

Section 6. The generalized additive model

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Nonparametric regression

Model $Y = f(X) + \epsilon$

f : smooth ϵ : noise, mean 0, $\perp f(X)$

$$f(x) = E\{Y|X=x\}$$

This conditional expectation has two interpretations:

1) $\min_f E\{(Y - f(X))^2\}$
 $E\{\epsilon^2\}$

Proof. $E\{(Y - EY|X + EY|X - f(X))^2\}$
 $= E\{(Y - EY|X)^2\} + E\{(EY|X - f(X))^2\}$
 $+ 2 E\{E\{(Y - EY|X)(EY|X - f(X))\}\}$ $E - 0$

2) $\max \text{corr}\{Y, f(X)\}$

This result will be used to motivate $\text{acc}()$ later.

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Model and large sample properties.

Suppose Y_1, \dots, Y_n are independent r.v.'s with

$$E\{Y_i | x_i\} = \lambda(x_i)$$

$$\text{var}\{Y_i | x_i\} = \sigma(x_i)^2$$

Consider

$$\hat{\lambda}(x) = \frac{\sum Y_i K_n(x-x_i)}{\sum K_n(x-x_i)}$$

where $K_n(x) = \frac{1}{b_n} K(x/b_n)$ for some bandwidth b_n .

$$E \hat{\lambda}(x) = \frac{\sum \lambda(x_i) K_n(x-x_i)}{\sum K_n(x-x_i)}$$

and

$$\text{var} \hat{\lambda}(x) = \frac{\sum \sigma(x_i)^2 K_n(x-x_i)^2}{\left(\sum K_n(x-x_i)\right)^2}$$

Let us look for approximations of the terms appearing, using the lemma and supposing $b_n \rightarrow 0$ as $n \rightarrow \infty$.

$$\frac{1}{n} \sum K_n(x-x_i) = \int K_n(x-u) f_X(u) du + \text{remainder}$$

$$= \int K(v) f_X(x-b_n v) dv + \text{remainder}$$

$$\approx f_X(x) \int K(v) dv, \text{ for smooth } f$$

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Next

$$\begin{aligned} \frac{1}{n} \sum \delta(x_i) K_n(x-x_i) &= \int \delta(u) K_n(x-u) f_X(u) du + \text{remainder} \\ &= \int K(u) \delta(x-b_n u) f_X(x-b_n u) du + \text{remainder} \\ &\approx \delta(x) f_X(x) \int K(u) du, \text{ for smooth } \delta \text{ \& } f \end{aligned}$$

So provided $f_X(x) \neq 0$, $\int K(u) du \neq 0$

$$\boxed{E \hat{\delta}(x) \approx \delta(x)}, \text{ is asymptotically unbiased.}$$

Next consider the variance. As before

$$\begin{aligned} \frac{1}{n} \sum \sigma(x_i)^2 K_n(x-x_i)^2 &= \int \sigma(u)^2 K_n(x-u)^2 f_X(u) du + \text{remainder} \\ &= \frac{1}{b_n} \int K(u)^2 \sigma(x-b_n u)^2 f_X(x-b_n u) du + \text{remainder} \\ &\approx \frac{1}{b_n} \sigma(x)^2 f_X(x) \int K(u)^2 du \end{aligned}$$

So the variance

$$\begin{aligned} &\approx \frac{1}{n} \frac{1}{b_n} \sigma(x)^2 f_X(x) \int K(u)^2 du / \left(n f(x) \int K(u) du \right)^2 \\ &\approx \boxed{\frac{1}{n b_n} \frac{\sigma(x)^2}{f_X(x)} \frac{\int K(u)^2 du}{\left(\int K(u) du \right)^2}} \end{aligned}$$

This will tend to 0 provided $n b_n \rightarrow \infty$. Also estimate then consistent.

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Local weighting / local likelihood.

Model: $f(y|\theta)$

Suppose measurements made in time, (t_i, y_i)

Wish $\hat{\theta}(t)$ as θ may be changing.

I. Local likelihood

$$\max_{\theta} \prod_{i: |t_i - t| \leq b} f(y_i | \theta)$$

II. Local weighting,

$$\max_{\theta} \sum_i k\left(\frac{t - t_i}{b}\right) \log f(y_i | \theta)$$

cp. loess

Tibshirani

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We have been considering the models

$$Y = s(x) + \text{noise} \quad s: \text{smooth}$$

$$Y = s(x_1, x_2) + \text{noise} \quad s: \text{smooth}$$

Now turn to

$$Y = s_1(x_1) + s_2(x_2) + \text{noise} \quad s: \text{smooth}$$

The generalized additive model (gam)

Hastie and Tibshirani `gam()`

Another technique - projection pursuit

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5. Nov 01

glm.

Basis.

(\underline{x}, Y)

$$EY = \mu(\underline{x})$$

$$\eta = \underline{x}' \underline{\beta}$$

$$= g(\mu)$$

$$\mu = h(\eta)$$

$$\text{var } Y = V(\mu)$$

link function

inverse link

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to get $\hat{\beta}_1$, then $\hat{\eta}_1$; then $\hat{\mu}_1 = h(\eta_1)$ 5 Nov 01

To get started take $\hat{\mu}_0 = y$, i.e. the response

The setup (*) even suggests large sample distribution.

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Generalized linear model.

Exponential family

$$p_Y(y; \theta, \varphi) = \exp\left\{ \frac{y\theta - b(\theta)}{a(\varphi)} + c(y, \varphi) \right\}$$

 θ : natural parameter φ : dispersion parameter $\mu = E(Y)$ related to covariates X_1, \dots, X_p by

$$g(\mu) = \eta$$

where

$$\eta = \alpha + X_1\beta_1 + \dots + X_p\beta_p$$

is the linear predictor and $g(\cdot)$ is the link function.{ $\mu = b'(\theta)$, the canonical link }

$$w_i^{-1} = \left(\frac{\partial \eta_i}{\partial \mu_i} \right) V_i^{-1}$$

weights

 $V_i^{-1} \equiv$ variance of Y at μ_i^0 Regress $z_i = \eta_i^0 + (y_i - \mu_i^0) \left(\frac{\partial \eta_i}{\partial \mu_i} \right)_0$ on x_i with weights w_i

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generalized additive variant

Now

$$g(\mu) = \alpha + \sum_{j=1}^p f_j(x_j)$$

Local scoring algorithm1) Initialize

$$\alpha = g(\bar{y})$$

$$f_1^0, \dots, f_p^0 = 0$$

2) Update

$$\beta_i = \eta_i^0 + (y_i - \mu_i^0) \left(\frac{\partial \eta_i}{\partial \mu_i} \right)_0$$

with

$$\eta_i^0 = \alpha^0 + \sum_{j=1}^p f_j^0(x_{ij})$$

$$\mu_i^0 = g^{-1}(\eta_i^0)$$

$$w_i = \left(\frac{\partial \mu_i}{\partial \eta_i} \right)_0^2 (V_i^0)^{-1}$$

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Fit a weighted additive model to z_i to
obtain: estimated functions f_j'
predictor η'
fitted values μ_i'

Convergence criterion

$$\Delta(\eta', \eta^0) = \frac{\sum_{j=1}^p \|f_j' - f_j^0\|}{\sum_{j=1}^p \|f_j^0\|}$$

iii) Repeat step ii) replacing η^0 by η' until
 $\Delta(\eta', \eta^0)$ is below some small threshold.

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Alternate approach to gam.

Penalized likelihood

linear predictor

$$\eta_i = \alpha + \sum_{j=1}^p f_j(x_{ij})$$

log likelihood $l(\underline{\eta}; \underline{y})$

Find functions f_1, \dots, f_p to maximize

$$l(\underline{\eta}; \underline{y}) - \frac{1}{2} \sum_{j=1}^p \lambda_j \int [f_j''(x)]^2 dx$$

$$\lambda_j \geq 0$$

Cox & O'Sullivan (1985)

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Resistant fitting of additive models.

Penalized M-estimator

$$\sum_{i=1}^n \hat{\sigma}^2 \rho \left\{ \frac{y_i - \sum_{j=1}^p f_j(x_{ij})}{\hat{\sigma}} \right\} + \frac{1}{2} \sum_{j=1}^p \lambda_j \int [f_j''(x)]^2 dx$$

Iterative re-weighting $\psi = \rho'$

$$w_i = \frac{\psi(r_i / \hat{\sigma})}{r_i / \hat{\sigma}}$$

$$r_i = y_i - \sum_{j=1}^p f_j(x_{ij})$$

$$\hat{\sigma} = \text{med } |r_i| / 0.67$$

Solution sum of cubic splines
Can use Newton-Raphson

$$f(x) = \alpha + \sum_{j=1}^{k+3} \alpha_j B_j(x) \quad k \text{ knots}$$

Linear parametrization, Easy way to think about it all.

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Resistant fitting of gam's

View deviance contribution $D(y_i; \hat{\mu}_i)$ as analog
of $(y_i - \hat{\mu}_i)^2$.

$$g(\mu_i) = \alpha + \sum_j f_j(x_{ij})$$

Re-express $\rho(r)$ as $w(r^2)$

Penalized criterion

$$\sum_{i=1}^n w_i \{ D(y_i; \mu_i) \} + \frac{1}{2} \sum_{j=1}^p \lambda_j \int [f_j''(x)]^2 dx$$

Express f_j using finite dimensional basis

Use penalized iterative reweighted least squares

May need to use

$$D(y_i; \mu_i) / \hat{\sigma}^2$$

eg. $\hat{\sigma} = \text{med } D(y_i; \hat{\mu}_i)$

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gam(, family = robust(binomial))

cp. robust version of glm()

Instead of minimizing usual
 $\sum_{i=1}^n b(y_{i,j}; \mu_i)$

minimize

$$D_w = \sum_{i=1}^n \hat{\sigma}^2 w_i \left(\frac{D(y_{i,j}; \mu_i)}{\hat{\sigma}^2} \right)$$

$\hat{\sigma}$: robust estimate of scale

Idea: damp down large contributions

eg.

$$w(t) = \begin{cases} t & t \leq k^2 \\ 2k\sqrt{t} - k^2 & t > k^2 \end{cases}$$

eg. $k = 1.345$

Iterative weights get multiplied by a factor which is ~ 1 for small deviance contributions and gets small for large contributions

```

> robust
function(family = gaussian(), scale = 0, k = 1.345, maxit = 10)
{
  family <- as.family(family)
  weight <- family$weight
  new.exp <- eval(if(scale == 0) substitute(expression({
    if(iter == 1)
      robweight <- 1
    else {
      if(iter == 2) {
        robust.scale <- median(abs(family$deviance(mu,
          y, w, T, F)))/0.67
        attr(w, "robust") <- c(robust.scale, k)
      }
      robust.scale <- attr(w, "robust")[1]
      robweight <- (k * robust.scale)/abs(family$
        deviance(mu, y, w, T, F))
      robweight <- ifelse(robweight > 1, 1, robweight
        )
    }
  }
), list(k = k)) else substitute(expression({
  robweight <- (k * scale)/abs(family$deviance(mu, y, w,
    T, F))
  robweight <- ifelse(robweight > 1, 1, robweight)
  attr(w, "robust") <- c(scale, k)
}
), list(k = k, scale = scale)))
dummy <- expression(junk * robweight)
dummy[[1]][[2]] <- weight[[1]]
new.exp[[1]][[length(new.exp[[1]]) + 1]] <- dummy[[1]]
family$weight <- new.exp
family$deviance <- substitute(function(mu, y, w, residuals = F, robust
  = T)
{
  old.deviance <- function(mu, y, w, residuals = F)
  body
  if(!robust)
    return(old.deviance(mu, y, w, residuals))
  a <- attr(w, "robust")
  if(is.null(a))
    return(old.deviance(mu, y, w, residuals))
  else {
    robust.scale <- a[1]
    k <- a[2] * robust.scale
    dev <- old.deviance(mu, y, w, T) #
    # remember if there are prior weights they are included here
    devtest <- abs(dev) <= k
    devsq <- dev^2 * devtest + (!devtest) * (2 * k * abs(
      dev) - k^2)
    if(residuals)
      sign(dev) * sqrt(devsq)
    else sum(devsq)
  }
}
, list(body = family$deviance[[5]]))
family$family["name"] <- paste("Robust", family$family["name"])
family$initialize <- c(family$initialize, substitute(expression(maxit <-
  nit), list(nit = maxit))[2])
family
}

```


typescript Mon Oct 22 13:29:49 2001 1

Script started on Mon Oct 22 13:29:34 2001
script_wol.brill% Splus<analfromel
License Warning : S-PLUS license expires Wed Oct 31 23:59:59 2001
S-PLUS : Copyright (c) 1988, 1996 MathSoft, Inc.
S : Copyright AT&T.
Version 3.4 Release 1 for Sun SPARC, SunOS 5.3 : 1996
Working data will be in /saruman/accounts/fac/brill/.Data

Call: glm(formula = y ~ a + b + offset(log(n)), family = "poisson")
Deviance Residuals:

	Min	1Q	Median	3Q	Max
	-1.832904	-0.8559731	-0.3807713	0.4241323	2.176178

Coefficients:

	Value	Std. Error	t value
(Intercept)	-7.2810177	0.1724004	-42.2331955
a1	-2.1787235	0.5027471	-4.3336372
a2	-0.9586813	0.3663622	-2.6167581
a3	-0.0796293	0.2562401	-0.3107605
a4	0.1302123	0.2492969	0.5223182
a5	0.7221383	0.1716511	4.2070126
a6	0.9374875	0.1689896	5.5476038
b1	-3.1187052	0.8933875	-3.4908761
b2	-2.1717629	0.5299118	-4.0983481
b3	-1.4171269	0.3886831	-3.6459703
b4	0.0842177	0.2294316	0.3670711
b5	0.1235435	0.2421091	0.5102803
b6	1.0901213	0.2050192	5.3171658
b7	1.3289269	0.2177310	6.1035266
b8	1.7861285	0.2292702	7.7904966

(Dispersion Parameter for Poisson family taken to be 1)

Null Deviance: 445.099 on 62 degrees of freedom

Residual Deviance: 51.47087 on 48 degrees of freedom

Number of Fisher Scoring Iterations: 5

Call: glm(formula = y ~ d + b + offset(log(n)), family = poisson)
Deviance Residuals:

	Min	1Q	Median	3Q	Max
	-1.991026	-1.202705	-0.3255014	0.4096175	2.018623

Coefficients:

	Value	Std. Error	t value
(Intercept)	-11.7739704	0.37019955	-31.804389
d	0.4886346	0.04956777	9.857911
b	0.5637749	0.03775633	14.931931

(Dispersion Parameter for Poisson family taken to be 1)

Null Deviance: 445.099 on 62 degrees of freedom

Residual Deviance: 71.21102 on 60 degrees of freedom

Number of Fisher Scoring Iterations: 4

Correlation of Coefficients:

	(Intercept)	d
d	-0.7462301	
b	-0.6817992	0.0678269

Call: gam(formula = y ~ lo(d) + lo(b) + offset(log(n)), family = poisson)
Deviance Residuals:

British physicians: 1 & 2 fitted factors, 3 & 4 via ~~gam~~

