Introduction to Time Series Analysis. Lecture 2. Peter Bartlett

Last lecture:

- 1. Objectives of time series analysis.
- 2. Time series models.
- 3. Time series modelling: Chasing stationarity.

Introduction to Time Series Analysis. Lecture 2. Peter Bartlett

- 1. Stationarity
- 2. Autocovariance, autocorrelation
- 3. MA, AR, linear processes
- 4. Sample autocorrelation function

 $\{X_t\}$ is strictly stationary if

for all $k, t_1, \ldots, t_k, x_1, \ldots, x_k$, and h,

$$P(X_{t_1} \le x_1, \dots, X_{t_k} \le x_k) = P(X_{t_1+h} \le x_1, \dots, X_{t_k+h} \le x_k).$$

i.e., shifting the time axis does not affect the distribution.

We shall consider **second-order properties** only.

Mean and Autocovariance

Suppose that $\{X_t\}$ is a time series with $\mathrm{E}[X_t^2] < \infty$.

Its **mean function** is

$$\mu_t = \mathrm{E}[X_t].$$

Its autocovariance function is

$$\gamma_X(s,t) = \text{Cov}(X_s, X_t)$$
$$= \text{E}[(X_s - \mu_s)(X_t - \mu_t)].$$

Weak Stationarity

We say that $\{X_t\}$ is (weakly) stationary if

- 1. μ_t is independent of t, and
- 2. For each h, $\gamma_X(t+h,t)$ is independent of t.

In that case, we write

$$\gamma_X(h) = \gamma_X(h,0).$$

The autocorrelation function (ACF) of $\{X_t\}$ is defined as

$$\rho_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)}$$

$$= \frac{\text{Cov}(X_{t+h}, X_t)}{\text{Cov}(X_t, X_t)}$$

$$= \text{Corr}(X_{t+h}, X_t).$$

Example: i.i.d. noise, $E[X_t] = 0$, $E[X_t^2] = \sigma^2$. We have

$$\gamma_X(t+h,t) = \begin{cases} \sigma^2 & \text{if } h = 0, \\ 0 & \text{otherwise.} \end{cases}$$

Thus,

- 1. $\mu_t = 0$ is independent of t.
- 2. $\gamma_X(t+h,t) = \gamma_X(h,0)$ for all t.

So $\{X_t\}$ is stationary.

Similarly for any white noise (uncorrelated, zero mean), $X_t \sim WN(0, \sigma^2)$.

Example: Random walk, $S_t = \sum_{i=1}^t X_i$ for i.i.d., mean zero $\{X_t\}$. We have $E[S_t] = 0$, $E[S_t^2] = t\sigma^2$, and

$$\gamma_S(t+h,t) = \text{Cov}(S_{t+h}, S_t)$$

$$= \text{Cov}\left(S_t + \sum_{s=1}^h X_{t+s}, S_t\right)$$

$$= \text{Cov}(S_t, S_t) = t\sigma^2.$$

- 1. $\mu_t = 0$ is independent of t, but

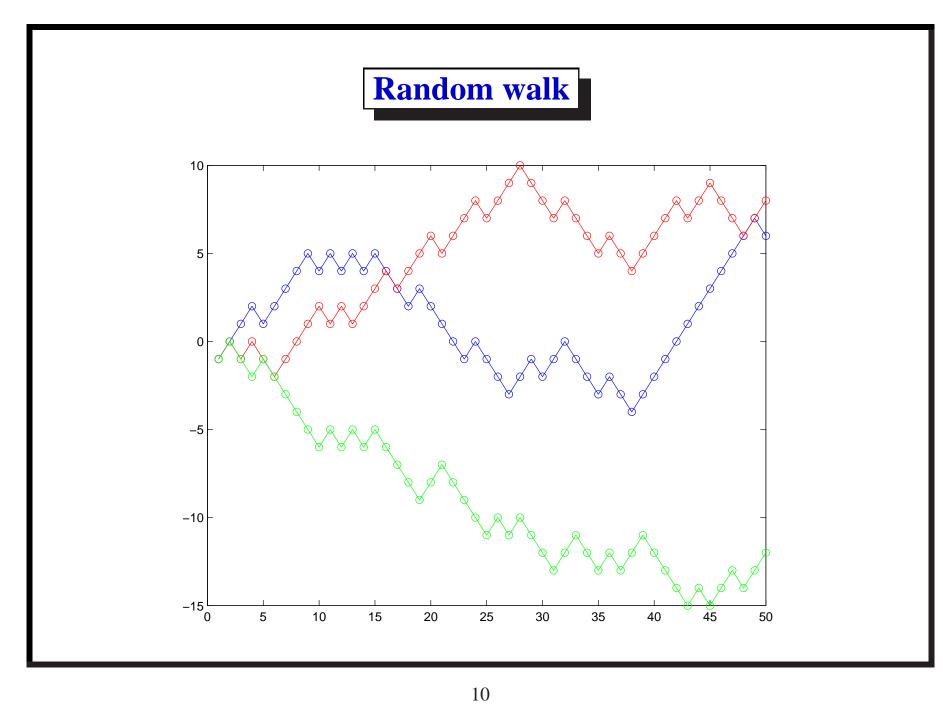
2. $\gamma_S(t+h,t)$ is not. So $\{S_t\}$ is not stationary.

An aside: covariances

$$Cov(X + Y, Z) = Cov(X, Z) + Cov(Y, Z),$$
$$Cov(aX, Y) = a Cov(X, Y),$$

Also if X and Y are independent (e.g., X = c), then

$$Cov(X, Y) = 0.$$



Example: MA(1) process (**Moving Average**):

$$X_t = W_t + \theta W_{t-1}, \qquad \{W_t\} \sim WN(0, \sigma^2).$$

We have $E[X_t] = 0$, and

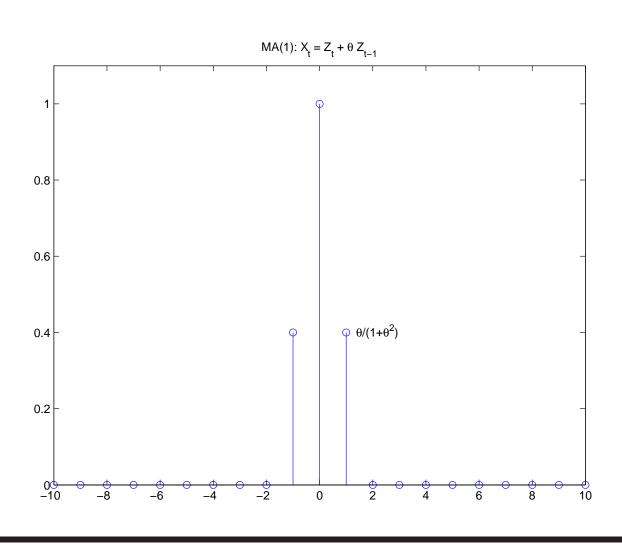
$$\gamma_X(t+h,t) = \mathbf{E}(X_{t+h}X_t)$$

$$= \mathbf{E}[(W_{t+h} + \theta W_{t+h-1})(W_t + \theta W_{t-1})]$$

$$= \begin{cases} \sigma^2(1+\theta^2) & \text{if } h = 0, \\ \sigma^2\theta & \text{if } h = \pm 1, \\ 0 & \text{otherwise.} \end{cases}$$

Thus, $\{X_t\}$ is stationary.

ACF of the MA(1) process



Example: AR(1) process (**AutoRegressive**):

$$X_t = \phi X_{t-1} + W_t, \qquad \{W_t\} \sim WN(0, \sigma^2).$$

Assume that X_t is stationary and $|\phi| < 1$. Then we have

$$E[X_t] = \phi E X_{t-1}$$

$$= 0 \quad \text{(from stationarity)}$$

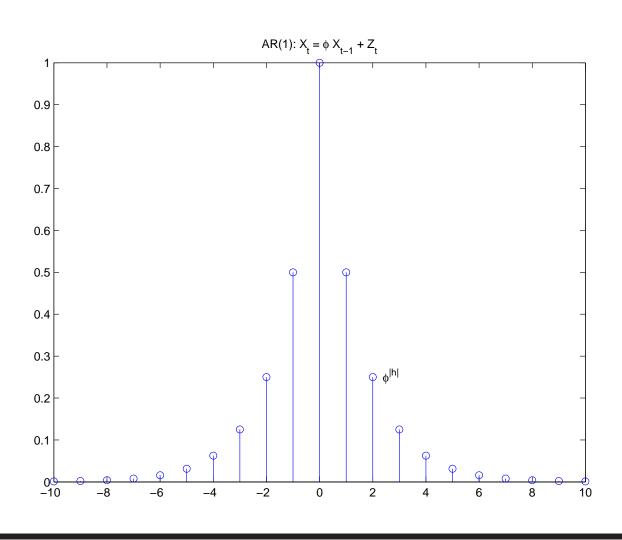
$$E[X_t^2] = \phi^2 E[X_{t-1}^2] + \sigma^2$$

$$= \frac{\sigma^2}{1 - \phi^2} \quad \text{(from stationarity)},$$

Example: AR(1) process, $X_t = \phi X_{t-1} + W_t$, $\{W_t\} \sim WN(0, \sigma^2)$. Assume that X_t is stationary and $|\phi| < 1$. Then we have

$$\begin{split} \mathbf{E}[X_t] &= 0, \qquad \mathbf{E}[X_t^2] = \frac{\sigma^2}{1 - \phi^2} \\ \gamma_X(h) &= \mathrm{Cov}(\phi X_{t+h-1} + W_{t+h}, X_t) \\ &= \phi \mathrm{Cov}(X_{t+h-1}, X_t) \\ &= \phi \gamma_X(h-1) \\ &= \phi^{|h|} \gamma_X(0) \qquad \text{(check for } h > 0 \text{ and } h < 0) \\ &= \frac{\phi^{|h|} \sigma^2}{1 - \phi^2}. \end{split}$$

ACF of the AR(1) process



Linear Processes

An important class of stationary time series:

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$$

where $\{W_t\} \sim WN(0, \sigma_w^2)$

and μ, ψ_j are parameters satisfying

$$\sum_{j=-\infty}^{\infty} |\psi_j| < \infty.$$

Linear Processes

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$$

We have

$$\mu_X = \mu$$

$$\gamma_X(h) = \sigma_w^2 \sum_{j=-\infty}^\infty \psi_j \psi_{h+j}.$$
 (why?)

Examples of Linear Processes: White noise

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$$

Choose
$$\mu$$
,
$$\psi_j = \begin{cases} 1 & \text{if } j = 0, \\ 0 & \text{otherwise.} \end{cases}$$

Then
$$\{X_t\} \sim WN(\mu, \sigma_W^2)$$
.

Examples of Linear Processes: MA(1)

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$$

Choose
$$\mu = 0$$

$$\psi_j = \begin{cases} 1 & \text{if } j = 0, \\ \theta & \text{if } j = 1, \\ 0 & \text{otherwise.} \end{cases}$$

Then
$$X_t = W_t + \theta W_{t-1}$$
.

(why?)

Examples of Linear Processes: AR(1)

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$$

Choose
$$\mu = 0$$

$$\psi_j = \begin{cases} \phi^j & \text{if } j \ge 0, \\ 0 & \text{otherwise.} \end{cases}$$

Then for $|\phi| < 1$, we have $X_t = \phi X_{t-1} + W_t$.

(why?)

Estimating the ACF: Sample ACF

Recall:

Suppose that $\{X_t\}$ is a stationary time series.

Its mean is

$$\mu = \mathrm{E}[X_t].$$

Its autocovariance function is

$$\gamma(h) = \operatorname{Cov}(X_{t+h}, X_t)$$
$$= \operatorname{E}[(X_{t+h} - \mu)(X_t - \mu)].$$

Its autocorrelation function is

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)}.$$

Estimating the ACF: Sample ACF

For observations x_1, \ldots, x_n of a time series,

the sample mean is
$$\bar{x} = \frac{1}{n} \sum_{t=1}^{n} x_t$$
.

The sample autocovariance function is

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (x_{t+|h|} - \bar{x})(x_t - \bar{x}),$$

for -n < h < n.

The sample autocorrelation function is

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}.$$

Estimating the ACF: Sample ACF

Sample autocovariance function:

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (x_{t+|h|} - \bar{x})(x_t - \bar{x}).$$

 \approx the sample covariance of $(x_1, x_{h+1}), \dots, (x_{n-h}, x_n)$, except that

- \bullet we normalize by n instead of n-h, and
- we subtract the full sample mean.

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