

# Nonparametric inverse probability weighted estimators based on the highly adaptive lasso


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## Motivating example

The *observed data* unit is  $O := (W, A, Y) \sim P_0 \in \mathcal{M}$ :

- $W \in \mathbb{R}^d$  is a vector of covariates;
- $A \in \{0, 1\}$  is a binary treatment; and
- $Y \in \mathbb{R}$  is an outcome of interest.

Let  $\mathcal{M}$  be a large *semiparametric model* and for each  $P \in \mathcal{M}$ , define the *average treatment effect* (ATE) as

$$\Psi(P) := \mathbb{E}_P\{\mathbb{E}_P(Y | A = 1, W) - \mathbb{E}_P(Y | A = 0, W)\} .$$

## Estimation of the ATE

An estimator  $\psi_n$  of  $\psi_0 := \Psi(P_0)$  is *efficient* if and only if

$$\psi_n - \psi_0 = n^{-1} \sum_{i=1}^n D^*(P_0)(O_i) + o_P(n^{-1/2}),$$

where  $D^*(P)$  is the *efficient influence function* (EIF) of  $\Psi$  with respect to the model  $\mathcal{M}$  at  $P$ .

The EIF of  $\Psi$  is indexed by two key *nuisance parameters*

$$\begin{aligned} \bar{Q}_P(A, W) &:= \mathbb{E}_P(Y \mid A, W) && \text{outcome mechanism} \\ g_P(W) &:= \mathbb{E}_P(A \mid W) && \text{propensity score} \end{aligned}$$

## Estimation of a counterfactual mean

We'll rely on *empirical process notation* throughout:

- $P_0 f = \mathbb{E}_{P_0} \{f(O)\} = \int f(o) dP(o)$
- $P_n f = \mathbb{E}_{P_n} \{f(O)\} = n^{-1} \sum_{i=1}^n f(O_i)$

Consider estimating the *counterfactual mean in the treatment arm*:

$$\Psi(P) = \mathbb{E}_P \{ \mathbb{E}_P(Y | A = 1, W) \},$$

using the inverse probability weighted (IPW) estimator

$$\psi_n = n^{-1} \sum_{i=1}^n \frac{A_i Y_i}{g_n(1 | W_i)}.$$

- IPW estimators are the oldest class of causal effect estimators, and they are still very commonly used in practice today.
- IPW is easy to implement and appropriate across a variety of settings, but IPW estimators have several disadvantages:
  1. require a correctly specified estimate of the propensity score;
  2. can be inefficient, never attaining the efficiency bound; and
  3. suffer from an (asymptotic) curse of dimensionality.

## IPW estimators

An IPW estimator  $\Psi(P_n, g_n)$  is a solution to the score equation  $P_n U_{g_n}(\Psi) = 0$ , where  $U_g(O; \Psi) = \frac{AY}{g(1|W)} - \Psi(P)$ . That is,

$$\Psi(P_n, g_n) = n^{-1} \sum_{i=1}^n \frac{A_i Y_i}{g_n(1 | W_i)}.$$

- Consistency and convergence rate of IPW relies on those same properties of the propensity score estimator  $g_n$ .
- Generally, finite-dimensional (i.e., parametric) models are not flexible enough to consistently estimate  $g_0$ .

## Data-adaptive estimators

Data-adaptive regression can improve consistency of  $g_n$  for  $g_0$  but establishing asymptotic linearity is challenging:

$$\begin{aligned}\Psi(P_n, g_n) - \Psi(P_0, g_0) &= P_n U_{g_n}(\Psi) - P_0 U_{g_0}(\Psi) \\ &= (P_n - P_0) U_{g_0}(\Psi) \\ &\quad + P_0 \{U_{g_n}(\Psi) - U_{g_0}(\Psi)\} \\ &\quad + (P_n - P_0) \{U_{g_n}(\Psi) - U_{g_0}(\Psi)\}.\end{aligned}$$

- Using only standard empirical process theory and the assumption of consistency, the blue term is  $o_p(n^{-1/2})$ .
- Asymptotic linearity of our IPW estimator relies on the asymptotic linearity of the red term.

## Curse of dimensionality

Goal: Construct nuisance parameter *estimators* that are *consistent* and *converge faster* than  $n^{-1/4}$  under *minimal assumptions*.

*Challenging* for moderately large  $d$  due to the *curse of dimensionality*.

For example, consider *kernel regression* with bandwidth  $h$  and kernels orthogonal to polynomials in  $W$  of degree  $k$ .

- Assume parameter is  $k$  times *differentiable*.
- Optimal bandwidth  $O(n^{-1/(2k+d)})$
- Optimal convergence rate  $O(n^{-k/(2k+d)})$



## Curse of dimensionality

Broadly, *two approaches* for handling the *curse of dimensionality*.

[1] Enforce (strong) *smoothness assumptions* on model space.

- No guarantee of *consistency*

[2] Ensemble machine learning, e.g., *Super Learning*

- No guarantee of *quarter rates*

## An important class of functions

Consider space of *cadlag* functions with *finite variation norm*.

**Def.** *cadlag* = *left-hand continuous* with *right-hand limits*

**Variation norm** Let  $\theta_s(u) = \theta(u_s, 0_{s^c})$  be the *section* of  $\theta$  that sets the coordinates in  $s$  equal to zero.

The *variation norm* of  $\theta$  can be written:

$$|\theta|_v = \sum_{s \subset \{1, \dots, d\}} \int |d\theta_s(u_s)|,$$

where  $x_s = (x(j) : j \in s)$  and the sum is over all subsets.

## Variation norm

We can represent the function  $\theta$  as

$$\theta(x) = \theta(0) + \sum_{s \subset \{1, \dots, d\}} \int I(x_s \geq u_s) d\theta_s(u_s),$$

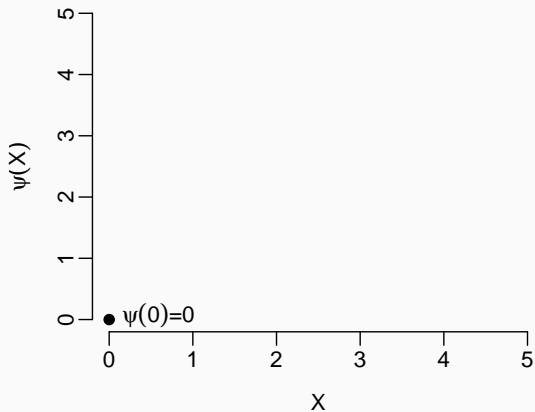
For discrete measures  $d\theta_s$  with *support points*  $\{u_{s,j} : j\}$  we get a *linear combination of indicator basis functions*:

$$\theta(x) = \theta(0) + \sum_{s \subset \{1, \dots, d\}} \sum_j \beta_{s,j} \theta_{u_{s,j}}(x),$$

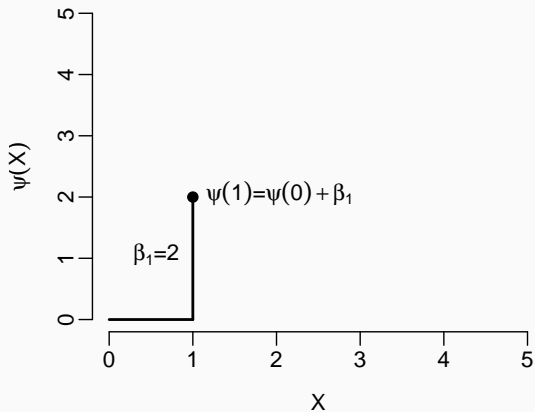
where  $\beta_{s,j} = d\theta_s(u_{s,j})$ ,  $\theta_{u_{s,j}}(x) = I(x_s \geq u_{s,j})$ , and

$$|\theta|_v = \theta(0) + \sum_{s \subset \{1, \dots, d\}} \sum_j |\beta_{s,j}|.$$

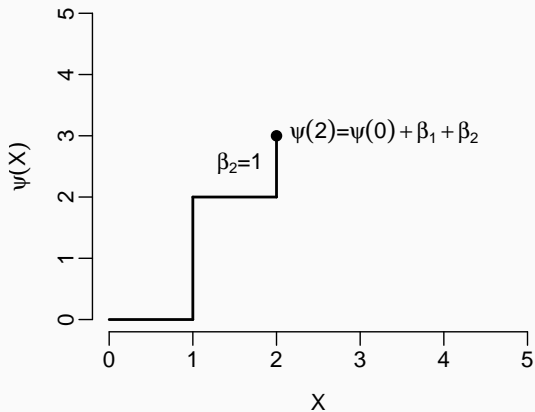
# Illustration



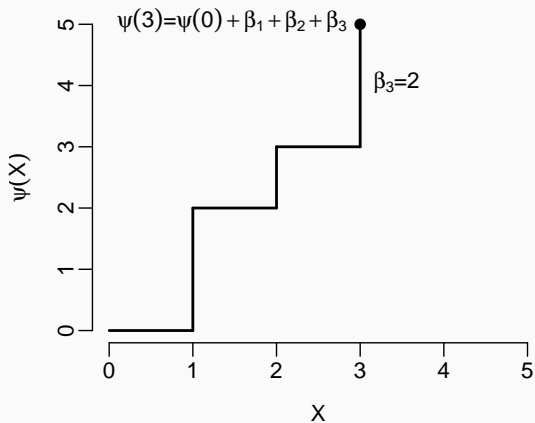
# Illustration



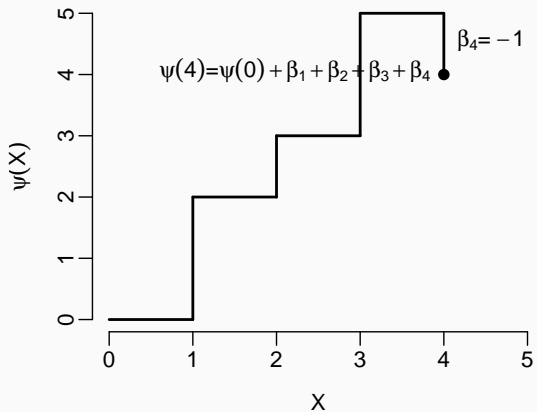
# Illustration



# Illustration

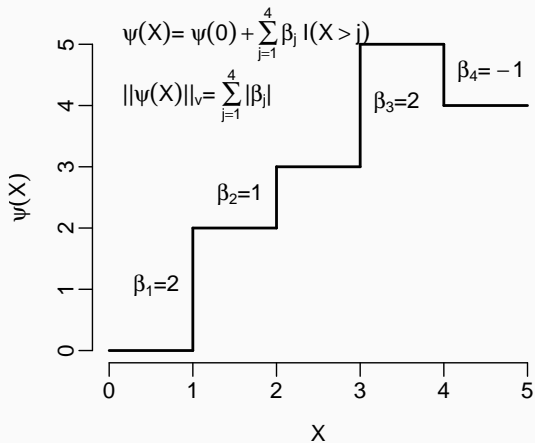


# Illustration





# Illustration



## Convergence rate of HAL

We have

$$|\theta_{n,M} - \theta_{0,M}|_{P_0} = o_P(n^{-(1/4+\alpha(d)/8)}),$$

where  $\alpha(d) = 1/(d+1)$ .

Thus, if we select  $M > |\theta_0|_v$ , then

$$|\theta_{n,M} - \theta_0|_{P_0} = o_P(n^{-(1/4+\alpha(d)/8)}) .$$

Due to oracle inequality for the cross-validation selector  $M_n$ ,

$$|\theta_{n,M_n} - \theta_0|_{P_0} = o_P(n^{-(1/4+\alpha(d)/8)}) .$$

Improved rate (Bibaut and van der Laan 2019):

$$|\theta_{n,M_n} - \theta_0|_{P_0} = o_P(n^{-1/3} \log(n)^{d/2}) .$$

## HAL estimate of $g_0$

Under the assumption that our nuisance functional parameter  $g$  is a cadlag function with finite sectional variation norm,  $\text{logit } g$  may be approximated as (Gill et al. 1995):

$$\text{logit } g_\beta = \beta_0 + \sum_{s \subset \{1, \dots, d\}} \sum_{i=1}^n \beta_{s,i} \phi_{s,i},$$

where  $\phi_{s,i}$  is an indicator basis function.

The loss-based HAL estimator  $\beta_n$  may then be defined as

$$\beta_{n,\lambda} = \arg \min_{\beta: |\beta_0| + \sum_{s \subset \{1, \dots, d\}} \sum_{i=1}^n |\beta_{s,i}| < \lambda} P_n L(\text{logit } g_\beta),$$

where  $L(\cdot)$  is an appropriate loss function.

Denote by  $g_{n,\lambda} \equiv g_{\beta_{n,\lambda}}$  the HAL estimate of  $g_0$ .

## The proposal

The efficient influence function expansion is of the form

$$\Psi(P_n, g_n) - \Psi(P_0, g_0) = P_n\{U_{g_0}(\Psi) - D_{\text{CAR}}(P_0)\} + o_p(n^{-1/2}).$$

In particular, the EIF may be expressed

$$\begin{aligned} D^*(P_0) &:= U_{g_0}(\Psi) - D_{\text{CAR}}(P_0) \\ &= \left[ \frac{AY}{g(1|W)} - \Psi(P, g) \right] - \left[ \frac{\bar{Q}(1, w)}{g(1|W)} \{A - g(1|W)\} \right]. \end{aligned}$$

The term  $D_{\text{CAR}}(g_n, Q_0)$  is key to both efficiency and asymptotic linearity. When the HAL estimator  $g_n$  is properly *undersmoothed*

$$P_n D_{\text{CAR}}(g_n, Q_0) = o_p(n^{-1/2}).$$

## The score function

The score function of the HAL fit is

$$S_h(g) = \Phi(A - g_{n,\lambda_n})$$

where  $\Phi$  is a vector consisting of indicator basis functions  $\phi_s$ . As we undersmooth, the dimension of  $\Phi$  increases, and thus, we start solving more and more equations.

Recall,  $D_{CAR} = f(W)(A - g_{n,\lambda_n})$  where  $f(W) = Q(1, W)/g(A | W)$ . The  $f$  function can be approximated with  $\sum_j \alpha_j \phi_j$ .

If we undersmooth enough then we would also solve  $P_n D_{CAR}(g_n, Q_n) = o_P(n^{-1/2})$ .

# Undersmoothing in practice

We propose two criteria.

1.  $D_{CAR}$  based:

$$\lambda_n = \arg \min_{\lambda} \left| P_n D_{CAR}(g_{n,\lambda}, Q_n) \right|,$$

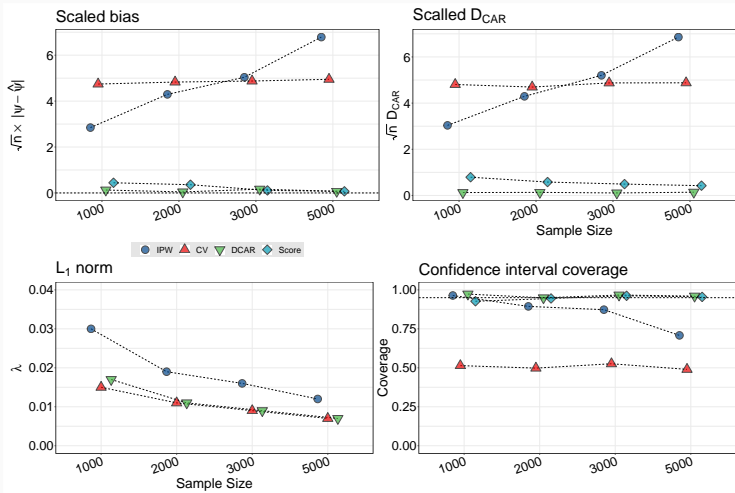
where  $Q_n$  is a HAL estimate of  $Q_0(1, W)$ .

2. Score based:

$$\lambda_n = \arg \min_{\lambda} \left[ \sum_{(s,j) \in \mathcal{J}_n} \frac{1}{\|\beta_{n,\lambda}\|_{L_1}} \left| P_n \tilde{S}_{s,j}(\phi, g_{n,\lambda}) \right| \right],$$

in which  $\tilde{S}_{s,j}(\phi, g_{n,\lambda}) = \phi_{s,j}(W) \{A - g_{n,\lambda}(1 | W)\} \{g_{n,\lambda}(1 | W)\}^{-1}$ .

# Simulation



**Figure 1:** Circle: parametric; Triangle: NP with cross-validated  $\lambda$  selector; “ $\nabla$ ”:  $D_{CAR}$ -based  $\lambda$  selector; “ $\diamond$ ”: score-based  $\lambda$  selector.

# The Big Picture

1. Unlike standard IPW estimators, our estimators **avoid the asymptotic curse of dimensionality**, and are asymptotically efficient;
2. in contrast to targeted IPW estimators, our estimators **do not suffer from irregularity issues**; and
3. in contrast with typical doubly robust estimators, our estimators rely on a single nuisance parameter and may be **formulated without the form of the EIF**.



# Thank you!

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 <https://arxiv.org/abs/2005.11303>

# Appendix

## The red term

Let  $Q_0(1) = \mathbb{E}(Y | A = 1, \mathbf{W})$ . Then,

$$\begin{aligned} & P_0 \{U_{G_n}(\Psi) - U_{G_0}(\Psi)\} \\ &= P_0 \left\{ G_0 Q_0(1) \left( \frac{G_0 - G_n}{G_n G_0} \right) \right\} \\ &= P_0 \left\{ Q_0(1) \left( \frac{G_0 - G_n}{G_0} \right) \right\} + P_0 \left\{ \frac{Q_0(1)}{G_n} (G_0 - G_n)^2 \right\} \\ &= P_0 \left\{ Q_0(1) \left( \frac{G_0 - G_n}{G_0} \right) \right\} + o_p(n^{-1/2}) \\ &= -(P_n - P_0) \{D_{\text{CAR}}(P_0)\} - P_n \{D_{\text{CAR}}(Q_0, G_0, G_n)\} + o_p(n^{-1/2}), \end{aligned}$$

where  $D_{\text{CAR}}(Q_0, G_0, G_n) = Q_0(1) \left( \frac{A - G_n}{G_0} \right)$  and

$$D_{\text{CAR}}(P_0) = Q_0(1) \left( \frac{A - G_0}{G_0} \right).$$

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