

Introduction to Time Series Analysis. Lecture 5.

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1. Causality
2. Invertibility
3. AR(p) models

$$\begin{aligned} |\phi| < 1 \\ \phi = -1 \\ \phi = 1 \end{aligned}$$

$$X_t = \sum_{j=0}^{\infty} \phi^j W_{t-j}$$

If $|\phi| > 1$,

where $W_t \sim WN(0, \sigma^2)$.

$$X_t - \phi X_{t-1} = W_t,$$

Let X_t be the stationary solution to

AR(1) and Causality

AR(1) and Causality

If $|\phi| > 1$, $\pi(B)W_t$ does not converge.

But we can rearrange

$$X_t = \phi X_{t-1} + W_t$$

as

$$X_{t-1} = \frac{\phi}{1} X_t - \frac{\phi}{1} W_t,$$

and we can check that the unique stationary solution is

$$X_t = - \sum_{j=1}^{\infty} \phi^{-j} W_{t+j}.$$

But... X_t depends on **future** values of W_t .

Causality

A linear process $\{X_t\}$ is **causal** (strictly, a causal function of $\{W_t\}$) if there is a

$$\psi(B) = \psi_0 + \psi_1 B + \psi_2 B^2 + \dots$$

with $\sum_{j=0}^{\infty} |\psi_j| < \infty$

and $X_t = \psi(B)W_t$.

AR(1) and Causality

- Causality is a property of $\{X_t\}$ **and** $\{W_t\}$.
- The AR(1) process defined by $\phi(B)X_t = W_t$ (with $\phi(B) = 1 - \phi B$) is causal iff $|\phi| < 1$, iff the root z_1 of the polynomial $\phi(z) = 1 - \phi z$ satisfies $|z_1| > 1$.
- If $|\phi| > 1$, we can define an equivalent causal model, $X_t - \phi^{-1}X_{t-1} = \tilde{W}_t$, where \tilde{W}_t is a new white noise sequence.
- Is an MA(1) process causal?

MA(1) and Invertibility

Define

$$X_t = W_t + \theta W_{t-1}$$

$$= (1 + \theta B)W_t.$$

If $|\theta| < 1$, we can write

$$(1 + \theta B)^{-1} X_t = W_t$$

$$\Leftrightarrow (1 - \theta B + \theta^2 B^2 - \theta^3 B^3 + \dots) X_t = W_t$$

$$\Leftrightarrow \sum_{j=0}^{\infty} (-\theta)^j X_{t-j} = W_t.$$

That is, we can write W_t as a *causal* function of X_t .

We say that this MA(1) is *invertible*.

MA(1) and Invertibility

$$X_t = W_t + \theta W_{t-1}$$

If $|\theta| > 1$, the sum $\sum_{j=0}^{\infty} (-\theta)^j X_{t-j}$ diverges, but we can write

$$W_{t-1} = -\theta^{-1} W_t + \theta^{-1} X_t.$$

Just like the noncausal AR(1), we can show that

$$W_t = - \sum_{j=1}^{\infty} (-\theta)^{-j} X_{t+j}.$$

That is, we can write W_t as a linear function of X_t , but it is not causal. We say that this MA(1) is not invertible.

A linear process $\{X_t\}$ is **invertible** (strictly, an **invertible function of** $\{W_t\}$) if there is a

$$\pi(B) = \pi_0 + \pi_1 B + \pi_2 B^2 + \dots$$

with $\sum_{j=0}^{\infty} |\pi_j| < \infty$

and $W_t = \pi(B)X_t$.

Invertibility

MA(1) and Invertibility

- Invertibility is a property of $\{X_t\}$ and $\{W_t\}$.
- The MA(1) process defined by $X_t = \theta(B)W_t$ (with $\theta(B) = 1 + \theta B$) is invertible iff $|\theta| > 1$ iff the root z_1 of the polynomial $\theta(z) = 1 + \theta z$ satisfies $|z_1| > 1$.
- If $|\theta| > 1$, we can define an equivalent invertible model in terms of a new white noise sequence.
- Is an AR(1) process invertible?

AR(p): Autoregressive models of order p

An AR(p) process $\{X_t\}$ is a stationary process that satisfies

$$X_t - \phi_1 X_{t-1} - \dots - \phi_p X_{t-p} = W_t,$$

where $\{W_t\} \sim WN(0, \sigma^2)$.

Equivalently, $\phi(B)X_t = W_t,$

where $\phi(B) = 1 - \phi_1 B - \dots - \phi_p B^p.$

AR(p): Constraints on ϕ

Recall: For $p = 1$ (AR(1)), $\phi(B) = 1 - \phi_1 B$.

This is an AR(1) model only if there is a *stationary* solution to $\phi(B)X_t = W_t$, which is equivalent to $|\phi_1| \neq 1$.

This is equivalent to the following condition on $\phi(z) = 1 - \phi_1 z$:

$$\forall z \in \mathbb{R}, \phi(z) = 0 \Leftrightarrow z \neq \pm 1$$

$$\text{equivalently, } \forall z \in \mathbb{C}, \phi(z) = 0 \Leftrightarrow |z| \neq 1,$$

where \mathbb{C} is the set of complex numbers.

AR(p): Constraints on ϕ

Stationarity: $\forall z \in \mathbb{C}, \phi(z) = 0 \Rightarrow |z| \neq 1,$

where \mathbb{C} is the set of complex numbers.

$\phi(z) = 1 - \phi_1 z$ has one root at $z_1 = 1/\phi_1 \in \mathbb{R}.$

But the roots of a degree $p > 1$ polynomial might be complex.

For stationarity, we want the roots of $\phi(z)$ to avoid the **unit circle**,
 $\{z \in \mathbb{C} : |z| = 1\}.$

AR(p): Stationarity and causality

Theorem: A (unique) stationary solution to $\phi(B)X_t = W_t$ exists iff

$$|z| = 1 \Leftrightarrow \phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p \neq 0.$$

This AR(p) process is *causal* iff

$$|z| \leq 1 \Leftrightarrow \phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p \neq 0.$$

Recall: Causality

A linear process $\{X_t\}$ is **causal** (strictly), a causal function of $\{W_t\}$ if there is a

$$\psi(B) = \psi_0 + \psi_1 B + \psi_2 B^2 + \dots$$

with $\sum_{j=0}^{\infty} |\psi_j| < \infty$

and $X_t = \psi(B)W_t$.

So if $|z| \leq 1 \Rightarrow \phi(z) = 0$, then $S^m = \sum_{j=0}^m \psi_j B^j W_t$ converges in mean square, so we have a stationary, causal time series $X_t = \phi^{-1}(B)W_t$.

$$\Leftrightarrow \exists \delta_0, \forall \delta > \delta_0, \exists \epsilon > 0, \sum_{j=0}^{\infty} |\psi_j| < \infty \Leftrightarrow \frac{1}{1 + \delta/2} \leq \sum_{j=0}^{\infty} |\psi_j| < \infty$$

$$\Leftrightarrow \forall \delta > 0, \exists \epsilon > 0, \sum_{j=0}^{\infty} |\psi_j| < \epsilon \Leftrightarrow \sum_{j=0}^{\infty} |\psi_j| < \epsilon$$

$$\Leftrightarrow \exists \delta > 0, \forall \epsilon > 0, \sum_{j=0}^{\infty} |\psi_j| < \epsilon \Leftrightarrow \sum_{j=0}^{\infty} |\psi_j| < \epsilon$$

$$\forall z \in \mathbb{C}, |z| \leq 1 \Rightarrow \phi(z) \neq 0$$

AR(p): All roots outside the unit circle implies causal

Calculating ψ for an AR(p): matching coefficients

Example: $X_t = \psi(B)W_t \Leftrightarrow (1 - 0.5B + 0.6B^2)X_t = W_t,$

so

$$1 = \psi(B)(1 - 0.5B + 0.6B^2)$$

\Leftrightarrow

$$1 = (\psi_0 + \psi_1 B + \psi_2 B^2 + \dots)(1 - 0.5B + 0.6B^2)$$

\Leftrightarrow

$$1 = \psi_0,$$

$$0 = \psi_1 - 0.5\psi_0,$$

$$0 = \psi_2 - 0.5\psi_1 + 0.6\psi_0,$$

$$0 = \psi_3 - 0.5\psi_2 + 0.6\psi_1,$$

\vdots

Calculating ψ for an AR(p): example

$$\begin{aligned} \Leftrightarrow \quad 1 = \psi_0, \quad 0 = \psi_j \quad (j \leq 0), \\ 0 = \psi_j - 0.5\psi_{j-1} + 0.6\psi_{j-2} \\ \Leftrightarrow \quad 1 = \psi_0, \quad 0 = \psi_j \quad (j \leq 0), \end{aligned}$$

We can solve these *linear difference equations* in several ways:

- numerically, or
- by guessing the form of a solution and using an inductive proof, or
- by using the theory of linear difference equations.

Calculating ψ for an AR(p): general case

$$\phi(B)X_t = W_t, \quad \Leftrightarrow \quad X_t = \psi(B)W_t$$

$$\text{so } 1 = \psi(B)\phi(B)$$

$$\Leftrightarrow 1 = (\psi_0 + \psi_1 B + \dots)(1 - \phi_1 B - \dots - \phi_p B^p)$$

$$\Leftrightarrow 1 = \psi_0,$$

$$0 = \psi_1 - \phi_1 \psi_0,$$

$$0 = \psi_2 - \phi_1 \psi_1 - \phi_2 \psi_0,$$

$$\vdots$$

$$\Leftrightarrow 1 = \psi_0, \quad 0 = \psi_j \quad (j > 0),$$

$$0 = \phi(B)\psi_j.$$