

Overview of RandNLA: Randomized Numerical Linear Algebra

Michael W. Mahoney

ICSI and Dept of Statistics, UC Berkeley

*(For more info, see:
<http://www.stat.berkeley.edu/~mmahoney/>
or Google on "Michael Mahoney")*

February 2015

Outline

- 1 Overview and Background
- 2 Basic RandNLA Principles
- 3 Applications of Basic RandNLA Principles
- 4 Conclusions

RandNLA: Randomized Numerical Linear Algebra

Matrices provide a natural structure with which to **model data**.

- $A \in \mathbb{R}^{m \times n}$ can encode information about **m objects**, each of which is described by n *features*; etc.
- A positive definite $A \in \mathbb{R}^{n \times n}$ can encode the correlations/similarities between all **pairs of n objects**; etc.

Motivated by data problems, recent years have witnessed **many exciting developments** in the theory and practice of matrix algorithms.

- Particularly remarkable is the ***use of randomization***.
- Typically, it is assumed to be a property of the input data due (e.g., to noise in the data generation mechanisms).
- Here, it is used as an algorithmic or computational resource.

RandNLA: Randomized Numerical Linear Algebra

RandNLA: an interdisciplinary research area that exploits randomization as a computational resource to develop improved algorithms for large-scale linear algebra problems.

- **Foundational perspective:** roots in theoretical computer science (TCS); deep connections with convex analysis, probability theory, and metric embedding theory, etc.; and strong connections with scientific computing, signal processing, and numerical linear algebra (NLA).
- **Implementational perspective:** well-engineered RandNLA algorithms beat highly-optimized software libraries for problems such as very over-determined least-squares and scale well to parallel/distributed environments.
- **Data analysis perspective:** strong connections with machine learning and statistics and many “non-methodological” applications of data analysis.

Moreover, there is a growing interest in providing an *algorithmic and statistical foundation for modern large-scale data analysis*.

An historical perspective

Linear algebra has had a **long history** in large-scale (by the standards of the day) **statistical data analysis**.

- Method of least-squares (LS): due to Gauss, Legendre, and others; and used in early 1800s for fitting linear equations to determine planetary orbits.
- Principal Component Analysis (PCA) and low-rank approximations: due to Pearson, Hotelling, and others, and used in early 1900s for exploratory data analysis and predictive analytics.

These and related methods are of interest since, *e.g.*, if there is noise or randomness *in the data* then the leading principle components tend to capture the signal and remove the noise.

An historical perspective

Advent of the **digital computer** in the 1950s:

- Proto computer science and early applications of linear algebra focused on scientific computing problems (where computation was an essential tool)
- Even for “well-posed” problems, many algorithms performed very poorly in the presence of the finite precision.
- Work by Turing, von Neumann, and others laid much of the foundations for scientific computing and NLA: this led to problem-specific complexity measures (e.g., the condition number) that characterize the behavior of an input for a specific class of algorithms (e.g., iterative algorithms).

But ... (for various technical and nontechnical reasons), there then occurred a **split in the nascent field of computer science**:

- Continuous linear algebra became the domain of applied mathematics.
- Computer science theory and practice became discrete and combinatorial.

An historical perspective

Linear algebra became the domain of **continuous applied mathematics**; and it focused on **scientific applications**.

- Nearly all work in scientific computing and NLA has been deterministic; this led to high-quality codes in the 1980s/1990s, *e.g.*, LAPACK.
- Most work focused on optimizing FLOPS—matrix-vector multiplies on dense matrices—in shared memory environments on matrices that arise in structured scientific computing applications.
- This code is now widely-used in NLA and scientific computing as well as in machine learning, statistics, data analysis, etc.

An historical perspective

Computer science became **discrete and combinatorial**; and it focused on **business and commerce applications**.

- Turing, Church, and other studied computation *per se*.
- Seemingly-different approaches (recursion theory, the λ -calculus, and Turing machines) defined the same class of functions
- Belief arose that the concept of computability is formally captured in a qualitative and robust way by these three equivalent processes, *independent of the input data*.
- Randomization (where the randomness is *inside the algorithm*, and the algorithm is applied to arbitrary or worst-case data) was introduced and exploited as a powerful computational resource.

An historical perspective: now and going forward ...

Recently, a **convergence of these two very different perspectives**.

- Motivated by scientific, Internet, social media, financial, etc. applications.
- Computation *per se* is necessary but very insufficient.
- Most people want to *obtain insight* and/or *make predictions* from the data they generate to make downstream claims about the world.

Central to these developments RandNLA, including:

- Randomness in the data versus randomness in the algorithm.
- Continuous (mathematics) versus discrete (computer science).
- Worst-case algorithms versus problem-specific complexity measures.
- Scientific versus business/commerce applications.

Good “hydrogen atom” to consider algorithmic and statistical foundations of modern large-scale data analysis.

Outline

- 1 Overview and Background
- 2 Basic RandNLA Principles**
- 3 Applications of Basic RandNLA Principles
- 4 Conclusions

Basic RandNLA Principles

Basic RandNLA method: given an input matrix:

- **Construct a “sketch”** (a smaller or sparser matrix that represents the essential information in the original matrix) by random sampling.
- **Use that sketch** as a surrogate to compute quantities of interest.

Basic design principles* underlying RandNLA:

- Randomly **sample** (in a careful data-dependent manner) a small number of **elements** to create a much sparser sketch of the original matrix.
- Randomly **sample** (in a careful data-dependent manner) a small number of **columns and/or rows** to create a much smaller sketch of the original matrix.
- **Preprocess an input matrix** with a random-projection-type matrix and then do uniform sampling of rows/columns/elements in order to create a sketch.

*The first two principles deal with identifying nonuniformity structure. The third principle deals with preconditioning the input (*i.e.*, uniformizing nonuniformity structure) s.t. uniform random sampling performs well.▶

Element-wise Sampling

- An $m \times n$ matrix A is an array of numbers, A_{ij} , $\forall i \in [m], \forall j \in [n]$.
- Randomly **sample** a small number of **entries**, each w.r.t. importance sampling probability distribution p_{ij} .
- **Return a sparse matrix \tilde{A}** that contains precisely the (rescaled) entries.
- Uniform sampling easily leads to poor results; but **non-uniform sampling** w.r.t. magnitudes or element-wise leverage scores gives nontrivial results.
- Thm [AM01/AM07/DZ11]: If sample s elements with $p_{ij} = \frac{A_{ij}^2}{\sum_{i,j} A_{ij}^2}$, then

$$\|A - \tilde{A}\|_2 \leq O\left(\sqrt{\frac{(m+n) \ln(m+n)}{s}}\right) \|A\|_F.$$

This gives “*additive-error*” bounds for low-rank matrix approximation.

- Proof method: $A - \tilde{A}$ is a random matrix; use random matrix theory, combinatorial moment methods, matrix measure concentration bounds.

Row/column Sampling

- An $m \times n$ matrix A is a **linear operator**, with column/row spaces.
- Randomly **sample** a small number of **rows**, each w.r.t. importance sampling probability distribution $\{p_i\}_{i=1}^m$.
- **Return $s \times n$ matrix \tilde{A}** , an approximation to A , containing s (rescaled) rows.
- Uniform sampling easily leads to poor results; but **non-uniform sampling** w.r.t. magnitudes or leverage scores gives nontrivial results.
- Thm [FVK97/DKM05/RV06]: If sample s rows with $p_i = \frac{\|A_{(i)}\|^2}{\sum_{i,j} A_{ij}^2}$, then

$$\|A^T A - \tilde{A}^T \tilde{A}\|_F \leq \frac{1}{\sqrt{s}} \|A\|_F^2.$$

This gives “*additive-error*” bounds for low-rank matrix approximation.

- Proof method: expectations and variances for $\|\cdot\|_F$; Khintchine inequality or matrix-Bernstein inequalities for $\|\cdot\|_2$ extension.

Row/column Sampling

- **Norm-squared sampling** does only comparable to element-wise sampling.
- **Leverage score sampling** does better: say $m \gg n$, then let

$$p_i = \frac{1}{n} (P_A)_{ii} = \frac{1}{n} \|U_{(i)}\|_2^2,$$

where U is any $m \times n$ orthogonal matrix spanning the column space of A .

- These *statistical leverage scores*
 - ▶ are useful in **regression diagnostics** to identify outliers
 - ▶ approximatable **without computing U** in “random projection time”
 - ▶ give “*relative-error*” bounds for least-squares & low-rank approximation
 - ▶ provide **data-aware subspace embedding**: fix $\epsilon \in (0, 1)$, $s \gtrsim \frac{n \log(n)}{\epsilon}$ then

$$\|U^T U - (SU)^T SU\|_2 = \|I - (SU)^T SU\| \leq \epsilon.$$

(For NLA, this is an acute perturbation; for TCS this is a subspace JL.)

Random Projections as Preconditioners[†]

- **Main challenge** for uniform sampling: relevant information could be *localized* on a small number of rows/columns/elements.
- Main challenge for non-uniform sampling: construct sampling probabilities.
- **One solution**: *spread out* this information, so uniform sampling does well.
- Bicriteria:
 - ▶ Preprocessed matrix should be similar to the original matrix.
 - ▶ Preprocessing should be computationally efficient to perform.
- Do this preconditioning with random projections:
 - ▶ Pre-/post-multiply by appropriately-scaled random matrix (i.i.d. Gaussians, i.i.d. Rademacher, Hadamard-based constructions, etc.)
 - ▶ Can get **data-oblivious subspace embedding**: fix $\epsilon \in (0, 1)$, then

$$\|U^T U - (\Pi U)^T \Pi U\|_2 = \|I - (\Pi U)^T \Pi U\| \leq \epsilon.$$

(For NLA, this is an acute perturbation; for TCS this is a subspace JL.)

[†]Preconditioners: a transformation that converts a problem instance into another instance that is more-easily solved by a given class of algorithms.

Outline

- 1 Overview and Background
- 2 Basic RandNLA Principles
- 3 Applications of Basic RandNLA Principles**
- 4 Conclusions

Least-squares approximation

Least-squares (LS) : given $m \times n$ matrix A and m -dimensional vector b , solve

$$x_{opt} = \arg \min_{x \in \mathbb{R}^n} \|Ax - b\|_2.$$

- If $m \gg n$, it is overdetermined/overconstrained.
- Compute solution in $O(mn^2)$ time (in RAM model) with one of several methods: computing the normal equations; QR decompositions; or SVD.
- **RandNLA provides faster algorithms** for this ubiquitous problem.
 - ▶ **TCS**: faster in terms of low-precision asymptotic worst-case theory.
 - ▶ **NLA**: faster in terms of high-precision wall-clock time.
 - ▶ **Implementations**: (in Spark) can compute low, medium, and high precision solutions on up to terabyte-sized data.
- *The basic RandNLA approach extends to many other matrix problems.*

Least-squares approximation: leverage and condition

- **Statistical leverage.** (*Think: eigenvectors. Important for low-precision.*)
 - ▶ The **statistical leverage scores** of A (assume $m \gg n$) are the diagonal elements of the projection matrix onto the column span of A .
 - ▶ They equal the ℓ_2 -norm-squared of any orthogonal basis spanning A .
 - ▶ They measure:
 - ★ how well-correlated the singular vectors are with the canonical basis
 - ★ which constraints have largest “influence” on the LS fit
 - ★ a notion of “coherence” or “outlierness”
 - ▶ Computing them exactly is as hard as solving the LS problem.
- **Condition number.** (*Think: eigenvalues. Important for high-precision.*)
 - ▶ The **ℓ_2 -norm condition number** of A is $\kappa(A) = \sigma_{\max}(A)/\sigma_{\min}^+(A)$.
 - ▶ $\kappa(A)$ bounds the number of iterations; for ill-conditioned problems (e.g., $\kappa(A) \approx 10^6 \gg 1$), the convergence speed is very slow.
 - ▶ Computing $\kappa(A)$ is generally as hard as solving the LS problem.

Least-squares approximation: Meta-algorithm (1 of 2)

- 1: Using the ℓ_2 statistical leverage scores of A , **construct** an importance sampling distribution $\{p_i\}_{i=1}^m$.
- 2: Randomly **sample** a small number of constraints according to $\{p_i\}_{i=1}^m$ to construct a subproblem.
- 3: **Solve** the ℓ_2 -regression problem on the subproblem.

A naïve version of this meta-algorithm gives a $1 + \epsilon$ relative-error approximation—on both the objective function and the certificate/vector achieving the optimum—in roughly $O(mn^2/\epsilon)$ time. (Ugh.)

Least-squares approximation: Meta-algorithm (2 of 2)

(Drineas, Mahoney, etc., 2006, 2008, etc., starting with SODA 2006; Mahoney FnTML, 2011. ¶)

But, **we can make this meta-algorithm “fast” in RAM:**‡

- This meta-algorithm runs in $O(mn \log n / \epsilon)$ time in RAM if:
 - ▶ we perform a Hadamard-based random random projection and sample uniformly sampling in the randomly rotated basis, or
 - ▶ we quickly computing approximations to the statistical leverage scores and using those as an importance sampling distribution.
- Can be improved to run in **almost $O(\text{nnz}(A))$** time.

And, **we can make this meta-algorithm “high precision” in RAM:**§

- This meta-algorithm runs in $O(mn \log n \log(1/\epsilon))$ time in RAM if:
 - ▶ we use the random projection/sampling basis to construct a preconditioner and couple with a traditional iterative algorithm.
- See Blendenpik/LSRN for NLA-style **wall-clock time** comparisons.
- Can also be improved to run in almost $O(\text{nnz}(A))$ time.

‡ (Sarlós 2006; Drineas, Mahoney, Muthu, Sarlós 2010; Drineas, Magdon-Ismail, Mahoney, Woodruff 2011.)

§ (Rokhlin & Tygert 2008; Avron, Maymounkov, & Toledo 2010; Meng, Saunders, & Mahoney 2011.)

¶ (Mahoney, “Randomized Algorithms for Matrices and Data,” FnTML, 2011.)

Extensions to Low-rank Matrix Approximation

What is your objective?

- *In NLA*: deterministic algorithms & greedy pivot rule decisions; choose exactly k columns; strong connections with QR/RRQR; focus on $\|\cdot\|_2$.
- *In TCS*: randomized algorithms, that might fail; select more than k columns, e.g., $\Theta(k \log(k))$ columns; focus on $\|\cdot\|_F$.
- *In ML/data applications*: low-rank approximations an intermediate step.

Best algorithms: exploit the following **structural condition underlying randomized low-rank algorithms**: If $V_k^T Z$ has full rank, then

$$\|A - P_{AZ}A\|_{\xi}^2 \leq \|A - A_k\|_{\xi}^2 + \left\| \Sigma_{k,\perp} (V_{k,\perp}^T Z) (V_k^T Z)^{\dagger} \right\|_{\xi}^2.$$

This structural condition

- was introduced to solve the “column subset selection problem,”
- can be used to get $o(k \log(k))$ columns in TCS theory,
- is easy to parameterize RandNLA algorithms to choose $k + p$ columns,
- is easy to couple with various NLA iterative algorithms, and
- often leads to less variance in downstream data applications.

Matrix Completion

Given arbitrary $m \times n$ matrix A , reconstruct A by sampling $O((m+n)\text{poly}(\frac{1}{\epsilon^\alpha}))$ entries (α small, e.g., 2, $\log(\frac{mn}{\epsilon})$ factors ok, but not all mn entries) s.t.

$$\|A - \tilde{A}\| \leq (1 + \epsilon)\|A - A_k\|_F. \quad (1)$$

- **One approach** from TCS: above element-wise sampling algorithm. In two “passes,” sample entries with based on their squared magnitude:

$$\|A - \tilde{A}\| \leq \|A - A_k\|_F + \epsilon\|A\|_F.$$

Entire matrix is observed; works for worst-case input matrices.

Additive error bound is too large to satisfy Eqn. (1).

- **Another approach**^{||} from signal processing and applied mathematics: under incoherence assumptions, give a uniform sample of $O((m+n)k \ln(m+n))$ entries of A to form \tilde{A} , then A is the solution to:

$$\min_{\tilde{A} \in \mathbb{R}^{m \times n}} \|\tilde{A}\|_1 \quad \text{s.t.} \quad \tilde{A}_{ij} = A_{ij}, \quad \forall \text{ sampled entries } A_{ij}.$$

Don't even observe all of A ; but strong assumptions on A are allowed.

If A is exactly low-rank and incoherent, then Eqn. (1) is satisfied.

^{||}Very different problem parameterizations: either assume worst-case input and must identify nonuniformity structure; or make “niceness” assumptions about input, where the worst nonuniformity structure is not present 

Solving Systems of Laplacian-based Linear Equations

Consider the problem of solving the **system of linear equations** $Ax = b$.

$$x_{opt} = \arg \min_{x \in \mathbb{R}^n} \|Ax - b\|_2. \quad (2)$$

- Solvable “exactly” in $O(n^3)$ time for worst-case dense input A
- Iterative techniques (e.g., CG) used if A is positive definite (PD); then, running time is $O(\mathbf{nnz}(A))$ time, times $\kappa(A)$ factor.
- Important **special case**: A is the Laplacian matrix of an graph $G = (V, E)$. (Arises in scientific computing, machine learning, etc.)
- Then, there exist randomized, relative-error algorithms that run in $O(\mathbf{nnz}(A)\text{polylog}(n))$ time.
- First step: randomized graph sparsification to create sparser Laplacian \tilde{L} .
 - ▶ sample edges of G according to leverage scores of weighted edge-incidence matrix
 - ▶ but must approximate them graph theoretically
- Second step: use \tilde{L} (recursively) as a preconditioner to solve Eqn. (2).

Statistics, Machine Learning, and Data Applications

Many examples:

- Kernel-based machine learning: fast low-rank approximations via projections and Nyström method.
- CX/CUR decompositions provide scalable and interpretable low-rank approximations in genetics, astronomy, etc.
- More scalable scientific computing for classes of pdes.
- Divide-and-conquer matrix completion algorithms use similar analysis.
- Statistical aspects of this “algorithmic leveraging” approach.

Main challenges:

- Most people who use low-rank approximations use them for something else.
- Many statistics and machine learning formulations of these problems render the problem trivial (for important algorithmic-statistical reasons).
- Sometimes the methods do “better” than they “should” (implicit regularization), but sometimes they don't.

Outline

- 1 Overview and Background
- 2 Basic RandNLA Principles
- 3 Applications of Basic RandNLA Principles
- 4 Conclusions**

Conclusions

- RandNLA has had **several big successes** already:
 - ▶ The **best works-case algorithms** (TCS-style) for very overdetermined least-squares problems.
 - ▶ **Implementations** (NLA-style) are competitive with and can beat the best high-quality NLA libraries.
 - ▶ **Implementations** (in Spark) can compute low, medium, and high precision solutions on up to terabyte-sized data.
 - ▶ Several big wins in statistics, machine learning, and **data applications**.
- Are these just “one off” successes, or just the tip of the iceberg?

- **This reading group:**
 - ▶ Go through several papers central to **RandNLA** and **RandNLA**
 - ▶ Learn a bit about RandNLA
 - ▶ **Identify particularly promising directions** to strengthen the NLA foundations of RandNLA