

- Forecasting
- Peter Bartlett
- Introduction to Time Series Analysis. Lecture 8.
1. Linear prediction.
  2. Projection in Hilbert space.
  3. Forecasting and backcasting.
  4. Prediction operator.

For a stationary time series  $\{X_t\}$ , the best linear predictor is

$$\hat{x}_t = \alpha_0 + \alpha_1 x_{t-1} + \epsilon_t$$

where  $\epsilon_t$  is the error term.

Consider a linear predictor of  $X_{t+h}$  given  $X_t$ :

$$\hat{x}_{t+h} = \alpha_0 + \alpha_1 x_t + \epsilon_{t+h}$$

The mean squared error of prediction is:

$$E[(\hat{x}_{t+h} - x_{t+h})^2] = E[(\alpha_0 + \alpha_1 x_t + \epsilon_{t+h} - x_{t+h})^2]$$

$$= E[(\alpha_0 + \alpha_1 x_t - x_{t+h})^2 + \epsilon_{t+h}^2]$$

$$= (\alpha_0 + \alpha_1 x_t - x_{t+h})^2 + \sigma^2$$

$$= (\alpha_0 + \alpha_1 x_t - x_{t+h})^2 + \sigma^2$$

## Review: Least squares linear prediction

This is a special case of the *projection theorem*.

$$\mathbb{E}[(X_{n+m} - \alpha_0 - \sum_{i=1}^n \alpha_i X_i)^2] = 0 \quad \text{for } i = 1, \dots, n.$$

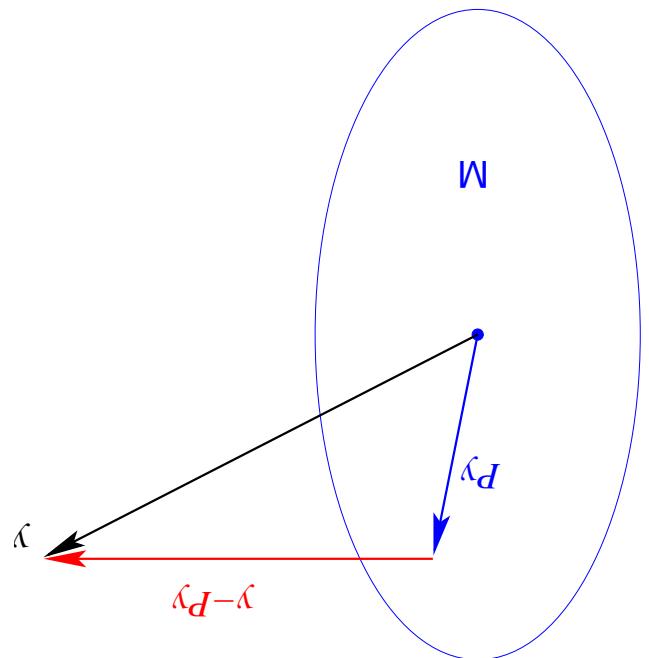
$$\mathbb{E}(X_{n+m} - \alpha_0 - \sum_{i=1}^n \alpha_i X_i) = 0$$

of  $X_{n+m}$  satisfies the **prediction equations**

$$\sum_{i=1}^n \alpha_i X_i + \alpha_0 = X_{n+m}$$

Given  $X_1, X_2, \dots, X_n$ , the best linear predictor

**Linear prediction**



- If  $H$  is a Hilbert space,  
 $M$  is a closed linear subspace of  $H$ ,  
and  $y \in H$ ,
1.  $\|Py - y\| \leq \|u - y\|$  for  $u \in M$ ,
  2.  $\|Py - y\| > \|u - y\|$  for  $u \in M, u \neq y$

satisfying

- (the **projection of  $y$  on  $M$** )  
then there is a point  $Py \in M$   
 $\langle y - Py, u \rangle = 0$  for  $u \in M$ .

## Projection Theorem

(Strictly, equivalence classes of a.s. equal r.v.s)

with inner product  $\langle X, Y \rangle = E(XY)$ .

2.  $\mathcal{H} = \{\text{mean } 0 \text{ random variables } X : EX^2 < \infty\}$ ,
1.  $\mathbb{R}^n$ , with Euclidean inner product,  $\langle x, y \rangle = \sum_i x_i y_i$ .

Examples:

complete = limits of Cauchy sequences are in the space

Norm:  $\|a\|_2 = \langle a, a \rangle$ .

- $\langle a, a \rangle = 0 \Leftrightarrow a = 0$ .

- $\langle a_1 a_1 + a_2 a_2, q \rangle = a_1 \langle a_1, q \rangle + a_2 \langle a_2, q \rangle$ ,

- $\langle a, q \rangle = \langle q, a \rangle$ .

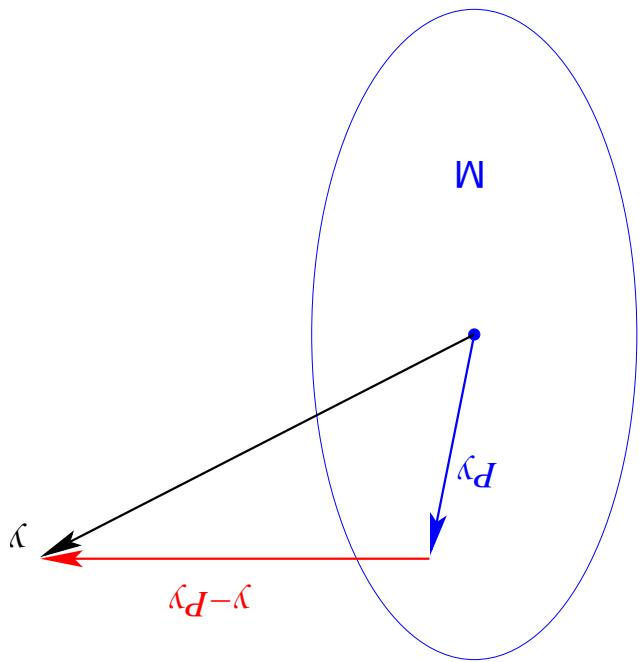
Inner product space: vector space, with inner product  $\langle a, q \rangle$ :

Hilbert space = complete inner product space:

## Hilbert spaces

Example: Linear regression  
 Given  $y = (y_1, y_2, \dots, y_n) \in \mathbb{R}^n$ , and  $Z = (z_1, \dots, z^b) \in \mathbb{R}^{n \times b}$ ,  
 choose  $\beta = (\beta_1, \dots, \beta^b) \in \mathbb{R}^b$  to minimize  $\|y - Z\beta\|_2$ .  
 Here,  $\mathcal{H} = \mathbb{R}^n$ , with  $\langle a, b \rangle = \sum_i a_i b_i$ , and  
 $M = \{Z\beta : \beta \in \mathbb{R}^b\} = \{z_1, \dots, z^b\}$ .

## Projection theorem



If  $H$  is a Hilbert space,  
 $M$  is a closed subspace of  $H$ ,  
and  $y \in H$ ,  
then there is a point  $P_M y \in M$   
(the **projection of  $y$  on  $M$** )  
satisfying  
1.  $\|P_M y - y\| \leq \|w - y\|$   
2.  $\langle y - P_M y, w \rangle = 0$   
for  $w \in M$ .

## Projection theorem

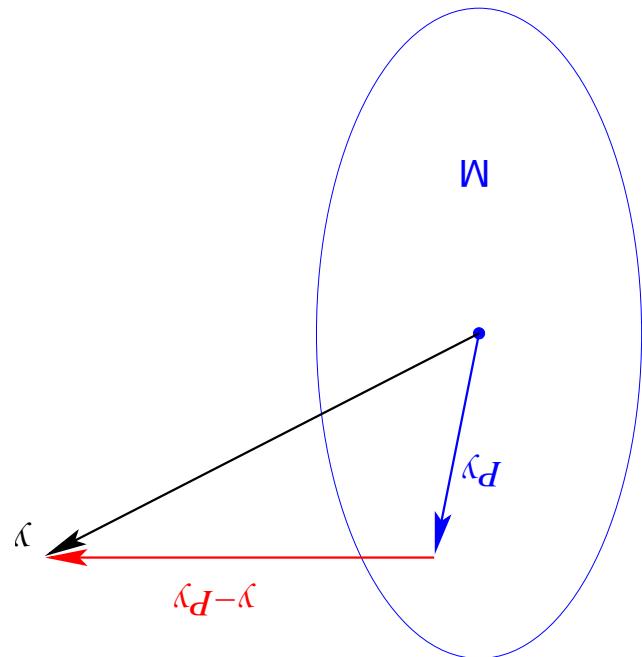
„normal equations.“

$$\hat{y}_r Z_{1-}(Z_r Z) = \hat{g} \Leftrightarrow$$

$$\hat{y}_r Z = \hat{g} Z_r Z \Leftrightarrow$$

$$\forall z^* 0 = \langle z^*, \hat{g} Z - \hat{y} \rangle \Leftrightarrow$$

$$0 = \langle m^* \hat{y}_D - \hat{y} \rangle$$



**Projection theorem**

Here,  $\langle X, Y \rangle = E(XY)$

$$M = \{a_0 + \sum_{i=1}^n a_i X^i : a_i \in \mathbb{R}\}$$

$$\text{and } \{X^1, \dots, X^n\}$$

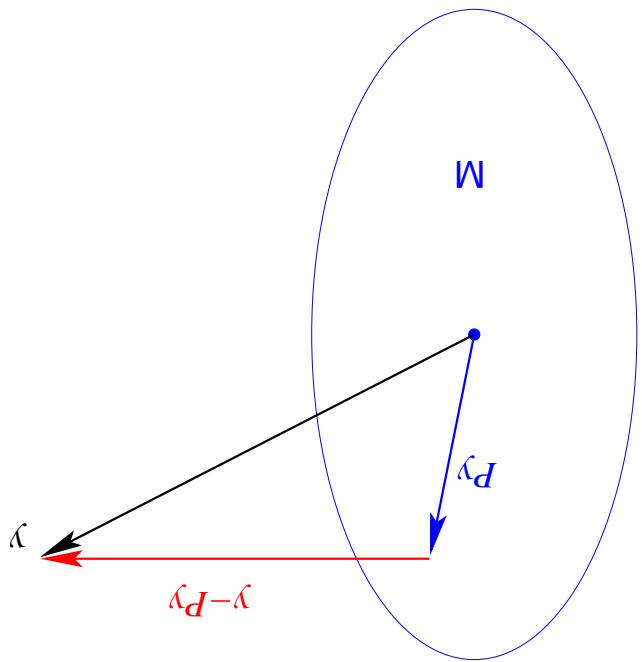
$$y = X^{u+m}.$$

so that  $Z = a_0 + \sum_{i=1}^n a_i X^i$  minimizes  $E(X^{u+m} - Z)^2$ .

Given  $1, X_1, X_2, \dots, X_n \in \{\text{mean 0 r.v.s } X : E X^2 < \infty\}$ ,

**Example: Linear prediction**

**Projection theorem**



If  $H$  is a Hilbert space,  
 $M$  is a closed subspace of  $H$ ,  
and  $y \in H$ ,  
then there is a point  $Py \in M$   
(the **projection of  $y$  on  $M$** )  
satisfying  
1.  $\|Py - y\| \leq \|w - y\|$   
2.  $\langle y - Py, w \rangle = 0$   
for  $w \in M$ .

## Projection theorem

That is, the prediction errors ( $X_u^{n+m} - X - Z$ ) are uncorrelated with the prediction variables ( $1, X_1, \dots, X_n$ ).

$$\begin{aligned} 0 &= \left[ \mathbb{E} \left( \sum_{i=1}^n (X_i - \bar{X}) (X_{u+1}^{n+m} - \bar{X}_u^{n+m}) \right) \right] = \\ &= \left( \mathbb{E} (X - \bar{X}) \mathbb{E} (X_{u+1}^{n+m} - \bar{X}_u^{n+m}) \right) \quad \Leftrightarrow \\ \{X_u^{n+m}, Z\} &= 0 \quad \text{for all } Z \in \mathcal{M} \quad \Leftrightarrow \\ \{X_u^{n+m}, Z\} &= 0 \quad \text{for all } Z \in \mathcal{M} \end{aligned}$$

The projection theorem implies the orthogonality

$$\|X_u^{n+m} - Z\|_2 \geq \|X_u^{n+m} - X\|_2 \quad \text{for all } Z \in \mathcal{M}.$$

Let  $\hat{X}_u^{n+m}$  denote the best linear predictor:

**Projection theorem: Linear prediction**

Thus, for forecasting, we can assume  $u = 0$ . So we'll ignore  $a_0$ .

$$\cdot (u - {}^i X) {}^i \alpha \sum^i = u - {}^{m+u} {}_u X \Leftrightarrow {}^i X {}^i \alpha \sum^i + 0 \alpha = {}^{m+u} {}_u X \text{ so}$$

$$\cdot 0 \alpha = \left( {}^i \alpha \sum^i - 1 \right) u \Leftrightarrow$$

$$0 = \left( {}^{m+u} X - {}^i X {}^i \alpha \sum^i + 0 \right) E \Leftrightarrow$$

$$0 = \left( {}^{m+u} {}_u X - {}^{m+u} X \right) E$$

Error  $({}^{u+m} X_u - {}^{u+m} X)$  is uncorrelated with the prediction variable  $L$ :

**Linear prediction**

$$\begin{aligned}
 {}^u\psi &= {}^u\phi {}^uT && \Leftrightarrow \\
 ({}^i\psi) &= ({}^j - {}^i)\psi {}^j\phi \sum_u {}^{j=1} && \Leftrightarrow \\
 ({}^iX^1 + {}^uX)E &= ({}^iX^{j-1+u}X)E {}^j\phi \sum_u {}^{j=1} && \Leftrightarrow \\
 u &= ({}^iX^{u+1}X - {}^iX^u)E, \text{ for } i = 1, \dots, n && \text{Prediction equations:}
 \end{aligned}$$

Write

$$X^u = \phi^u X^1 + \phi^{u-1} X^2 + \dots + \phi^1 X^u$$

**One-step-ahead linear prediction**

$$\cdot \cdot \cdot ((u)\gamma, \cdot \cdot \cdot, (\gamma(1), \gamma(2), \cdot \cdot \cdot, \gamma(n), u\phi) = u\phi$$

$$\cdot \cdot \cdot \begin{bmatrix} (0)\gamma & \cdots & (n-2)\gamma & (n-1)\gamma \\ \vdots & \ddots & & \vdots \\ (n-2)\gamma & \gamma(0) & \gamma(1) & \gamma(0) \\ (n-1)\gamma & \gamma(1) & \cdots & \gamma(n) \end{bmatrix} = u\Gamma$$

Prediction equations:  $\Gamma^u \phi^u = \gamma^u$

**One-step-ahead linear prediction**

where  $X = X^u \cdot \dots \cdot X^{u-1} \cdot X^1$

$$\mathbb{E}^u - \mathbb{E}^u(0) =$$

$$(\mathbb{E}^u X X^u \phi) - \mathbb{E}^u(0) =$$

$$(\mathbb{E}^u X^u - \mathbb{E}^u X) \mathbb{E}^u =$$

$$((\mathbb{E}^u X^u - \mathbb{E}^u X) (\mathbb{E}^u X^u - \mathbb{E}^u X)) =$$

$$\mathbb{E}^u P^u = \mathbb{E}^u X^u - \mathbb{E}^u X$$

**Mean squared error of one-step-ahead linear prediction**

where  $X = X^u, X^{u-1}, \dots, X^1$ .

$$\begin{aligned} &= E(X^{u+1} - 0)^2 - \text{Cov}(X^{u+1}, X) \text{Cov}(X, X^{u+1}) \\ &= \text{Var}(X^{u+1}) - \text{Cov}(X^{u+1}, X) \text{Cov}(X, X^{u+1}) \\ &\quad - \text{Cov}(X^{u+1}, X) \text{Cov}(X, X^{u+1}) \\ &= \gamma(0) - \gamma_u \Gamma_{u-1} \gamma_u \\ P^{u+1} &= E(X^{u+1} - X^u)^2 \end{aligned}$$

Variance is reduced:

**Mean squared error of one-step-ahead linear prediction**

$$\cdot = \left( \begin{matrix} X_1 \\ \vdots \\ X_n \end{matrix} \right) - \left( \begin{matrix} X_1^{1-m} \\ \vdots \\ X_n^{1-m} \end{matrix} \right) \quad \Leftrightarrow \quad \langle Z - \left( \begin{matrix} X_1 \\ \vdots \\ X_n \end{matrix} \right), \left( \begin{matrix} X_1^{1-m} \\ \vdots \\ X_n^{1-m} \end{matrix} \right) \rangle = 0 \quad \text{for all } Z \in M$$

The prediction equations are

Given  $X_1, \dots, X_n$ , we wish to predict  $X^{1-m}$  for  $m < 0$ . That is, we choose  $Z \in M = \text{sp}\{X_1, \dots, X_n\}$  to minimize  $\|Z - X^{1-m}\|_2^2$ .

**Backcasting: Predicting  $m$  steps in the past**

$$\begin{aligned}
 & \cdot u \circ = {}^u \phi {}^u J \quad \Leftrightarrow \\
 & (\iota) \circ = (\iota - \ell) \circ \cdot {}^\ell u \phi \sum_u^{\iota = \ell} \quad \Leftrightarrow \\
 & 0 = \left( {}^\iota X \left( {}^0 X - {}^\ell X \cdot {}^\ell u \phi \sum_u^{\iota = \ell} \right) \right) E \quad \Leftrightarrow \\
 & u \cdot \cdots \cdot 1 = \iota \quad \text{for } \iota = 0 = \left( {}^\iota X \left( {}^0 X - {}^0 u X \right) \right) E
 \end{aligned}$$

The prediction equations are

where the predictor vector is reversed: now  $X = (X_1, \dots, X_n)$

$${}^u X^u \phi = {}^u X^{un} \phi + \cdots + {}^u X^{n2} \phi + {}^u X^1 \phi = \phi$$

Write the least squares prediction of  $X_0$  given  $X_1, \dots, X_n$  as

# One-step backcasting

predictor vector reversed:  $X = (X^1, \dots, X^n)'$  versus  $X = (X^n, \dots, X^1)'$ , which is exactly the same as for forecasting, but with the indices of the

$$\mathbf{L}^n \phi^n = \mathbf{y}^n,$$

The prediction equations are

## One-step backcasting

$$\begin{aligned}
 & \cdot \phi_{11} = \phi_1. && \Leftrightarrow \\
 & (\phi_1 \gamma(0) = \gamma(0) \phi_{11}) && \text{Prediction equation:} \\
 & = \text{Cov}(X^0, X^1) && \\
 & (\gamma(0) \phi_{11} = \gamma(1)) && \\
 & X^2_1 = \phi_{11} X^2_1 && \text{Linear prediction of } X^2: \\
 & {}^t W + \phi^1 X^{t-1} + {}^t X && \text{AR(1) model:}
 \end{aligned}$$

**Example: Forecasting AR(1)**

$$\begin{aligned}
 & \phi_{11} = \phi_1 \cdot && \Leftrightarrow \\
 & (\phi_1 \gamma(0) = \gamma(0) \phi_{11}) && \text{Prediction equation:} \\
 & = \text{Cov}(X^0, X^1) && \text{Linear prediction of } X^0: \\
 & & & \gamma(0) \phi_{11} = \gamma(1) \\
 & \phi_1 X^0 = \phi_{11} X^1 && \text{AR(1) model:} \\
 & {}^t W + {}^t X \phi = {}^t X
 \end{aligned}$$

**Example: Backcasting AR(1)**

For random variables  $Y, Z_1, \dots, Z_n$ , define the best linear prediction of  $Y$  given  $Z = (Z_1, \dots, Z_n)$  as the operator  $P(\cdot | Z)$  applied to  $Y$ :

$$(Z \eta - Z)_{\perp} \phi + \eta_Y = (Z | Y) P(Y | Z)$$

with  $\eta = \text{Cov}(Y, Z)$

where  $\Gamma = \text{Cov}(Z, Z)$ .

## The prediction operator

1.  $E(Y - P(Y|Z)) = 0$ .
2.  $E((Y - P(Y|Z))^2) = \text{Var}(Y|Z)$ .
3.  $P(\alpha_1 Y_1 + \alpha_2 Y_2 + \dots + \alpha_n Y_n | Z) = P(Y_1 | Z) \dots P(Y_n | Z)$ .
4.  $P(Z|Y) = (Z|Y)^*$ .
5.  $P(Y|Z) = EY$  if  $\gamma = 0$ .

### Properties of the prediction operator

$$\begin{aligned} \text{With } & X_{(m)}^u \phi + \cdots + {}^1 X_{(m)}^u \phi + {}^u X_{(m)}^1 \phi = {}^{m+u} u X \\ \text{with } & \Gamma^u = \Gamma^u(\mu) = (\Gamma^u(\mu), \Gamma^u(\mu+1), \dots, \Gamma^u(m+u)) \\ \text{Also, } & \mathbb{E}({}^{m+u} u X) - (\Gamma^u(\mu+1) - \Gamma^u(\mu)) \phi = \Gamma^u(\mu+1) \end{aligned}$$

**Example: predicting  $m$  steps ahead**