

CS281B/Stat241B. Statistical Learning Theory.

Lecture 12.

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- Tuning Fixed Share for low adaptive regret (See lecture 11 notes).
- Normalised Maximum Likelihood
- Universal Portfolios

Normalised Maximum Likelihood

Today we look at *probability forecasting*.

Log loss measures mismatch of probability prediction P and outcome x :

$$\text{loss}(P, x) = -\ln P(x)$$

Log-loss game

Protocol:

- For $t = 1, 2, \dots$
 - Learner chooses a distribution P_t on outcomes \mathcal{X} .
 - Adversary reveals outcome $x_t \in \mathcal{X}$.
 - Learner incurs the **log loss** $-\ln P_t(x_t)$.

Joint vs predictive viewpoint

Correspondence between

- Joint distribution $P(x_1, \dots, x_T)$ and
- Prediction strategy $P(x_t | x_1, \dots, x_{t-1})$

Log loss telescopes:

$$\sum_{t=1}^T -\ln P(x_t | x_1, \dots, x_{t-1}) = -\ln P(x_1, \dots, x_T)$$

Reference strategies : probabilistic model

This lecture: compete with a family of distributions

$$\{P_\theta(x_1, \dots, x_T) \mid \theta \in \Theta\}$$

Regret w.r.t. Θ

$$R_T = \underbrace{\sum_{t=1}^T -\ln P_t(x_t)}_{\text{Loss of Learner}} - \underbrace{\inf_{\theta \in \Theta} -\ln P_\theta(x_1, \dots, x_T)}_{\text{Loss of best parameter } \theta \in \Theta}$$

Crucial new ingredient: Learner has *white-box* access to “experts” P_θ .

From T rounds to one mega round

Sequential minimax reduces to single-shot

$$\min_{P_1} \max_{x_1} \dots \min_{P_T} \max_{x_T} R_T = \min_P \max_{x_1, \dots, x_T} R_T$$

Idea: joint distribution P already encodes all sequential behaviour

Minimax game solution

Theorem: The T -round log loss prediction game w. model Θ

$$\min_P \max_{x^T} R_T \left(= \max_Q \min_P \mathbb{E}_{x^T \sim Q} R_T \right)$$

has value given by the *parametric complexity* of model Θ

$$\mathfrak{C}_T(\Theta) := \ln \left(\sum_{x_1, \dots, x_T} \sup_{\theta \in \Theta} P_\theta(x_1, \dots, x_T) \right),$$

and both Learner's minimax and Adversary's maximin strategy are the *Normalised Maximum Likelihood* distribution

$$P_T^{\text{NML}}(x_1, \dots, x_T) = \frac{\sup_{\theta \in \Theta} P_\theta(x_1, \dots, x_T)}{\sum_{z_1, \dots, z_T} \sup_{\theta \in \Theta} P_\theta(z_1, \dots, z_T)}$$

Minimax analysis

For Learner, P^{NML} equalises the regret over all sequences x^T :

$$-\ln P^{\text{NML}}(x^T) - \inf_{\theta} -\ln P_{\theta}(x^T) = \mathfrak{C}_T(\Theta)$$

For Adversary, we need to do some work:

$$\begin{aligned} & \max_Q \min_P \mathbb{E}_{x^T \sim Q} \left[-\ln P(x^T) - \inf_{\theta} -\ln P_{\theta}(x^T) \right] \\ &= \max_Q \mathbb{E}_{x^T \sim Q} \left[-\ln Q(x^T) - \inf_{\theta} -\ln P_{\theta}(x^T) \right] \end{aligned}$$

To find maximin distribution Q introduce Lagrange multiplier λ

$$= \min_{\lambda} \max_Q \mathbb{E}_{x^T \sim Q} \left[-\ln Q(x^T) - \inf_{\theta} -\ln P_{\theta}(x^T) \right] + \lambda \left(1 - \sum_{x^T} Q(x^T) \right)$$

At the optimal Q the derivative of the objective vanishes, i.e.

$$0 = -\ln Q(x^T) + 1 - \lambda - \inf_{\theta} -\ln P_{\theta}(x^T)$$

from which it follows that

$$Q(x^T) = \frac{\sup_{\theta} P_{\theta}(x^T)}{\sum_{x^T} \dots} = P^{\text{NML}}(x^T)$$

Plugging this in, we find that the value again equals $\mathfrak{C}_T(\Theta)$.

Discussion

- Continuous case: densities w.r.t. reference measure
- Efficient implementation tricky.
- NML strategy depends on final horizon T .
- Infinite parametric complexity $\Rightarrow P^{\text{NML}}$ undefined.
- Sometimes success with *Sequential NML* (SNML), also known as *Last Step Minimax*. In round t play minimiser of

$$\min_{P_t} \max_{x_t} -\ln P_t(x_t) - \inf_{\theta \in \Theta} -\ln P_\theta(x_1, \dots, x_t)$$

Universal portfolios

Best fixed weights

Back to the mix loss game without outcomes.

In lecture 9 we minimised regret w.r.t. the best expert.

Today we consider a more ambitious reference class:

Definition: Regret w.r.t. the best fixed weights

$$R_T = \underbrace{\sum_{t=1}^T -\ln \left(\sum_{k=1}^K w_t^k e^{-\ell_t^k} \right)}_{\text{Mix loss of Learner}} - \inf_{\mathbf{w}} \underbrace{\sum_{t=1}^T -\ln \left(\sum_{k=1}^K w^k e^{-\ell_t^k} \right)}_{\text{Mix loss of fixed weights } \mathbf{w}}$$

Investment interpretation

Loss ℓ^k is negative log return of stock k , i.e. $\ell_t^k = -\ln \frac{\text{price}_{t+1}^k}{\text{price}_t^k}$

Weight vector w is portfolio: fraction w^k of capital invested in stock k .

Mix loss is negative log return of portfolio:

$$-\ln \sum_{k=1}^K w_t^k e^{-\ell_t^k} = -\ln \sum_{k=1}^K w_t^k \frac{\text{price}_{t+1}^k}{\text{price}_t^k}$$

Strategy playing fixed weights w called *constantly rebalanced portfolio*

Strategy with low regret w.r.t. best w called *universal portfolio*

Intuition

Mix loss is convex in w , so minimiser typically in interior of simplex

stock	daily return							
A	$\frac{1}{2}$	2	$\frac{1}{2}$	2	$\frac{1}{2}$	2	$\frac{1}{2}$	2
B	3	$\frac{1}{3}$	3	$\frac{1}{3}$	3	$\frac{1}{3}$	3	$\frac{1}{3}$

Best single stock: overall return 1.

Best portfolio:

$$\max_p \left\{ 4 \ln \left(p \frac{1}{2} + (1-p)3 \right) + 4 \ln \left(p 2 + (1-p) \frac{1}{3} \right) \right\}$$

results in $p = \frac{1}{2}$ and per-round log return

$$0.357 \approx \ln(1.43)$$

Technology

“Experts” are constantly rebalanced portfolios w .

We again have white-box experts.

Close w have close loss.

First idea:

- Run AA on finely discretised simplex.
- Regret: overhead of AA w.r.t. best discretisation point plus overhead of best discretisation point w.r.t. best portfolio
- Balancing act.

Second idea:

- Run AA with density on simplex (discretise infinitely fine).
- Balancing act only in analysis.

Cover's *Universal* “algorithm”

Put Dirichlet $(\frac{1}{2}, \dots, \frac{1}{2})$ prior on simplex: $\pi_1(\mathbf{w}) = \frac{\prod_{k=1}^K w_k^{-1/2}}{\int \dots d\mathbf{w}}$.

Density in round t :

$$\begin{aligned}\pi_t(\mathbf{w}) &= \frac{\pi_1(\mathbf{w}) e^{-\sum_{s=1}^{t-1} \ln \sum_{k=1}^K w^k e^{-\ell_s^k}}}{\int \dots d\mathbf{w}} \\ &= \frac{\pi_1(\mathbf{w}) \prod_{s=1}^{t-1} \left(\sum_{k=1}^K w^k e^{-\ell_s^k} \right)}{\int \dots d\mathbf{w}}\end{aligned}$$

Actual portfolio \mathbf{w}_t played:

$$\mathbf{w}_t = \int \mathbf{w} \pi_t(\mathbf{w}) d\mathbf{w}$$

Analysis

Cumulative mix loss of Universal again telescopes:

$$\begin{aligned} & \sum_{t=1}^T -\ln \left(\sum_{k=1}^K w_t^k e^{-\ell_t^k} \right) \\ &= \sum_{t=1}^T -\ln \left(\sum_{k=1}^K \left(\int w^k \pi_t(\mathbf{w}) \, d\mathbf{w} \right) e^{-\ell_t^k} \right) \\ &= \sum_{t=1}^T -\ln \left(\int \left(\sum_{k=1}^K w^k e^{-\ell_t^k} \right) \pi_t(\mathbf{w}) \, d\mathbf{w} \right) \\ &= -\ln \left(\int \pi_1(\mathbf{w}) \prod_{t=1}^T \left(\sum_{k=1}^K w^k e^{-\ell_t^k} \right) \, d\mathbf{w} \right) \end{aligned}$$

However, we cannot bound using a single \mathbf{w} .

Analysis

Regret

$$\begin{aligned} R_T &= \sup_{\mathbf{w}} \ln \frac{\prod_{t=1}^T \left(\sum_{k=1}^K w^k e^{-\ell_t^k} \right)}{\int \pi_1(\mathbf{w}) \prod_{t=1}^T \left(\sum_{k=1}^K w^k e^{-\ell_t^k} \right) d\mathbf{w}} \\ &\leq \sup_{\mathbf{w}} \max_{k_1, \dots, k_T} \ln \frac{\prod_{t=1}^T w_{k_t} e^{-\ell_t^{k_t}}}{\int \pi_1(\mathbf{w}) \prod_{t=1}^T w_{k_t} e^{-\ell_t^{k_t}} d\mathbf{w}} \\ &= \sup_{\mathbf{w}} \max_{k_1, \dots, k_T} \ln \frac{\prod_{t=1}^T w_{k_t}}{\int \pi_1(\mathbf{w}) \prod_{t=1}^T w_{k_t} d\mathbf{w}} \\ &\leq \frac{K-1}{2} \ln T + \ln K \end{aligned}$$

The first inequality follows from the log-sum inequality, which is tight when *every round* all but one expert suffer infinite loss.

The last inequality is the regret bound for the KT estimator (see Catoni 2004).

Now the worst-case is when k_1, \dots, k_T identical.

Discussion

Universal algorithm not efficient. Can integrate in $O(T^{K-1})$ time.

Algorithms based on sampling. Typically \sqrt{T} regret regime.

Can use efficient Online Newton Step, which has $O(\ln T)$ regret provided the expert losses are bounded (shares do not spike/crash too much per round).

Transaction costs?

Adaptive regret? Perhaps slow drift instead of abrupt switches?