

# Spring 2013 Statistics 153 (Time Series) : Lecture Seventeen

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## 1 Overfitting as a Diagnostic Tool

After fitting an adequate model to the data, fit a slightly more general model. For example, if an AR(2) model seems appropriate, overfit with an AR(3) model. The original AR(2) model can be confirmed if while fitting the AR(3) model:

1. The estimate of the additional  $\phi_3$  parameter is not significantly different from zero.
2. The estimates of the common parameters,  $\phi_1$  and  $\phi_2$ , do not change significantly from their original estimates.

How does one choose this general model to overfit? While fitting a more general model, one should not increase the order of both the AR and MA models. Because it leads to lack of identifiability issues. For example: consider the MA(1) model:  $X_t = (1 + \theta B)Z_t$ . Then by multiplying by the polynomial  $1 - \phi z$  on both sides: we see that  $X_t$  also satisfies the ARMA(1, 2) model:  $X_t - \phi X_{t-1} = Z_t + (\theta - \phi)Z_{t-1} + \phi\theta Z_{t-2}$ . But note that the parameter  $\phi$  is not unique and thus if we fit an ARMA(1, 2) model to a dataset that is from MA(1), we might just get an arbitrary estimate for  $\phi$ .

In general, it is a good idea to find the general overfitting model based on the analysis of the residuals. For example, if after fitting an MA(1) model, a not too small correlation remains at lag 2 in the residuals, then overfit with an MA(2) and not ARMA(1, 1) model.

## 2 Sines and Cosines

Frequency domain techniques: Using sines and cosines to study time series data.

Sinusoid:  $R \cos(2\pi ft + \Phi)$ . The following terminology is standard.  $R$  is called the *amplitude*,  $f$  is called the *frequency* and  $\Phi$  is called the *phase*. The quantity  $1/f$  is called the *period* and  $2\pi f$  is termed the *angular frequency*. Note that three parameters  $R, f$  and  $\Phi$  are involved in the definition of the sinusoid.

The function can also be written as  $A \cos 2\pi ft + B \sin 2\pi ft$  where  $A = R \cos \Phi$  and  $B = R \sin \Phi$ . This parametrization also has three parameters:  $f, A$  and  $B$ .