When càdlàg (RCLL) with finite sectional variation, we have

$$\operatorname{logit}\{\mathbb{P}(s \in [\alpha_{t-1}, \alpha_t) \mid L)\} = \beta_0 + \sum_{w \subset \{1, \dots, d\}} \sum_{i=1}^n \beta_{w,i} \phi_{w,i},$$

for appropriate basis functions $\{\phi_{w,i}\}_{i=1}^n$ (Gill et al. 1995).

Flexible Conditional Density Estimation of $g_{0,S}$

- Utilizing a particular basis construction for ϕ_w , van der Laan (2017)'s HAL estimator achieves $n^{-1/4}$ convergence rate⁶.
- Loss-based cross-validation allows selection of a suitable HAL estimator, which has only the ℓ_1 regularization term λ :

$$\beta_{n,\lambda} = \mathop{\arg\min}_{\beta: |\beta_0| + \sum_{w \subset \{1, \dots, d\}} \sum_{i=1}^n |\beta_{w,i}| < \lambda} P_n \mathcal{L}(g_{\beta,\lambda,S}),$$

where $\mathcal{L}(\cdot)$ is an appropriate loss function, giving $\{\lambda_n, \beta_n\}$.

- We denote by $g_{n,\lambda,S} \coloneqq g_{\beta_{n,\lambda},S}$, the HAL estimate of $g_{0,S}$.
- Our haldensify R package implements our estimator of $g_{0,S}$.

 $^{^6}$ Similar rates can be achieved via *local* (vs. global) smoothness assumptions on $g_{n,S}$ (see, e.g., Robins et al. 2008, Mukherjee et al. 2017, Liu et al. 2021).

A Useful Class of Functions

Consider space of cadlag functions with finite variation norm.

Def. cadlag = *left-hand continuous* with *right-hand limits*

Variation norm Let $\theta_s(u) = \theta(u_s, 0_{s^c})$ be the section of θ that sets the coordinates in s equal to zero.

The *variation norm* of θ can be written:

$$|\theta|_{\nu} = \sum_{s \subset \{1,\ldots,d\}} \int |d\theta_s(u_s)|,$$

where $x_s = (x(j) : j \in s)$ and the sum is over all subsets.

Variation Norm

We can represent the function θ as

$$\theta(x) = \theta(0) + \sum_{s \subset \{1,\ldots,d\}} \int \mathbb{I}(x_s \geq u_s) d\theta_s(u_s),$$

For discrete measures $d\theta_s$ with support points $\{u_{s,j}:j\}$ we get a linear combination of indicator basis functions:

$$\theta(x) = \theta(0) + \sum_{s \subset \{1,\dots,d\}} \sum_{j} \beta_{s,j} \theta_{u_{s,j}}(x),$$

where
$$\beta_{s,j} = d\theta_s(u_{s,j})$$
, $\theta_{u_{s,j}}(x) = \mathbb{I}(x_s \geq u_{s,j})$, and

$$|\theta|_{\nu} = \theta(0) + \sum_{s \subset \{1, \dots, d\}} \sum_{i} |\beta_{s,j}|.$$

Convergence Rate of HAL

We have, for $\alpha(d) = 1/(d+1)$,

$$|\theta_{n,M} - \theta_{0,M}|_{P_0} = o_P(n^{-(1/4 + \alpha(d)/8)}).$$

Thus, if we select $M > |\theta_0|_v$, then

$$|\theta_{n,M} - \theta_0|_{P_0} = o_P(n^{-(1/4 + \alpha(d)/8)})$$
.

Due to oracle inequality for the cross-validation selector M_n ,

$$|\theta_{n,M_n} - \theta_0|_{P_0} = o_P(n^{-(1/4 + \alpha(d)/8)})$$
.

Improved convergence rate (Bibaut and van der Laan 2019):

$$|\theta_{n,M_n} - \theta_0|_{P_0} = o_P(n^{-1/3}\log(n)^{d/2})$$
.

Algorithm for TML Estimation

- 1. Construct initial estimators g_n of $g_0(S, L)$ and Q_n of $\overline{Q}_0(S, L)$, perhaps using data-adaptive regression techniques.
- 2. For each observation i, compute an estimate $H_n(s_i, l_i)$ of the auxiliary covariate $H(s_i, l_i)$.
- 3. Estimate the parameter ϵ in the logistic regression model

$$logit \overline{Q}_{\epsilon,n}(s,l) = logit \overline{Q}_n(s,l) + \epsilon H_n(s,l),$$

or an alternative regression model incorporating weights.

4. Compute TML estimator Ψ_n of the target parameter, defining update \overline{Q}_n^{\star} of the initial estimate $\overline{Q}_{n,\epsilon_n}$:

$$\Psi_n = \Psi(P_n^*) = \frac{1}{n} \sum_{i=1}^n \overline{Q}_n^*(d(S_i, L_i), L_i).$$

Algorithm for IPCW-TML Estimation

- 1. Using all observed units (X), estimate sampling mechanism $\pi(Y, L)$, perhaps using data-adaptive regression methods.
- 2. Using only observed units in the second-stage sample C=1, construct initial estimators $g_n(S,L)$ and $\overline{Q}_n(S,L)$, weighting by the sampling mechanism estimate $\pi_n(Y,L)$.
- 3. With the approach described for the full data case, compute $H_n(s_i, l_i)$, and fluctuate submodel via logistic regression.
- 4. Compute IPCW-TML estimator Ψ_n of the target parameter, by solving the IPCW-augmented EIF estimating equation.
- 5. Iteratively update estimated sampling weights $\pi_n(Y, L)$ and IPCW-augmented EIF, updating TMLE in each iteration.

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