Introduction to Time Series Analysis. Lecture 1. Peter Bartlett

- 1. Organizational issues.
- 2. Objectives of time series analysis. Examples.
- 3. Overview of the course.
- 4. Time series models.
- 5. Time series modelling: Chasing stationarity.

Organizational Issues

- Peter Bartlett. bartlett@stat. Office hours: Thu 1:30-2:30 (Evans 399). Fri 3-4 (Soda 527).
- Brad Luen. bradluen@stat. Office hours: Tue/Wed 2-3pm (Room TBA).
- http://www.stat.berkeley.edu/~bartlett/courses/153-fall2005/ Check it for announcements, assignments, slides, ...
- Text: Time Series Analysis and its Applications, Shumway and Stoffer.

Organizational Issues

Computer Labs:

Wed 12–1 and Wed 2–3, in 342 Evans.

You need to choose one of these times. Please email bradluen@stat with your preference. First computer lab sections are on September 7.

Classroom Lab Section:

Fri 12–1, in 330 Evans. First classroom lab

section is on September 2.

Assessment:

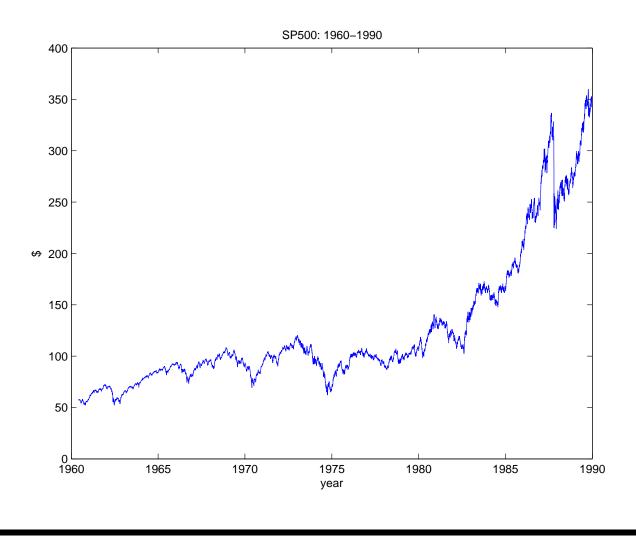
Lab/Homework Assignments (40%): posted on the website.

These involve a mix of pen-and-paper and computer exercises. You may use any programming language you choose (R, Splus, Matlab). The last assignment will involve analysis of a data set that you choose.

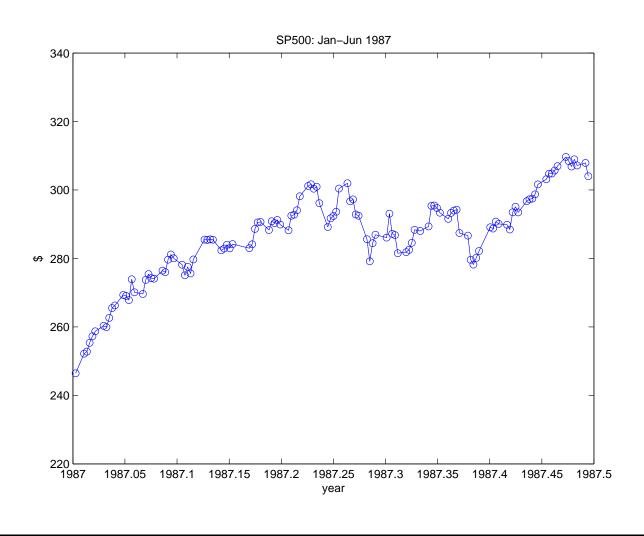
Midterm Exam (25%): scheduled for October 20, at the lecture.

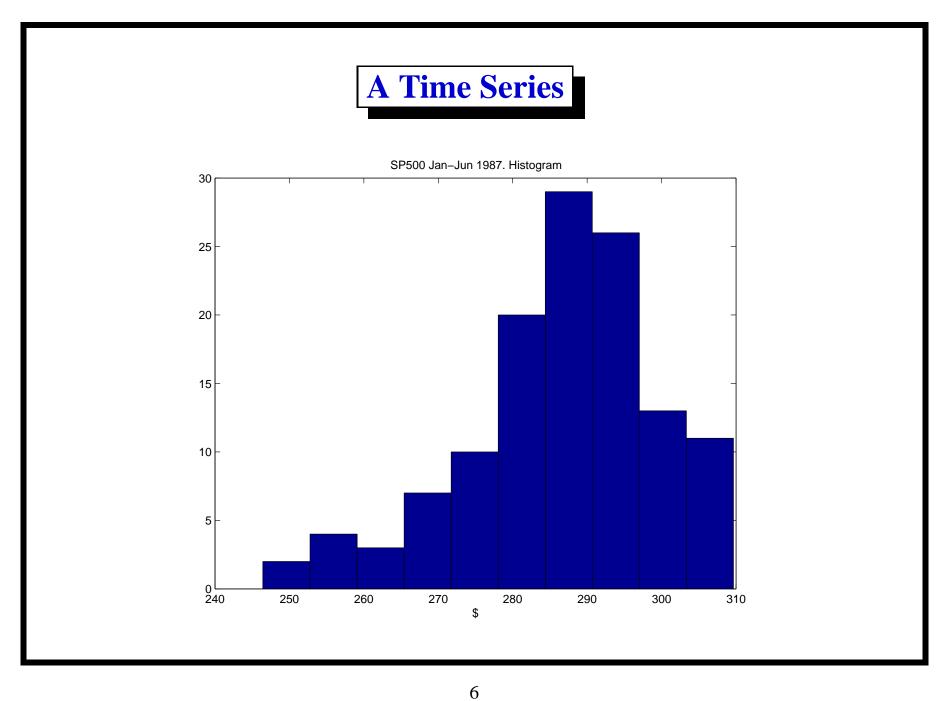
Final Exam (35%): scheduled for Thursday, December 15.

A Time Series

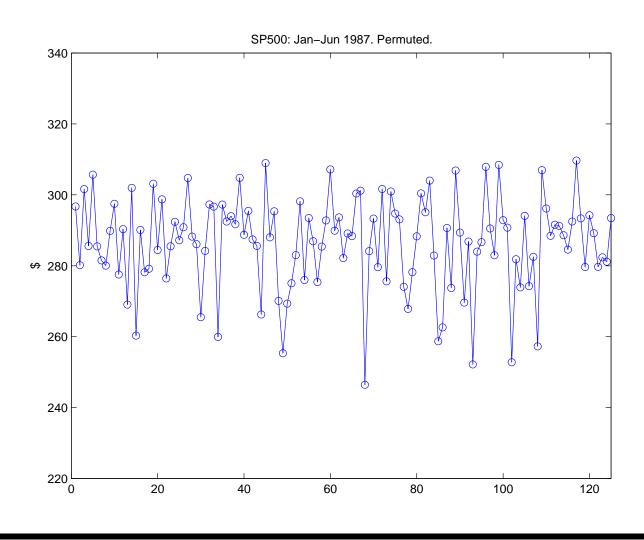


A Time Series





A Time Series



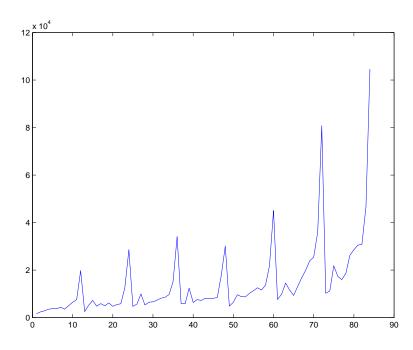
Objectives of Time Series Analysis

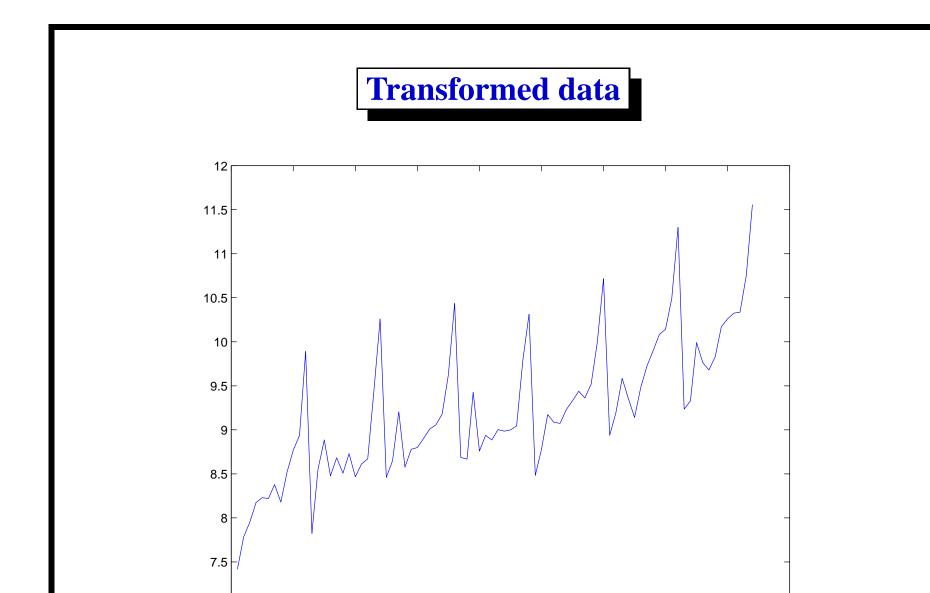
- 1. Compact description of data.
- 2. Interpretation.
- 3. Forecasting.
- 4. Control.
- 5. Hypothesis testing.
- 6. Simulation.

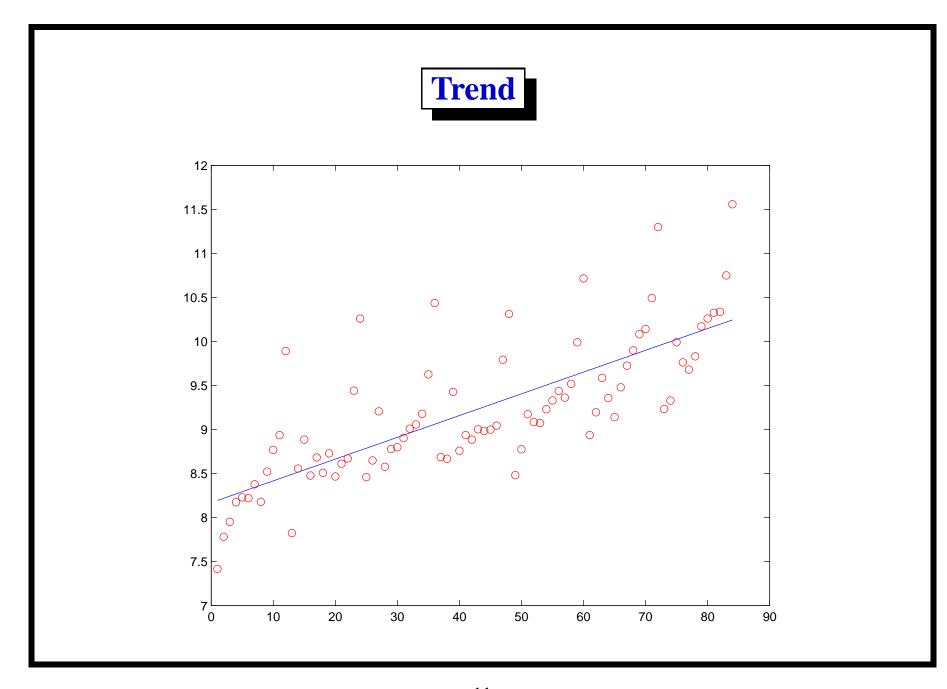
Classical decomposition: An example

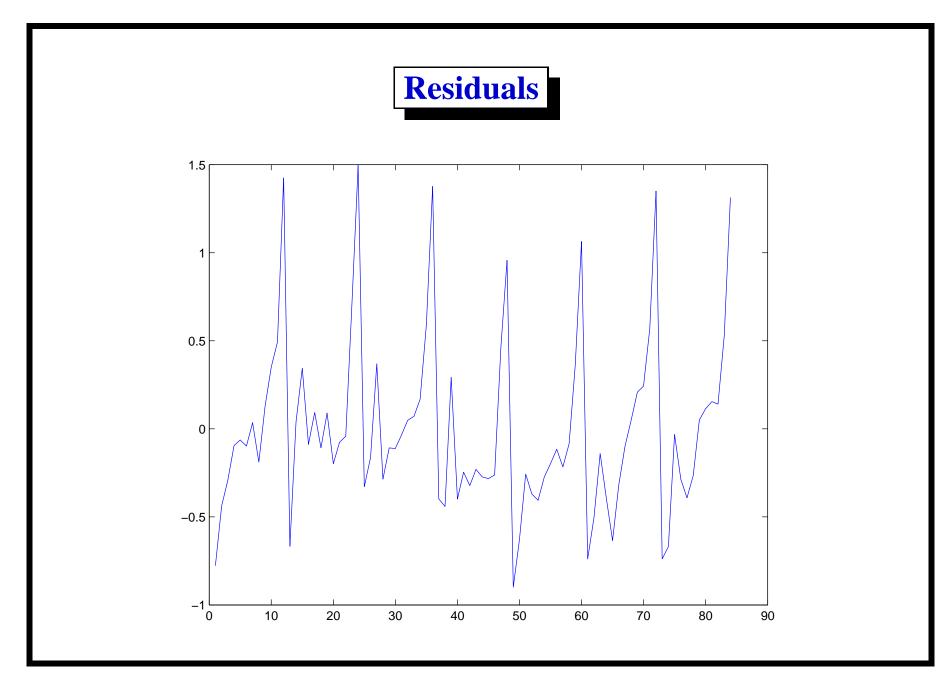
Monthly sales for a souvenir shop at a beach resort town in Queensland.

(Makridakis, Wheelwright and Hyndman, 1998)

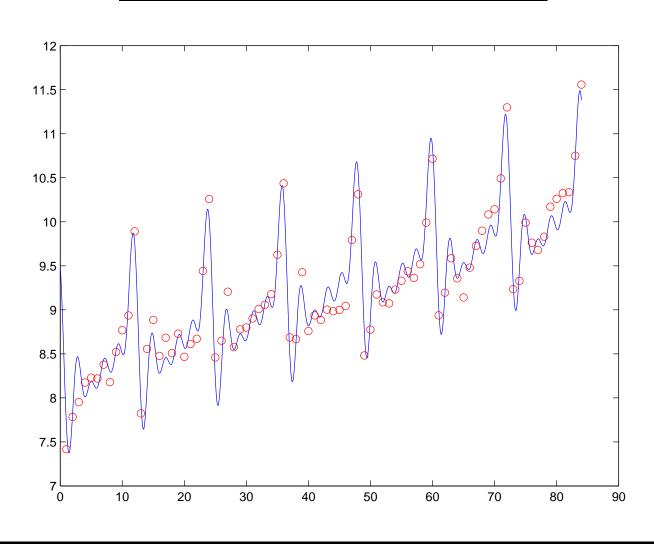












Objectives of Time Series Analysis

1. Compact description of data.

Example: Classical decomposition:

$$X_t = T_t + S_t + Y_t.$$

2. Interpretation.

3. Forecasting.

4. Control.

5. Hypothesis testing.

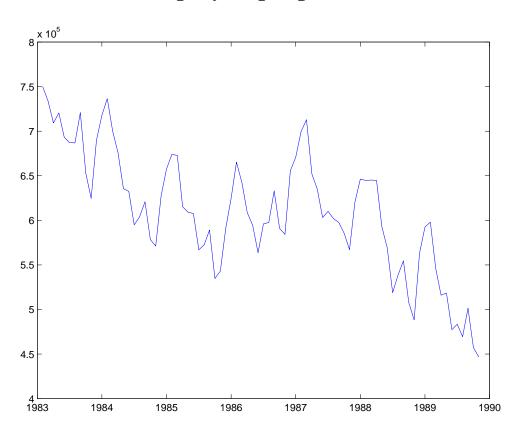
6. Simulation.

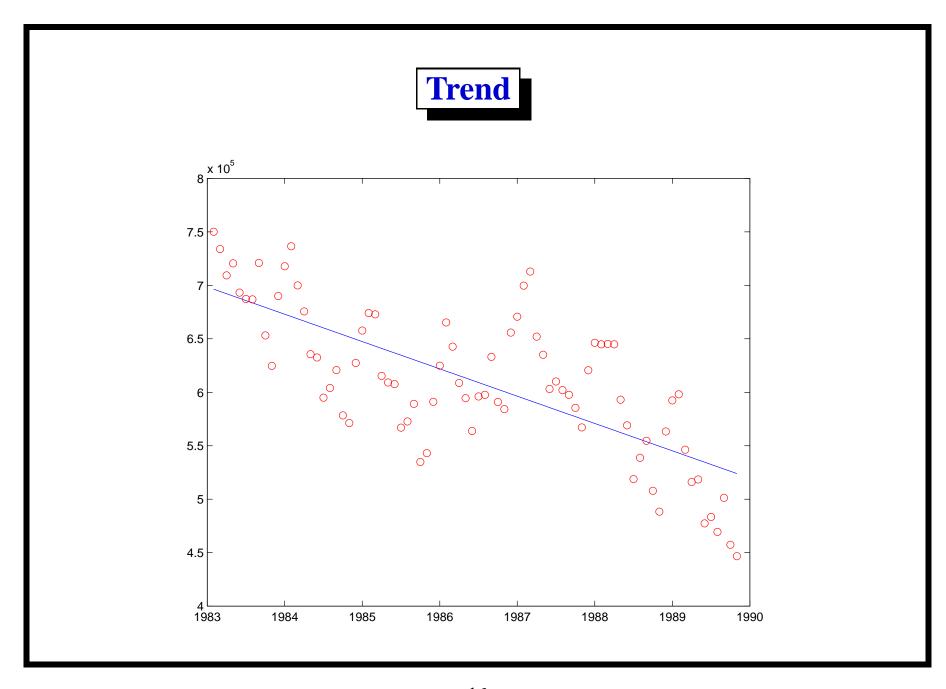
Example: Predict sales.

Example: Seasonal adjustment.

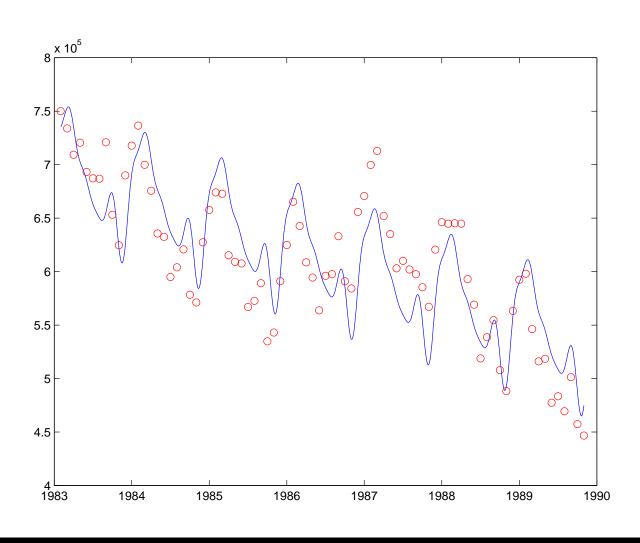
Unemployment data

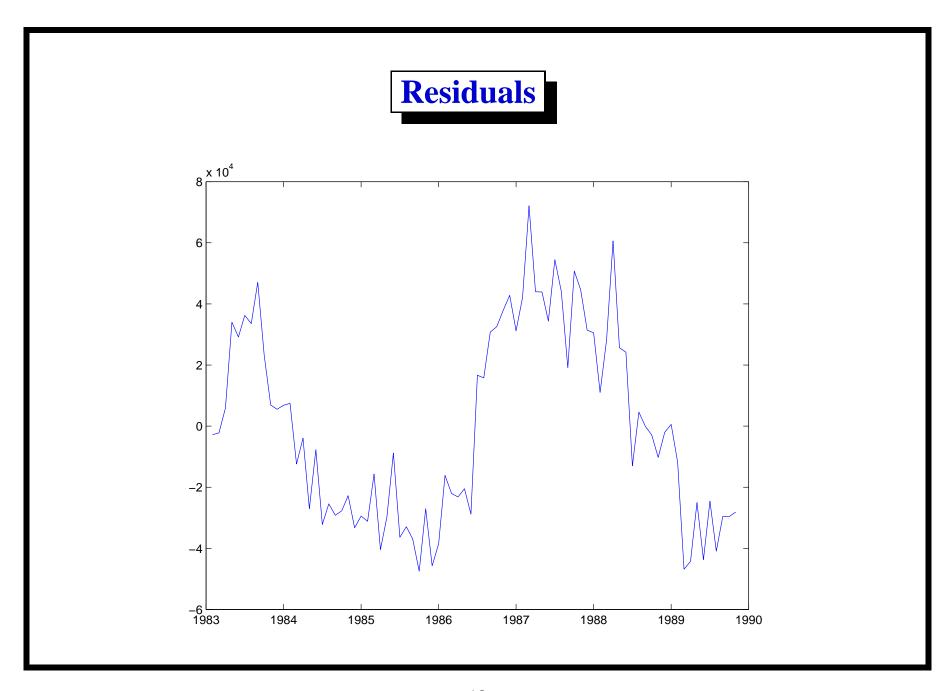
Monthly number of unemployed people in Australia. (Hipel and McLeod, 1994)



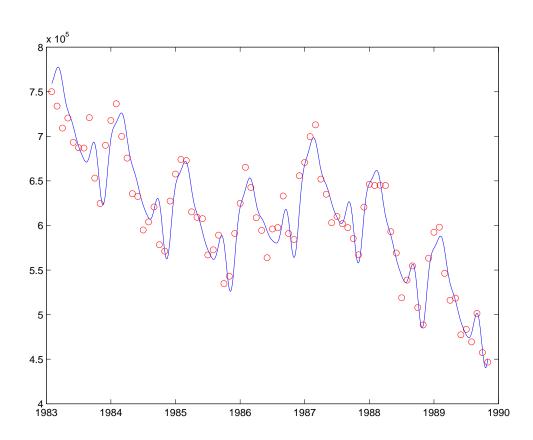








Predictions based on a (simulated) variable



Objectives of Time Series Analysis

1. Compact description of data:

$$X_t = T_t + S_t + f(Y_t) + W_t.$$

2. Interpretation. Example: Seasonal adjustment.

3. Forecasting. Example: Predict unemployment.

4. Control. Example: Impact of monetary policy on unemployment.

5. Hypothesis testing. Example: Global warming.

6. Simulation. Example: Estimate probability of catastrophic events.

- 1. Time series models
 - (a) Stationarity.
 - (b) Autocorrelation function.
 - (c) Transforming to stationarity.
- 2. Time domain methods
- 3. Spectral analysis
- 4. State space models(?)

- 1. Time series models
- 2. Time domain methods
 - (a) AR/MA/ARMA models.
 - (b) ACF and partial autocorrelation function.
 - (c) Forecasting
 - (d) Parameter estimation
 - (e) ARIMA models/seasonal ARIMA models
- 3. Spectral analysis
- 4. State space models(?)

- 1. Time series models
- 2. Time domain methods
- 3. Spectral analysis
 - (a) Spectral density
 - (b) Periodogram
 - (c) Spectral estimation
- 4. State space models(?)

- 1. Time series models
- 2. Time domain methods
- 3. Spectral analysis
- 4. State space models(?)
 - (a) ARMAX models.
 - (b) Forecasting, Kalman filter.
 - (c) Parameter estimation.

Time Series Models

A **time series model** specifies the joint distribution of the sequence $\{X_t\}$ of random variables.

For example:

$$P[X_1 \leq x_1, \dots, X_t \leq x_t]$$
 for all t and x_1, \dots, x_t .

Notation:

 X_1, X_2, \dots is a stochastic process.

 x_1, x_2, \dots is a single realization.

We'll mostly restrict our attention to **second-order properties** only:

 $EX_t, E(X_{t_1}X_{t_2}).$

Time Series Models

Example: White noise: $X_t \sim WN(0, \sigma^2)$.

i.e., $\{X_t\}$ uncorrelated, $EX_t = 0$, $Var X_t = \sigma^2$.

Example: i.i.d. noise: $\{X_t\}$ independent and identically distributed.

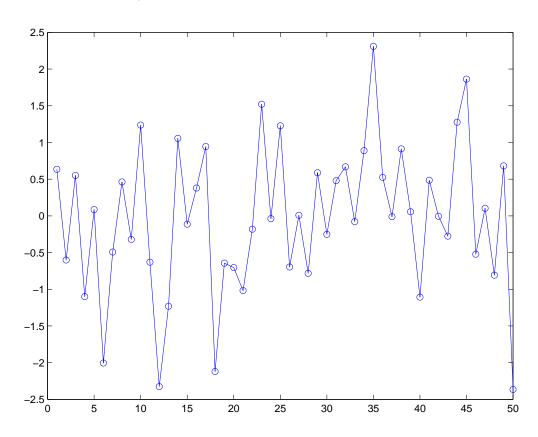
$$P[X_1 \le x_1, \dots, X_t \le x_t] = P[X_1 \le x_1] \cdots P[X_t \le x_t].$$

Not interesting for forecasting:

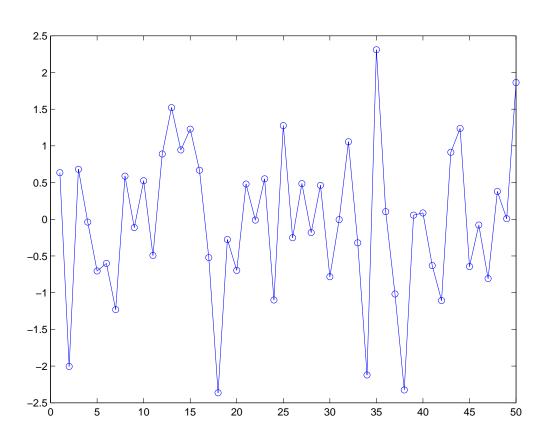
$$P[X_t \le x_t | X_1, \dots, X_{t-1}] = P[X_t \le x_t].$$

Gaussian white noise

$$P[X_t \le x_t] = \Phi(x_t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x_t} e^{-x^2/2} dx.$$



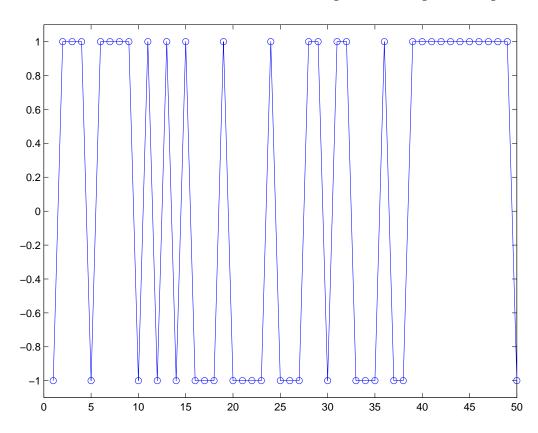
Gaussian white noise



Time Series Models

Example: Binary i.i.d.

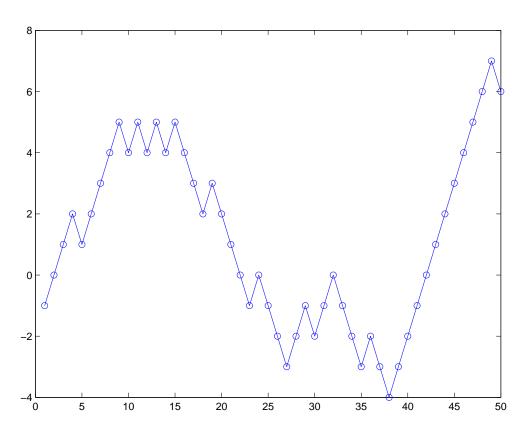
$$P[X_t = 1] = P[X_t = -1] = 1/2.$$



Random walk

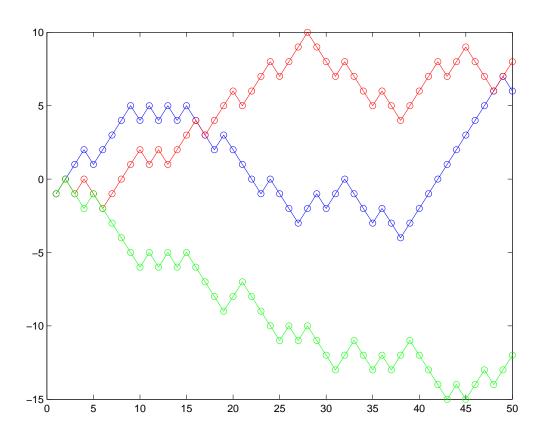
$$S_t = \sum_{i=1}^t X_i.$$

Differences: $\nabla S_t = S_t - S_{t-1} = X_t$.



Random walk

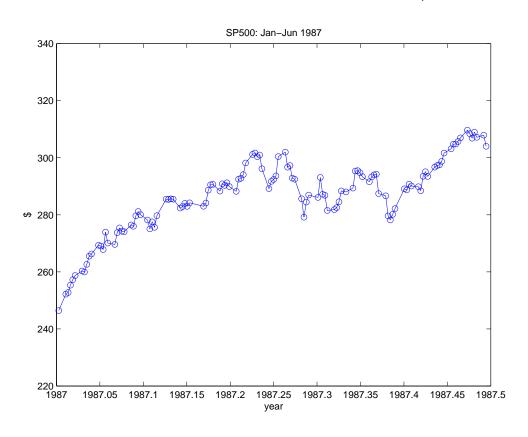
 ES_t ? $VarS_t$?



Random Walk

Recall S&P500 data.

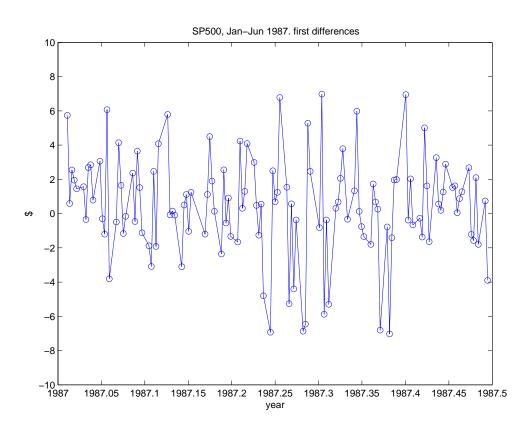
(Notice that it's smooth)



Random Walk

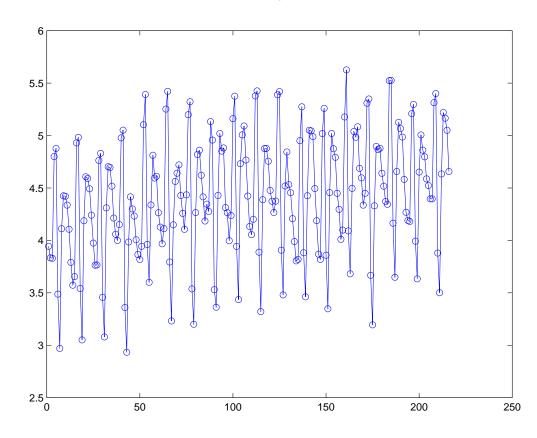
Differences:

$$\nabla S_t = S_t - S_{t-1} = X_t.$$



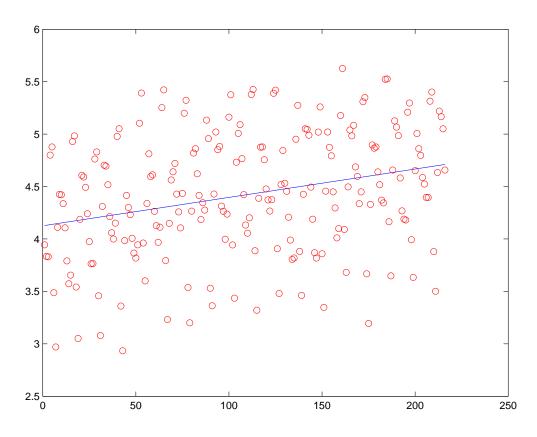
Trend and Seasonal Models

$$X_t = T_t + S_t + E_t = \beta_0 + \beta_1 t + \sum_i (\beta_i \cos(\lambda_i t) + \gamma_i \sin(\lambda_i t)) + E_t$$



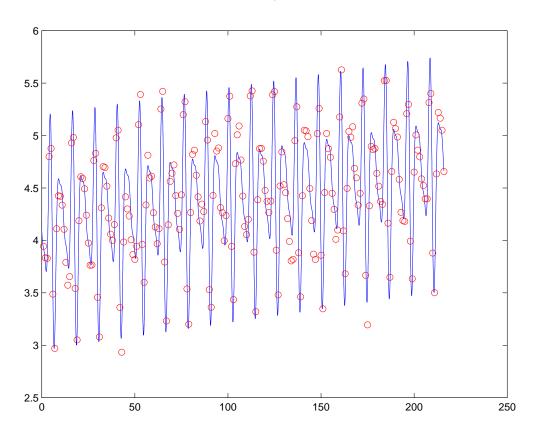
Trend and Seasonal Models

$$X_t = T_t + E_t = \beta_0 + \beta_1 t + E_t$$

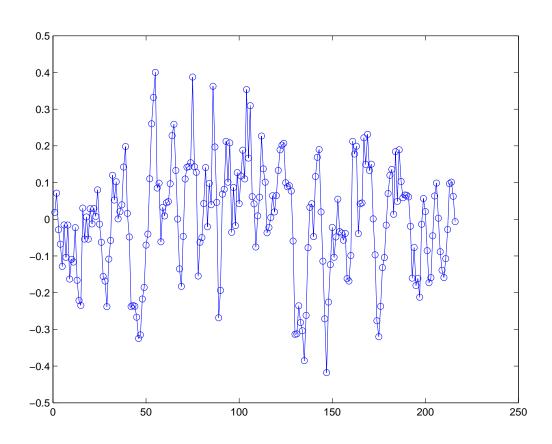


Trend and Seasonal Models

$$X_t = T_t + S_t + E_t = \beta_0 + \beta_1 t + \sum_i (\beta_i \cos(\lambda_i t) + \gamma_i \sin(\lambda_i t)) + E_t$$



Trend and Seasonal Models: Residuals



Time Series Modelling

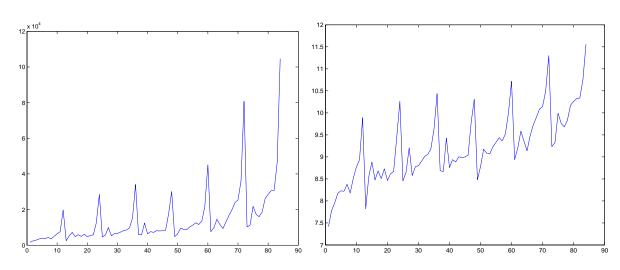
1. Plot the time series.

Look for trends, seasonal components, step changes, outliers.

- 2. Transform data so that residuals are **stationary**.
 - (a) Estimate and subtract T_t, S_t .
 - (b) Differencing.
 - (c) Nonlinear transformations (log, $\sqrt{\cdot}$).
- 3. Fit model to residuals.

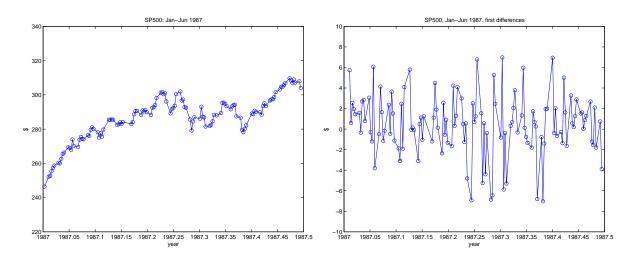
Nonlinear transformations

Recall: Monthly sales. (Makridakis, Wheelwright and Hyndman, 1998)



Differencing

Recall: S&P 500 data.



Differencing and Trend

Define the lag-1 difference operator,

(think 'fi rst derivative')

$$\nabla X_t = X_t - X_{t-1} = (1 - B)X_t,$$

where B is the **backshift** operator, $BX_t = X_{t-1}$.

• If $X_t = \beta_0 + \beta_1 t + Y_t$, then

$$\nabla X_t = \beta_1 + \nabla Y_t.$$

• If $X_t = \sum_{i=0}^k \beta_i t^i + Y_t$, then

$$\nabla^k X_t = k! \beta_k + \nabla^k Y_t,$$

where $\nabla^k X_t = \nabla(\nabla^{k-1} X_t)$ and $\nabla^1 X_t = \nabla X_t$.

Differencing and Seasonal Variation

Define the lag-s difference operator,

$$\nabla_s X_t = X_t - X_{t-s} = (1 - B^s) X_t,$$

where B^s is the backshift operator applied s times, $B^s X_t = B(B^{s-1} X_t)$ and $B^1 X_t = B X_t$.

If $X_t = T_t + S_t + Y_t$, and S_t has period s (that is, $S_t = S_{t-s}$ for all t), then

$$\nabla_s X_t = T_t - T_{t-s} + \nabla_s Y_t.$$

Least Squares Regression

Model:
$$X_{t} = \beta_{0} + \beta_{1}t + W_{t}$$

$$= \begin{pmatrix} 1 & t \end{pmatrix} \begin{pmatrix} \beta_{0} \\ \beta_{1} \end{pmatrix} + W_{t},$$

$$\begin{pmatrix} X_{1} \\ X_{2} \\ \vdots \\ X_{T} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ \vdots & \vdots \\ 1 & T \end{pmatrix} \underbrace{\begin{pmatrix} \beta_{0} \\ \beta_{1} \\ \beta_{1} \end{pmatrix}}_{\beta} + \underbrace{\begin{pmatrix} W_{1} \\ W_{2} \\ \vdots \\ W_{T} \end{pmatrix}}_{w}$$

Least Squares Regression

$$x = Z\beta + w$$
.

Least squares: choose β to minimize $||w||^2 = ||x - Z\beta||^2$.

Solution $\hat{\beta}$ satisfies the *normal equations*:

$$\nabla_{\beta} ||w||^2 = 2Z'(x - Z\hat{\beta}) = 0.$$

If Z'Z is nonsingular, the solution is unique:

$$\hat{\beta} = (Z'Z)^{-1}Z'x.$$

Least Squares Regression

Properties of the least squares solution $(\hat{\beta} = (Z'Z)^{-1}Z'x)$:

- Linear.
- Unbiased.
- For $\{W_t\}$ i.i.d., it is the linear unbiased estimator with smallest variance.

Other regressors Z: polynomial, trigonometric functions, piecewise polynomial (splines), etc.

Outline

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