

AdaBoost is Universally Consistent

Peter Bartlett

Computer Science Division and Department of Statistics
UC Berkeley.

Joint work with Mikhail Traskin.

AdaBoost

Sample, $S_n = ((x_1, y_1), \dots, (x_n, y_n)) \in (X \times \{\pm 1\})^n$

Number of iterations, T

function AdaBoost(S_n, T)

$f_0 := 0$

for t from $1, \dots, T$

$$(\alpha_t, h_t) := \arg \min_{\alpha \in \mathbb{R}, h \in F} \frac{1}{n} \sum_{i=1}^n \exp(-y_i (f_{t-1}(x_i) + \alpha h(x_i)))$$

$$f_t := f_{t-1} + \alpha_t h_t$$

return f_T

Universal Consistency

- Assume: **i.i.d. data**, $(X, Y), (X_1, Y_1), \dots, (X_n, Y_n)$ from $\mathcal{X} \times \mathcal{Y}$ (with $\mathcal{Y} = \{\pm 1\}$).
- Consider a method $f_n = A((X_1, Y_1), \dots, (X_n, Y_n))$,
e.g., $f_n = \text{AdaBoost}((X_1, Y_1), \dots, (X_n, Y_n), t_n)$.

Definition: We say that the method is **universally consistent** if, for all distributions P ,

$$L(f_n) \xrightarrow{a.s.} L^*,$$

where L is the **risk** and L^* is the **Bayes risk**:

$$L(f) = \Pr(Y \neq \text{sign}(f(X))), \quad L^* = \inf_f L(f).$$

AdaBoost is Universally Consistent

- Previous results
- The key theorem:
Universal consistency for sublinearly increasing stopping times.
- Idea of proof
- Open questions

Previous results: Regularized versions

AdaBoost greedily minimizes

$$\mathbf{E}_n \exp(-Y f(X)) = \frac{1}{n} \sum_{i=1}^n \exp(-Y_i f(X_i))$$

over $f \in \text{span}(F)$.

(Notice that, for many interesting basis classes F , the infimum is zero.)

Instead of AdaBoost, consider a **regularized version of its criterion**.

Previous results: Regularized versions

1. Minimize

$$\mathbf{E}_n \exp(-Y f(X))$$

over $f \in \gamma_n \text{co}(F)$, the scaled (by γ_n) convex hull of F .

2. Minimize

$$\mathbf{E}_n \exp(-Y f(X)) + \lambda_n \|f\|_*,$$

over $f \in \text{span}(F)$, where $\|f\|_* = \inf\{\gamma : f \in \gamma \text{co}(F)\}$.

For suitable choices of the parameters (γ_n and λ_n), these algorithms are universally consistent.

(Lugosi and Vayatis, 2004), (Zhang, 2004)

Previous results: Bounded step size

function AdaBoostwithBoundedStepSize(S_n, T)

$f_0 := 0$

for t from $1, \dots, T$

$$(\alpha_t, h_t) := \arg \min_{\alpha \in \mathbb{R}, h \in F} \frac{1}{n} \sum_{i=1}^n \exp(-y_i (f_{t-1}(x_i) + \alpha h(x_i)))$$

$$f_t := f_{t-1} + \min\{\alpha_t, \epsilon\} h_t$$

return f_T

For suitable choices of the parameters ($T = T_n$ and $\epsilon = \epsilon_n$), this algorithm is universally consistent.

(Zhang and Yu, 2005), (Bickel, Ritov, Zakai, 2006)

Previous results about AdaBoost

AdaBoost greedily minimizes

$$\mathbf{E}_n \exp(-Y f(X)) = \frac{1}{n} \sum_{i=1}^n \exp(-Y_i f(X_i))$$

over $f \in \text{span}(F)$.

- What is f_n ?

The function returned by AdaBoost after t_n steps.

- What is t_n ?

Note: The infimum is often zero. Don't want t_n too large.

Previous result about AdaBoost: ‘Process consistency’

Theorem: [Jiang, 2004] For all probability distributions P satisfying certain smoothness assumptions,
there is a sequence t_n such that $f_n = \text{AdaBoost}(S_n, t_n)$ satisfies

$$L(f_n) \xrightarrow{a.s.} L^*.$$

- Conditions on the distribution P are unnatural and cannot be checked.
- How should the stopping time t_n grow with sample size n ?
Does it need to depend on the distribution P ?
- Rates?

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The key theorem

- Assume $d_{VC}(F) < \infty$
Otherwise AdaBoost must stop and fail after one step.

- Assume

$$\lim_{\lambda \rightarrow \infty} \inf \{R(f) : f \in \lambda \text{co}(F)\} = R^*,$$

where

$$R(f) = \mathbf{E} \exp(-Y f(X)), \quad R^* = \inf_f R(f).$$

That is, the approximation error is zero.

For example, F is linear threshold functions, or binary trees with axis orthogonal decisions in \mathbb{R}^d and at least $d + 1$ leaves.

The key theorem

Theorem: If

$$d_{VC}(F) < \infty,$$

$$R_{\phi}^* = \liminf_{\lambda \rightarrow \infty} \{R_{\phi}(f) : f \in \lambda \text{co}(F)\},$$

$$t_n \rightarrow \infty$$

$$t_n = O(n^{1-\alpha}) \quad \text{for some } \alpha > 0,$$

then AdaBoost is universally consistent.

The key theorem: Idea of proof

We show $R(f_{t_n}) \rightarrow R^*$, which implies $L(f_{t_n}) \rightarrow L^*$, since the loss function $\alpha \mapsto \exp(-\alpha)$ is classification calibrated.

Step 1. Notice that we can clip f_{t_n} :

If we define $\pi_\lambda(f)$ as $x \mapsto \max\{-\lambda, \min\{\lambda, f(x)\}\}$, then

$$R(\pi_\lambda(f_{t_n})) \rightarrow R^* \implies L(\pi_\lambda(f_{t_n})) \rightarrow L^* \implies L(f_{t_n}) \rightarrow L^*.$$

We will need to relax the clipping ($\lambda_n \rightarrow \infty$).

The key theorem: Idea of proof

Step 2. Use VC-theory (for clipped combinations of t functions from F) to show that, with high probability,

$$R(\pi_\lambda(f_t)) \leq R_n(\pi_\lambda(f_t)) + c(\lambda) \sqrt{\frac{d_{VC}(F)t \log t}{n}},$$

where R_n is the empirical version of R ,

$$R_n(f) = \mathbf{E}_n \exp(-Y f(X)).$$

The key theorem: Idea of proof

Step 3. The clipping only hurts for small values of the exponential criterion:

$$R_n(\pi_\lambda(f_t)) \leq R_n(f_t) + e^{-\lambda}.$$

The key theorem: Idea of proof

Step 4. Apply numerical convergence result of (Bickel et al, 2006): For any comparison function $\bar{f} \in F_\lambda$,

$$R_n(f_t) \leq R_n(\bar{f}) + \epsilon(\lambda, t).$$

The key theorem: Idea of proof

Step 5. Apply VC-theory again to relate $R_n(\bar{f})$ to $R(\bar{f})$.

Choosing $\lambda_n \rightarrow \infty$ suitably slowly, we can choose \bar{f}_n so that $R(\bar{f}_n) \rightarrow R^*$ (by assumption), and then for $t = O(n^{1-\alpha})$, we have the result.

Open Problems

- Other loss functions?

e.g., LogitBoost uses $\alpha \mapsto \log(1 + \exp(-2\alpha))$ in place of $\exp(-\alpha)$. (The difficulty is the behaviour of the second derivative of R_n in the direction of a basis function. For the numerical convergence results, we want it large whenever R_n is large.)

- Real-valued basis functions?

(The same issue arises.)

- Rates?

The bottleneck is the rate of decrease of $R_n(f_t)$. The (Bickel et al, 2006) result ensures it decreases to \bar{f} as $\log^{-1/2} t$. This seems pessimistic.

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Slides at <http://www.cs.berkeley.edu/~bartlett>