

## Optimal flows through the disordered lattice

Consider lattice  $Z^2$  with i.i.d.r.v.'s  $(C_e)$  on edges  $e$ . This structure can be used in many settings

- first passage percolation
- RWIRE
- disordered Ising model
- disordered variants of many interacting particle systems.

We'll use it for “traffic flow” models.

**Big Picture.** Instead of studying only graph structure of networks, think “what does the network do?” One answer: “move stuff from place to place”. Envisage road traffic.

Complete info about routes is the **path-flow**, a measure  $\mu$  on (directed, loop-free) paths

source =  $v_0, v_1, v_2, \dots$ , destination.

Associated with a path-flow is its induced **flow-volume**  $\mathbf{f} = (f(e))$ ,

$f(e) =$  volume of flow across edge  $e$

(both directions combined) and its induced **transportation measure** on (source, destination).

**Optimal routing problem:** Given

- network
- transportation measure
- cost function depending on  $(f(e))$
- capacity constraints  $(\text{cap}(e))$

we ask

does there exist a feasible path-flow?

if so, what is minimum-cost feasible flow?

Deterministic algorithmic problems like this are studied as part of **network algorithms**; as multicommodity flow problems they are NP-hard in general. We take **statistical physics viewpoint** of modeling the network (topology, costs, constraints) as random and studying properties of optimal solution. We take transportation measure uniform on all (source,destination) pairs, so there's one parameter

$\rho =$  normalized traffic demand.

Seek to study (in different models on  $n$ -vertex networks) the  $n \rightarrow \infty$  limit curves giving some quantitative measure of network performance vs  $\rho$ .

In many random-graph like networks we hope to exploit the “locally tree-like” structure to do explicit calculations. But what about disordered  $Z^2$ ?

**Order-of-magnitude calculation** on  $N \times N$  grid. Send volume  $\rho_N$  between each (source, destination) pair. Then average flow volume  $\bar{f}$  across edges has

$$(N^2 \times N^2) \times \rho_N \times N \approx \bar{f} \times N^2$$

We take

$$\rho_N = \rho N^{-3}$$

so that flow-volumes  $f(e)$  will be order 1.

**Open Problem.** Take i.i.d. capacities ( $\text{cap}(e)$ ) with  $0 < c_- \leq \text{cap}(e) \leq c_+ < \infty$ . Then a feasible flow with normalized demand  $\rho$  exists for  $\rho < \rho_-$  and doesn't exist for  $\rho > \rho_+$ . Prove there is a constant  $\rho_*$  depending on distribution of  $\text{cap}(e)$  such that as  $N \rightarrow \infty$

$$P(\exists \text{ feasible flow, norm. demand } \rho) \begin{array}{l} \rightarrow 1 \quad , \quad \rho < \rho_* \\ \rightarrow 0 \quad , \quad \rho > \rho_* \end{array}$$

Instead of focussing on capacities, let's focus on congestion. In a network without congestion, the cost (to system; all users combined) of a flow of volume  $f(e)$  scales linearly with  $f(e)$ . With congestion, an extra user imposes extra costs on other users as well as on themselves. So cost scales super-linearly with  $f(e)$ .

**Model:** The cost of a flow  $f = (f(e))$  in an environment  $c = (c(e))$  is

$$\text{cost}_{(N)}(f, c) = \sum_e c(e) f^2(e).$$

**Theorem 1.**  $N \times N$  torus (for simplicity)  
Large constant bound  $B$  on edge-capacity (for simplicity)  
i.i.d. cost-factors  $c(e)$  with

$$0 < c_- \leq c(e) \leq c^+ < \infty.$$

Let  $\Gamma_N$  be minimum cost of flow with normalized intensity  $\rho = 1$ . Then

$$N^{-2} E \Gamma_N \rightarrow \text{constant}(B, \text{dist}(c(e))).$$

**Note:** Easy concentration-of-measure lemma then implies

$$N^{-2} \Gamma_N \rightarrow \text{constant}(B, \text{dist}(c(e)))$$

in probability.

**Idea of proof.** Consider optimal flow in a randomly positioned  $M \times M$  window; consider  $N \rightarrow \infty$  weak limits.

**Note:** As  $N \rightarrow \infty$  the volume of flow with source or destination at a vertex  $v$  becomes negligible compared to the flow through  $v$ .

Weak limit flows across the  $M \times M$  square.

- i.i.d. environment  $(c(e))$
- a path-flow across the square
- with a transportation measure  $Q$  on the boundary  $\text{Bou}_M \times \text{Bou}_M$
- $Q$  is dependent on  $(c(e))$
- given  $(c(e))$  and  $Q$ , the path-flow inside the square minimizes the local cost

$$\text{cost}_M(\mathbf{f}, \mathbf{c}) = \sum_e c(e) f^2(e).$$

Consider  $Q$  non-random. So there's an expectation (over random environment)

$$\text{cost}_M(Q) := E \inf\{\text{cost}_M(\mathbf{f}, \mathbf{c}) : \mathbf{f} \text{ has t.m. } Q\}.$$

Note

- $Q \rightarrow \text{cost}_M(Q)$  is convex
- An easy concentration inequality (C.I.)

shows that the r.v.

$$\inf\{\text{cost}_M(\mathbf{f}, \mathbf{c}) : \mathbf{f} \text{ has t.m. } Q\}$$

is close to its expectation.

These ingredients suggest the following conceptually standard (but technically hard to implement here) argument. Take a large finite set  $\mathcal{Q}$  which is  $\delta$ -dense in space of  $Q$ 's.

$N \rightarrow \infty$  weak limit involves

$$\text{cost}_M(\mathbf{f}, \mathbf{c}) : \mathbf{f} \text{ has random t.m. } Q$$

Use  $\delta$ -dense to say

$$\approx \text{cost}_M(\mathbf{f}, \mathbf{c}) : \mathbf{f} \text{ has random t.m. } Q \in \mathcal{Q}$$

[by C.I.]  $\approx$  weighted ave of  $\text{cost}_M(Q)$  over  $Q \in \mathcal{Q}$

$$[\text{convexity}] \geq \text{cost}_M(EQ) \quad .$$

Of course we don't know  $EQ$  but we'll write some constraints soon. This argument gives a lower bound for Theorem 1

$$\liminf N^{-2} E\Gamma_N \geq -\varepsilon_M$$

$$+M^{-2} \inf\{\text{cost}_M(Q^0) : Q^0 \text{ satisfy constraints}\}.$$

What are constraints on  $Q^0 = EQ$  arising from  $Q$  being t.m. across random  $M \times M$  window in a uniform source-destination flow on the  $N \times N$  torus?

Recall  $Q$  is a measure on pairs  $(v_{\text{ent}}, v_{\text{exi}}) \in \mathbb{R}^2 \times \mathbb{R}^2$ . Has marginals  $Q_{\text{ent}}$  and  $Q_{\text{exi}}$ .

**Constraint 1.** The push-forward of  $Q_{\text{exi}}^0$  under the reflection map equals  $Q_{\text{ent}}^0$ .

**Constraint 2.** Write

$$\text{drift}(Q) = M^{-2} \int (v_{\text{exi}} - v_{\text{ent}}) dQ.$$

Then  $Q^0$  has a mixture representation

$$Q^0 = \int Q \psi(dQ)$$

where  $\psi$  is a p.m. whose pushforward under the map

$$Q \rightarrow \text{drift}(Q) \bmod (1, 1)$$

is uniform on the continuous torus  $[0, 1)^2$ .

Ultimately we prove

$$\lim N^{-2} E\Gamma_N =$$

$$\lim_M M^{-2} \inf\{\text{cost}_M(Q^0) : Q^0 \text{ satisfy constraints}\}.$$

What do we need to do, to prove the upper bound? Fix some  $Q^0$  satisfying constraints. We need to construct a flow on the  $N \times N$  torus such that

$$\begin{aligned} \limsup_N N^{-2} E\text{cost}_{(N)}(\mathbf{f}, \mathbf{c}) \\ \leq M^{-2} \text{cost}_M(Q^0). \end{aligned}$$

Rather magically, our previous abstract [non-constructive] arguments provides clues for the construction. A transportation measure (t.m.)  $Q$  can be normalized to a transition matrix (t.m.). So we can use any given  $Q$  to define a Markov chain on the “skeleton” of the partition.

Take  $N/M$  steps of this chain starting from some vertex  $v_1$ . We finish at some random vertex  $v_2$  with

$$v_2 - v_1 \approx N \text{drift}(Q)$$

using Markov chain LLN. So we construct flows this way. Given source  $v_0$  and destination  $v_1$ , we want to use a  $Q$  with  $\text{drift}(Q) = (v_2 - v_1)/N$ . We get  $Q$  from the disintegration

$$Q^0 = \int Q \psi(dQ)$$

where  $\psi$  is a p.m. whose pushforward under the map

$$Q \rightarrow \text{drift}(Q) \bmod (1, 1)$$

is uniform on the continuous torus  $[0, 1)^2$ .

Putting together all source-destination pairs, we have flows on the skeleton graph which are independent of the realization of environment and for which the expectation of transportation measure across a  $M \times M$  square equals  $Q^0$ .

Within each  $M \times M$  square we simply use the flow  $f$  attaining

$$\inf\{\text{cost}_M(f, c) : f \text{ has t.m. } Q^0\}$$

## Discussion

**1.** Much of the outline seems robust to model details. Plausible that method works quite generally to prove existence of limit constant for cost of optimal flows in  $N \times N$  square with some kind of random environment. Essential requirement is

- Global cost function equals sum of order- $N^2$  local cost functions.

**2.** Assumed edge-capacity =  $B$  (large); helps in some places, hinders in other places. Probably not hard to remove assumption.

**3.** In our open problem (maximum flow volume subject to i.i.d. edge-capacities) the C.I. fails. Because maximum flow volume across  $M \times M$  square is order  $M$  but depends on order  $M^2$  random variables.

4. The global optimal flow satisfies a certain condition by virtue of being a local minimum of

$$\mathbf{f} \rightarrow \text{cost}_{(N)}(\mathbf{f}, \mathbf{c}).$$

But I don't know how to exploit this.