

Statistics 210B, Spring 1998

Class Notes

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First Set of Notes

1 Hypothesis Testing and Confidence Sets

1.1 Set-up

We are to collect a vector of data $X \in \mathcal{X}$, which has probability distribution \mathbf{P}_θ , with (possibly infinite-dimensional) parameter θ unknown, except that $\theta \in \Theta$, where Θ is a known set. Typically, $\mathcal{X} = \mathbf{R}^n$, but it might instead be a more general measurable space of possible observations. We are interested in making statistical inferences about $\tau(\theta)$, which might be θ itself, or a function of θ (for example, for a univariate normal we might have $\theta = (\mu, \sigma^2)$, and be interested in $\tau(\theta) = \mu$). Let

$$\mathbf{T} \equiv \tau(\Theta) = \{\gamma : \exists \eta \in \Theta \text{ s.t. } \gamma = \tau(\eta)\}, \quad (1)$$

and

$$\mathbf{P}_\Theta = \{\mathbf{P}_\eta : \eta \in \Theta\}. \quad (2)$$

We wish to test the *null hypothesis* $H : \tau(\theta) \in \mathbf{T}_H \subset \mathbf{T}$ against an alternative K not yet specified. In a deliberate “overloading” of notation, let H also stand for $\{\mathbf{P}_\eta, \eta \in \Theta : \tau(\eta) \in$

\mathbf{T}_H (the set of probability distributions for which the null hypothesis H is true), and let K also stand for $\{\mathbf{P}_\eta, \eta \in \Theta : \tau(\eta) \in \mathbf{T}_K\}$ (the set of probability distributions for which the alternative hypothesis K is true). We shall typically assume that $H \cup K = \mathbf{P}_\Theta$.

Definition 1 If $\{\mathbf{P}_\eta \in H\}$ be a singleton set (just one distribution), we say the null hypothesis H is simple. If the alternative K be a singleton set, we say K is simple. If an hypothesis is not simple, it is composite.

Definition 2 A (significance) level α test of the hypothesis $\tau(\theta) \in \mathbf{T}_H$ is a (possibly random) measurable decision rule $\delta(X) : \mathcal{X} \rightarrow \{ \text{accept}, \text{reject} \}$ such that

$$\sup_{\{\mathbf{P}_\eta \in H\}} \mathbf{P}_\eta \{ \delta(X) = \text{reject} \} \leq \alpha. \quad (3)$$

The constant α is (an upper bound on) the probability of a false rejection.

The most common decision rules (deterministic rules) reject when the data X fall outside a set $A = A_H$ that satisfies

$$\sup_{\{\mathbf{P}_\eta \in H\}} \mathbf{P}_\eta \{ X \notin A_H \} \leq \alpha, \quad (4)$$

The set A_H is called the *acceptance region* of the test; A_H^C is the *rejection region* of the test. Under the Neyman-Pearson paradigm, the term “acceptance region” is a misnomer— one never “accepts” the null hypothesis; one merely fails to reject it given certain data (evidence) X . I shall often blur the notational distinction between a test and its acceptance region.

Another family of decision rules performs a random experiment that depends on the observed value of X , such that for each x , the null hypothesis is rejected with probability $\phi(x)$ and not rejected with probability $1 - \phi(x)$. To have a significance level α randomized test, we need

$$\sup_{\{\mathbf{P}_\eta \in H\}} E_\eta \phi(X) = \int \phi(x) d\mathbf{P}_\eta(x) \leq \alpha. \quad (5)$$

Deterministic rules correspond to decision functions ϕ that take only the values 0 (do not reject, with probability 1) and 1 (reject, with probability 1).

Typically, the set A_H is defined in two steps: first, one selects a statistic $T(X)$ (a function of X that is \mathbf{P}_γ -measurable for all $\gamma \in \Theta$, and that does not depend on θ), then one defines

a subset A_{T_H} of the range of T , with the property that

$$\sup_{\{\mathbf{P}_\eta \in H\}} \mathbf{P}_\eta\{T(X) \notin A_{T_H}\} = \alpha. \quad (6)$$

Thus A_H , a subset of \mathcal{X} , is the pre-image under T of A_{T_H} , a subset of the range of T . (In symbols, $A_H = T^{-1}(A_{T_H})$.)

Suppose that the range \mathcal{X} of X is endowed with a distance

$$\begin{aligned} d(\cdot, \cdot) : \mathcal{X} \times \mathcal{X} &\rightarrow \mathbf{R}^+ \\ (x, y) &\mapsto d(x, y), \end{aligned} \quad (7)$$

where \mathbf{R}^+ are the nonnegative reals. (Recall that a distance $d(\cdot, \cdot)$ on a set \mathcal{X} must satisfy

1. $0 \leq d(x, y) \leq \infty$; $d(x, y) = 0 \iff x = y$ (positive definiteness)
2. $d(x, y) = d(y, x)$ (symmetry)
3. $d(x, z) \leq d(x, y) + d(y, z)$ (triangle inequality)

for all x, y, z in \mathcal{X} .)

Definition 3 *The diameter of a set A on which a metric d is defined is*

$$|A| \equiv \sup_{x, y \in A} d(x, y). \quad (8)$$

The radius of A relative to the point x is

$$|A|_\theta \equiv \sup_{y \in A} d(x, y). \quad (9)$$

One natural criterion of optimality of an acceptance region is that its diameter be minimal. This is related to (but not equivalent to) the power of the test against a family of alternatives; *vide infra*.

Definition 4 *A family of tests for $\tau \in \mathbf{T}$ is a set-valued function A_γ such that for each $\gamma \in \mathbf{T}$, A_γ is the acceptance region for a level α test of the hypothesis $H : \tau = \gamma$.*

Examples.

1. Suppose that \mathbf{P}_θ is the normal distribution with mean θ and unit variance, that $\Theta = \mathbf{R}$, $\tau(\theta) = \theta$, and that we observe $X \sim \mathbf{P}_\theta$. Let z_λ be the λ critical value of the standard normal distribution; that is,

$$\mathbf{P}_0\{X \geq z_\lambda\} = \lambda. \quad (10)$$

Then

$$A_\gamma \equiv (\gamma - z_{\alpha/2}, \gamma + z_{\alpha/2}) \quad (11)$$

is a family of level α tests for $\tau(\theta) = \theta \in \mathbf{R}$.

2. Suppose \mathbf{P}_Θ is the family of distributions on \mathbf{R} that are continuous with respect to Lebesgue measure. Let $\tau(\theta)$ be the 90th percentile of the distribution parametrized by θ . We observe $X = \{X_j\}_{j=1}^n$ i.i.d. P_θ . Let $T_\gamma : \mathbf{R}^n \rightarrow \mathbf{N}$ equal $\#\{X_j \geq \gamma\}$. (\mathbf{N} are the nonnegative integers). For all ν such that $\tau(\nu) = \gamma$, the probability distribution of $T_\gamma(X)$ is binomial with parameters n and $p = 0.1$. Thus for any γ , we can find integers $a_- = a_-(\gamma, n, \alpha)$ and $a_+ = a_+(\gamma, n, \alpha)$ such that

$$\mathbf{P}_\nu\{T_\gamma(X) \notin [a_-, a_+]\} \leq \alpha \quad \forall \nu \text{ s.t. } \tau(\nu) = \gamma. \quad (12)$$

Such a pair of mappings defines a family of level α tests for $\tau(\theta) \in \mathbf{R}$.

3. Suppose that \mathbf{P}_Θ is the set of probability distributions on \mathbf{R} that are continuous with respect to Lebesgue measure; let θ be the distribution function of the “true” measure, and suppose we are interested in $\tau(\theta) = \theta$. We observe $X = \{X_j\}_{j=1}^n$ i.i.d. \mathbf{P}_θ . Let $\hat{\theta}_n$ denote the empirical distribution

$$\hat{\theta}_n\{(-\infty, x]\} \equiv \frac{1}{n} \sum_{j=1}^n 1_{x \geq X_j}, \quad (13)$$

where 1_B is the indicator function of the event B . For any two probability distributions $\mathbf{P}_1, \mathbf{P}_2$, on \mathbf{R} , define the Kolmogorov-Smirnov distance

$$d_{KS}(\mathbf{P}_1, \mathbf{P}_2) \equiv \|\mathbf{P}_1 - \mathbf{P}_2\|_{KS} \equiv \sup_{x \in \mathbf{R}} |\mathbf{P}_1\{(-\infty, x]\} - \mathbf{P}_2\{(-\infty, x]\}|. \quad (14)$$

There exist universal constants χ_α so that for every continuous (w.r.t. Lebesgue measure) distribution θ ,

$$\mathbf{P}_\theta \left\{ \|\theta - \hat{\theta}_n\|_{KS} \geq \chi_n(\alpha) \right\} = \alpha. \quad (15)$$

This is the Dvoretzky-Kiefer-Wolfowitz inequality. Moreover, Massart (*Ann. Prob.*, 18, 1269–1283, 1990) showed that the constant

$$\chi_n(\alpha) \leq \sqrt{\frac{\ln \frac{2}{\alpha}}{2n}} \quad (16)$$

is *tight*. For $y = (y_1, \dots, y_n) \in \mathbf{R}^n$, let \hat{y}_n be the probability measure on \mathbf{R} whose distribution function is $1/n \sum_{j=1}^n 1_{x \geq y_j}$. Then

$$A_\gamma \equiv \{y \in \mathbf{R}^n : \|\gamma - \hat{y}_n\|_{KS} \leq \chi_\alpha\} \quad (17)$$

is a family of level α tests for $\theta \in \Theta$.

1.2 Most Powerful Tests

Definition 5 The power β of the test δ of H against the alternative K is

$$\beta = \beta(\delta, K) \equiv \inf_{\mathbf{P}_\nu \in K} \mathbf{P}_\nu \{\delta(X) = \text{reject}\}. \quad (18)$$

That is, $\beta(\delta, K)$ is the smallest probability of rejecting the null hypothesis when the value of the parameter of interest, $\tau(\theta)$, is in the alternative set \mathbf{T}_K .

In the Neyman-Pearson paradigm for hypothesis testing, one is concerned with the probabilities of two kinds of errors: rejecting the null hypothesis H when it is in fact true (a Type I error), and failing to reject the null hypothesis when it is in fact false (a Type II error). The significance level of a test is a bound on the probability of a Type I error; the power of the test against the alternative K is $1 - \sup_{\mathbf{P}_\nu \in K} \mathbf{P}_\nu \{\text{Type II error}\}$.

For a given bound α on the chance of a Type I error, one is naturally led to maximize the power $\beta(K)$. This can be thought of as a more general statistical decision problem with two zero-one loss functions: Define

$$L_1(\theta, \text{reject}) = \begin{cases} 0, & \mathbf{P}_\theta \notin H \\ 1, & \mathbf{P}_\theta \in H \end{cases} \quad (19)$$

$$L_1(\theta, \text{accept}) = 0, \forall \theta \in \Theta, \quad (20)$$

and

$$L_2(\theta, \text{reject}) = 0, \forall \theta \in \Theta, \quad (21)$$

$$L_2(\theta, \text{accept}) = \begin{cases} 0, & \mathbf{P}_\theta \in H \\ 1, & \mathbf{P}_\theta \notin H \end{cases} \quad (22)$$

Then the problem of finding the most powerful test is to find the decision rule δ that minimizes $EL_2(\theta, \delta(X))$ subject to the constraint $EL_1(\theta, \delta(X)) \leq \alpha$.

For the case H and K are simple, let $\mathbf{P}_H = H$ and $\mathbf{P}_K = K$. Considering first nonrandomized tests, one wants to find A_H to maximize

$$\beta = \int_{x \notin A_H} d\mathbf{P}_K(x) \quad (23)$$

subject to

$$\int_{x \notin A_H} d\mathbf{P}_H(x) \leq \alpha. \quad (24)$$

Subject to a bound on the chance of a Type I error, the best points to exclude from A_H are those that are most probable under K relative to their probability under H . Let $r(x) = d\mathbf{P}_K(x)/d\mathbf{P}_H(x)$. Then the most powerful nonrandomized level α test δ has

$$A_H = \{x : r(x) > c\}, \quad (25)$$

where c solves

$$\mathbf{P}_H\{X \notin A_H\} = \int_{x:r(x)>c} d\mathbf{P}_H(x) = \alpha. \quad (26)$$

If \mathbf{P}_H contains atoms, it can happen that for some values of α , the most powerful deterministic decision rule δ that attains exactly level α is not given by the likelihood ratio region 25 for some special values of α (for a given value of c , the level would be too large, while for infinitesimally larger c , the level would be too small). If one allows randomized decisions, that problem does not occur; one makes a deterministic decision when $r < c$ or $r > c$, and makes a random decision for $r = c$, with probability of rejection chosen s.t. the overall level is α . A more common approach (essentially ubiquitous in practice) is to choose α to avoid such pathology.

Theorem 1 *Fundamental Lemma of Neyman and Pearson (See Lehmann, TSH, 3.2, Theorem 1.) Suppose \mathbf{P}_H and \mathbf{P}_K have densities p_H and p_K relative to a measure μ (e.g., $\mathbf{P}_H + \mathbf{P}_K$). Then*

1. There is a decision function ϕ and a constant c such that

$$E_H\phi(X) = \alpha, \quad (27)$$

$$\phi(x) = \begin{cases} 1, & p_K(x) > cp_H(x) \\ 0, & p_K(x) < cp_H(x). \end{cases} \quad (28)$$

(The value of ϕ for $p_K(x) = cp_H(x)$ is adjusted to give $E_H\phi(X) = \alpha$; depending on α , H , and K , this can result in a randomized decision rule.)

2. If a decision function ϕ satisfies 27 and 28 for some c , it is most powerful for testing H against K at level α .
3. If ϕ is the most powerful decision function for testing H against K , then for some c it satisfies 28 a.e. (μ), and it satisfies 27 unless there is a level $< \alpha$ test of H against K with $\beta = 1$.

The fundamental lemma of Neyman and Pearson applies just to simple null and alternative hypotheses. One might hope that when H and K were composite, the same test would be most powerful for all $\mathbf{P}_\eta \in H$ against all $\mathbf{P}_\eta \in K$; unfortunately, that is not typically the case. Such a test, when it exists is called *uniformly most powerful* (UMP).

There is an important class of distributions with real parameters for which UMP tests exist. Suppose \mathbf{P}_η , $\eta \in \Theta = \mathbf{R}$ has density $p_\eta(x)$.

Definition 6 *The set of densities p_η has monotone likelihood ratio (in $T(x)$) if there exists a function $T : \mathcal{X} \rightarrow \mathbf{R}$ such that for $\nu < \eta$*

1. $\mathbf{P}_\nu \neq \mathbf{P}_\eta$, and
2. $p_\eta(x)/p_\nu(x)$ is a monotone non-decreasing function of $T(x)$.

Theorem 2 (See Lehmann, TSH, 3.3, Theorem 2.) *Suppose $\theta \in \Theta = \mathbf{R}$ and X has density $p_\theta(x)$ with monotone likelihood ratio in $T(x)$. Let $H = \{\mathbf{P}_\eta : \eta \leq \eta_H\}$ and $K = \{\mathbf{P}_\eta : \eta > \eta_H\}$. (Such a K is called a one-sided alternative.) Then*

1. A UMP level α test of H against K exists.

2. The decision function ϕ for the UMP test is

$$\phi(x) = \begin{cases} 1, & T(x) > c \\ b & T(x) = c \\ 0, & T(x) < c, \end{cases} \quad (29)$$

with b and c chosen to satisfy

$$E_{\mathbf{P}_{\eta_H}} \phi(X) = \alpha. \quad (30)$$

3. For this test, the power

$$\beta(\mathbf{P}_\theta) = E_{\mathbf{P}_\theta} \phi(X) \quad (31)$$

is a strictly increasing function of θ at all points for which $0 < \beta(\theta) < 1$.

4. For all γ , this test is UMP for testing $\theta \leq \gamma$ against $\theta > \gamma$ at level $\beta(\gamma)$.

5. For any $\theta < \eta_H$, the test minimizes $\beta(\theta)$ among all level α tests.

Definition 7 Let \mathbf{P}_θ , $\theta \in \Theta \subset \mathbf{R}$ have density

$$p_\theta(x) = C(\theta)e^{Q(\theta)T(x)}h(x) \quad (32)$$

relative to some measure μ , with $Q(\cdot)$ strictly monotone. Then $\{\mathbf{P}_\theta : \theta \in \Theta\}$ is a one parameter exponential family.

Remark. The one-parameter exponential families have monotone likelihood ratio in $T(x)$.

Remark. Lehmann refers to a converse due to Pfanzagl (1968) that under weak regularity conditions, if there exist level α UMP tests against one-sided alternatives for all sample sizes, \mathbf{P}_Θ is an exponential family.

1.3 Confidence Regions.

Definition 8 A $1 - \alpha$ confidence region for $\tau(\theta)$ is a random set $S(X) \subset \mathbf{T}$ satisfying

$$\mathbf{P}_\theta\{S(X) \ni \tau(\theta)\} \geq 1 - \alpha. \quad (33)$$

The most common way to construct a $1 - \alpha$ confidence region for $\tau(\theta)$ is by “inverting” a family of tests for the hypotheses $\tau(\theta) = \gamma$:

Theorem 3 *Duality between Tests and Confidence Regions.* (See Lehmann, *TSH*, 3.5, Theorem 4). Let A_γ be a family of acceptance regions for level α tests of the hypotheses $\tau(\theta) = \gamma$. For each value of $x \in \mathbf{R}^n$, define

$$S(x) = \{\gamma \in \mathbf{T} : x \in A_\gamma\}. \quad (34)$$

Then $S(X)$ is a confidence region for $\tau(\theta)$ with confidence level $1 - \alpha$.

Theorem 4 *The Ghosh-Pratt Identity.* (See Pratt, *J.W.*, 1961. *Length of confidence intervals*, *JASA*, 56, 549–567; Ghosh, *J.K.*, 1961. *On the relation among shortest confidence intervals of different types*, *Calcutta Stat. Assoc. Bull.*, 147–152.) For a set $S(x) \subset \Theta$, let

$$\mu(S(x)) \equiv \int_{\gamma \in S(x)} d\mu(\gamma), \quad (35)$$

for some measure μ on Θ . Then

$$E_{\mathbf{P}_\eta} \mu(S(X)) = \int \mathbf{P}_\eta\{S(X) \ni \gamma\} d\mu(\gamma). \quad (36)$$

The Ghosh-Pratt identity relates the expected “volume” (w.r.t. the measure μ) of a confidence set to the probability that points other than the true parameter are in the set: the right hand side is the integral of the “false coverage” probability. That is in turn related to the power of the tests to which S is dual against the alternative with respect to which the expectation and the probability are calculated. For example, suppose that $\Theta = \mathbf{R}^m$, that μ is Lebesgue measure (so the expectation on the left is the “ordinary” expected volume of the confidence set) and that S is the dual of a family of tests that are most powerful against the alternative $\theta = \mathbf{0}$. That is, the sets A_ν minimize $\mathbf{P}_\nu\{\mathbf{0} \ni A_\nu\}$. Then the confidence set $S(X)$ has minimal expected volume when the true value of θ is $\mathbf{0}$ among all confidence sets.

Brown, Casella and Huang (Optimal Confidence Sets, Bioequivalence, and the Limacon of Pascal, Brown Univ. Tech. Rept. BU-1205-M, 1993, rev.1994) use this result to develop confidence sets for assessing bioequivalence. In the case $X \sim N(\theta, I)$, the acceptance regions of tests with optimal power against $\mathbf{0}$ can be derived from the likelihood ratio; Brown and Huang obtain closed-form expressions for the shape of the resulting confidence sets.

Problem. Find a formula for a $1 - \alpha$ confidence set for the mean of a Poisson distribution from n i.i.d. observations, with minimal expected volume when the true mean $\theta = 1$. Is the

set always an interval? Give the confidence set that results when $X = 2$. It might help to read Brown and Huang.