

Hierarchical Linear Regression

The following hierarchical linear model was the basis for smoothing in the proposed 1990 census adjustment (Freedman et al, 1993):

$$\begin{aligned} (1a) \quad & Y = \gamma + \delta \\ (1b) \quad & \gamma = X\beta + \epsilon. \end{aligned}$$

Here, X may be viewed as a fixed $n \times p$ matrix; δ and ϵ are assumed to be independent $n \times 1$ vectors; the means are 0; $\text{cov}(\delta) = K$ is a given positive definite matrix; $\text{cov}(\epsilon) = \sigma^2 I$, where σ^2 is given, being positive and finite; I is the $n \times n$ identity matrix. In the census context, Y would be the vector of “raw” adjustment factors and γ the “true” adjustment factors, with one component of the vector for each post stratum in a region. Theorem (3) below would not apply: σ^2 and K have to be estimated from the data, X is chosen by a data-based algorithm, etc. For more discussion of the model in the census context, see Freedman et al (1993).

Goldberger (1962) proposed the estimator $\hat{\gamma}$ for γ . His construction involves an auxiliary matrix Γ ; to define the latter, let H be the OLS projection matrix, that is, $H = X(X'X)^{-1}X'$. Now

$$\begin{aligned} (2a) \quad & \Gamma^{-1} = K^{-1} + \sigma^{-2}(I - H) \\ (2b) \quad & \hat{\gamma} = \Gamma K^{-1}Y. \end{aligned}$$

The estimator $\hat{\gamma}$ can be motivated in the normal case as Bayes with a diffuse prior on β ; then Γ is the posterior covariance of γ given Y ; see Lindley and Smith (JRSS, 1972). Being positive definite, $K^{-1} + \sigma^{-2}(I - H)$ is invertible. Hence, Γ is well-defined and positive definite. Moreover, Γ is symmetric because K and H are symmetric.

Notes. Being a covariance matrix, K is symmetric; so is Γ ; but ΓK^{-1} is asymmetric. The estimator $\hat{\gamma}$ can also be represented as a generalized average of Y and gls; see (28). If U, V are $n \times 1$ and $m \times 1$, respectively, and $E(U) = E(V) = 0$, then $\text{cov}(U, V)$ is defined as $E(UV')$.

(3) Theorem (Goldberger).

- (a) $E(\hat{\gamma} - \gamma) = 0$
- (b) $\text{cov}(\hat{\gamma} - \gamma) = \Gamma$
- (c) $\hat{\gamma}$ is the minimum-variance unbiased linear estimator of γ .

The object here is to prove (3). Claim (c) can be translated as follows. If M is an $n \times n$ matrix and $E(MY - \gamma) = 0$, then $\text{cov}(MY - \gamma) - \Gamma$ is non-negative definite, vanishing only if $M = \Gamma K^{-1}$.

Warning. $\text{cov}(\hat{\gamma}) \neq \Gamma$ for the objectivist, because γ is random.

(4) Lemma. $\Gamma K^{-1}X = X$ so $\Gamma K^{-1}H = H$.

Proof. Let x be in the column space of X . Then

$$\Gamma^{-1}x = K^{-1}x;$$

indeed, by (2a) the difference is $\sigma^{-2}(I - H)x = 0$. Pre-multiply the display by Γ . QED

Claim (a) in the theorem is immediate: $E(\gamma) = X\beta = E(\hat{\gamma})$, the last equality holding by (4).

(5) Lemma. If M is an $n \times n$ matrix and $E(MY - \gamma) = 0$, then $MX = X$ and $MH = H$.

Proof. Clearly, $(MX - X)\beta = 0$ for all β . QED

(6) Lemma. If M is an $n \times n$ matrix and $MX = X$, then

$$\text{cov}(MY - \gamma) = MKM' + \sigma^2(M - I)(M' - I).$$

Proof. Clearly,

$$(7) \quad MY - \gamma = M\delta + (M - I)\epsilon$$

because $MX = X$. Now use the assumptions on δ and ϵ . QED

Use (7) with $M = \Gamma K^{-1}$ to see

$$(8) \quad \hat{\gamma} - \gamma = \Gamma K^{-1}\delta + (\Gamma K^{-1} - I)\epsilon.$$

Claim (3b) follows from (6) applied to $M = \Gamma K^{-1}$ and the identity

$$(9) \quad \Gamma K^{-1}\Gamma + \sigma^2(\Gamma K^{-1} - I)(K^{-1}\Gamma - I) = \Gamma.$$

To prove (9), multiply from the right by Γ^{-1} ; use definition (2a) to evaluate $K^{-1} - \Gamma^{-1}$ and (4) to simplify the results.

For claim (3c), let $\zeta = MY - \hat{\gamma}$, so that

$$(10) \quad MY - \gamma = (\hat{\gamma} - \gamma) + \zeta.$$

It suffices to show that $MX = X$ implies

$$(11) \quad \text{cov}(\zeta, \hat{\gamma} - \gamma) = 0$$

because then $\text{cov}(MY - \gamma) = \text{cov}(\hat{\gamma} - \gamma) + \text{cov}(\zeta)$. Clearly,

$$(12) \quad \zeta = (M - \Gamma K^{-1})(\delta + \epsilon).$$

By (8) and (12),

$$(13) \quad \text{cov}(\zeta, \hat{\gamma} - \gamma) = \text{E}\{\zeta(\hat{\gamma} - \gamma)'\} = (M - \Gamma K^{-1})\Gamma + (M - \Gamma K^{-1})(K^{-1}\Gamma - I)\sigma^2.$$

The right side of (13) is

$$(14) \quad (M - \Gamma K^{-1})\left[\Gamma + \sigma^2(K^{-1}\Gamma - I)\right].$$

By the definition (2a) of Γ ,

$$\left[K^{-1} + \sigma^{-2}(I - H)\right]\Gamma = I,$$

so

$$K^{-1}\Gamma = I - \sigma^{-2}(I - H)\Gamma$$

and

$$(15) \quad \sigma^2(K^{-1}\Gamma - I) = -(I - H)\Gamma.$$

The identity (15) can be used to evaluate the expression (14) as

$$(M - \Gamma K^{-1})(\Gamma - \Gamma + H\Gamma) = \left[(M - \Gamma K^{-1})H\right]\Gamma = 0$$

by (4) and (5). This proves (11), hence, (3). QED

Notes. (i) The proof of (9) could be rearranged slightly to use (15).

(ii) For uniqueness, $\text{cov}(\zeta) = 0$ means that $MY = \hat{\gamma}$ almost surely, and then $M = \Gamma K^{-1}$ rather easily.

Discussion

Goldberger's estimate is in the shrinkage—empirical Bayes style; Y is shrunk toward the column space C of X . This works fine if C is low-dimensional and γ is almost in there, i.e., σ^2 is small. The amount of shrinking and the directions are controlled by σ^2 and K . If you get these wrong, or some of the modeling assumptions break down, shrinking can actually make the errors bigger rather than smaller. Also, the benefits of shrinking—as gauged by Γ —depend rather critically on the assumptions about the error terms δ and ϵ . To sum up: If the model is wrong, the benefits of shrinking can be over-stated, and shrinking can be counter-productive. For some empirical evidence, see (Freedman and Navidi, 1986) or (Freedman et al, 1993).

Conditional Normal Distributions

Let U and V be jointly normal vectors, $n \times 1$ and $m \times 1$, respectively; both have mean 0. Suppose V is of full rank. By definition, $\text{cov}(U, V) = \text{E}(UV')$ and $\text{cov}(V) = \text{cov}(V, V)$. Let $M = \text{cov}(U, V)\text{cov}(V)^{-1}$; this is an $n \times m$ matrix, well-defined because V has full rank.

(16) Proposition.

- (a) $E\{U|V\} = MV$.
- (b) $\text{cov}\{U|V\} = \text{cov}(U) - \text{cov}(U, V)\text{cov}(V)^{-1}\text{cov}(V, U)$.
- (c) The conditional distribution of U is normal.

Proof. Let $\zeta = U - MV$. Clearly, U , V , and ζ are jointly normal with mean 0; furthermore, $\text{cov}(\zeta, V) = 0$ and $\text{cov}(\zeta)$ is given by the right hand side of (b). Thus, ζ and V are independent; given $V = v$, U is distributed as $Mv + \zeta$. QED

Notes. (i) It is normality that converts $\text{cov}(\zeta, V) = 0$ to independence. To argue the independence, you need to write down the density and factor it.

(ii) The right hand side in (b) is “total variance – explained variance.”

(17) Lemma. Let A and B be $n \times n$ matrices; suppose $A + B$ is invertible.

- (a) $A(A + B)^{-1} = I_n - B(A + B)^{-1}$.
- (b) $(A + B)^{-1}A = I_n - (A + B)^{-1}B$.
- (c) $A(A + B)^{-1}B = B(A + B)^{-1}A$.
- (d) Suppose A is invertible and $A^{-1}B = BA^{-1}$. Then

$$A(A + B)^{-1} = (A + B)^{-1}A.$$

Proof. For claim (a), $I_n = (A + B)(A + B)^{-1} = A(A + B)^{-1} + B(A + B)^{-1}$, and (b) is the same. For (c), use (a) and (b):

$$\begin{aligned} A(A + B)^{-1}B &= A\left[(A + B)^{-1}B\right] \\ &= A\left[I_n - (A + B)^{-1}A\right] \\ &= A - A(A + B)^{-1}A \\ &= \left[I_n - A(A + B)^{-1}\right]A \\ &= B(A + B)^{-1}A. \end{aligned}$$

For (d),

$$A(A + B)^{-1} = \left(I_n + \frac{B}{A}\right)^{-1} = (A + B)^{-1}A. \quad \text{QED}$$

(18) Proposition. Let ζ and η be independent mean 0 normal $n \times 1$ vectors with respective covariance matrices C and D . Then

- (a) $E\{\zeta|\zeta + \eta\} = C(C + D)^{-1}(\zeta + \eta)$
- (b) $\text{cov}\{\zeta|\zeta + \eta\} = C(C + D)^{-1}D$.

Proof. This follows from (16). Indeed, $\text{cov}(\zeta, \zeta + \eta) = \text{cov}(\zeta)$ so $M = C(C + D)^{-1}$. And $\text{cov}\{\zeta | \zeta + \eta\}$ is given by (17b) as

$$C - C(C + D)^{-1}C = C\left(I_n - (C + D)^{-1}C\right) = C(C + D)^{-1}D. \quad \text{QED}$$

Bayesian Least Squares

Consider the regression model

$$(19) \quad Y = X\beta + \epsilon, \quad \epsilon \sim N(0, \sigma^2 I_n)$$

where Y is $n \times 1$, X is $n \times p$ of full rank, β is $p \times 1$, and ϵ is $n \times 1$. For the moment, β is unknown but σ is known. Take X to be constant (non-random). For the Bayesian, β has a prior distribution—and a posterior given the data Y .

(20) Proposition. With the OLS regression model (19), and $\beta \sim N(0, \tau^2 I_p)$ independent of ϵ , the posterior distribution of β given Y is normal, with conditional mean

$$\hat{\beta}_{\text{Bayes}} = \left(I_p - \frac{\sigma^2}{\tau^2 X'X + \sigma^2 I_p}\right) \hat{\beta}_{\text{ols}}$$

and conditional variance

$$\text{cov}\{\beta | Y\} = \frac{\tau^2 \sigma^2}{\tau^2 X'X + \sigma^2 I_p}.$$

Proof. Since $X'Y$ is sufficient, it is enough to compute the conditional law of β given $X'Y$. This can be done using (16) with $U = \beta$ and $V = X'Y$. For the Bayesian, $\text{cov}(X'Y) = \tau^2(X'X)^2 + \sigma^2 X'X$ while $\text{cov}(\beta, X'Y) = \tau^2(X'X)$. So

$$\begin{aligned} M &= \frac{\tau^2 X'X}{\tau^2(X'X)^2 + \sigma^2 X'X} \\ &= \frac{\tau^2 X'X}{\tau^2 X'X + \sigma^2 I_p} (X'X)^{-1} \\ &= \left(I_p - \frac{\sigma^2}{\tau^2 X'X + \sigma^2 I_p}\right) (X'X)^{-1} \end{aligned}$$

and

$$MX'Y = \left(I_p - \frac{\sigma^2}{\tau^2 X'X + \sigma^2 I_p}\right) \hat{\beta}_{\text{ols}}.$$

The matrices commute, so the informal notation is unambiguous. The assertion about the conditional mean is now proved, and the conditional variance follows from (16b) by a straightforward calculation. QED

Notes. (i) With lots of data (and a little luck), $X'X$ is large. Then $\hat{\beta}_{\text{Bayes}} \approx \hat{\beta}_{\text{ols}} = \hat{\beta}_{\text{mle}}$ and $\text{cov}\{\beta|Y\} \approx \sigma^2(X'X)^{-1}$, the frequentist covariance of $\hat{\beta}_{\text{mle}}$. This is a special case of the Bernstein-von Mises theorem: under suitable regularity conditions, asymptotically, the posterior distribution of $\beta - \hat{\beta}_{\text{mle}}$ is close to the frequentist distribution of $\hat{\beta}_{\text{mle}} - \beta_{\text{true}}$.

(ii) Suppose σ^2 is fixed and τ^2 is large, so the prior is “diffuse” or “uninformative” or an “ignorance prior.” (An uninformative prior could be defined as Lebesgue measure on I_p .) Then the Bayes estimate is essentially the same as the OLS estimate.

(iii) Suppose τ^2 is fixed and σ^2 is large, so the data are “uninformative.” Then the posterior is essentially the same as the prior. In the extreme, if $\tau^2 = 0$, you start by knowing that $\beta = 0$, that is how you end up.

(iv) The proof of (20) can be based on (18) with $\zeta = X'X\beta$ and $\eta = X'\epsilon$.

(21) Corollary. In (19), suppose $\epsilon \sim N(0, K)$ where K is $n \times n$ positive definite and given. With this GLS model, the posterior distribution of β given Y is normal, with conditional mean

$$\hat{\beta}_{\text{Bayes}} = \left(I_p - (\tau^2 X' K^{-1} X + I_p)^{-1} \right) \hat{\beta}_{\text{GLS}}$$

and conditional variance

$$\text{cov}\{\beta|Y\} = \tau^2 (\tau^2 X' K^{-1} X + I_p)^{-1}.$$

Proof. Multiplication from the left by $K^{-1/2}$ converts the GLS model to OLS, with $\sigma^2 = 1$ and design matrix $K^{-1/2}X$. QED

An Identity

Of course, with the GLS regression model, it is possible to compute the posterior mean directly from (16), as $E(\beta|Y) = \tau^2 X' (\tau^2 X X' + K)^{-1}$. Thus we have an indirect proof of the well-known identity

$$(22) \quad X' (\tau^2 X X' + K)^{-1} = (\tau^2 X' K^{-1} X + I_p)^{-1} X' K^{-1}.$$

This can be proved directly: multiply from the left by

$$\tau^2 X' K^{-1} X + I_p$$

and from the right by $\tau^2 X X' + K$; then clean up.

Note. $X X'$ is singular, so the behavior of $(\tau^2 X X' + K)^{-1}$ on the left in (22) for large τ^2 is problematic. On the right, $X' K^{-1} X$ is invertible.

Bayes and Goldberger

Consider the model (1) from a Bayesian perspective: we assume K and σ^2 are known, and put a prior on the “hyper-parameters” β , namely, $\beta \sim N(0, \tau^2 I_p)$, independent of δ and ϵ .

(23) Theorem. Consider the model (1) with prior distribution $\beta \sim N(0, \tau^2 I_p)$ independent of δ and ϵ . Let $\tau \rightarrow \infty$. The Bayes estimate for γ converges to $\hat{\gamma}$, and the posterior variance converges to Γ .

The proof is a bit involved. As before, we can use (16) to compute the posterior law of γ given Y . This is best done in three steps:

Step 1. Compute the posterior law of β given Y . We have a GLS model with covariance matrix $\Sigma = K + \sigma^2 I_n$. The posterior distribution is by (16) multivariate normal with conditional mean

$$(24) \quad \hat{\beta}_{\text{Bayes}} = \left(I_p - (\tau^2 X' \Sigma^{-1} X + I_p)^{-1} \right) \hat{\beta}_{\text{GLS}}$$

and conditional variance

$$(25) \quad \text{cov}\{\beta|Y\} = \tau^2 (\tau^2 X' \Sigma^{-1} X + I_p)^{-1}.$$

Step 2. Compute the conditional law of γ given β and Y ; this is done below, also using (16). Call the conditional density $f(\gamma|\beta, y)$. Of course, f is normal.

Step 3. Integrate out β in $f(\cdot|\beta, y)$ from Step 2 using the posterior law of β from Step 1. This too is done below.

Step 2 can be implemented as follows: β and Y contain the same information (i.e., span the same σ -field) as β and $\delta + \epsilon$. Recall that $\gamma = X\beta + \epsilon$. Let $\Sigma = \sigma^2 I_p + K$. By (18),

$$(26) \quad \begin{aligned} \text{E}\{\gamma|\beta, Y\} &= \text{E}\{\gamma|\beta, \delta + \epsilon\} \\ &= X\beta + \text{E}\{\epsilon|\beta, \delta + \epsilon\} \\ &= X\beta + \text{E}\{\epsilon|\delta + \epsilon\} && \text{because } \beta \perp (\delta, \epsilon) \\ &= X\beta + \sigma^2 \Sigma^{-1} (\delta + \epsilon) \\ &= X\beta + \sigma^2 \Sigma^{-1} (Y - X\beta) \\ &= \sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} X\beta && \text{by (17a).} \end{aligned}$$

Likewise,

$$(27) \quad \text{cov}\{\gamma|\beta, Y\} = \sigma^2 \Sigma^{-1} K.$$

Note. Step 2 is conditional on β and results do not involve τ^2 .

Step 3 is done by the following computation:

$$(28) \quad \begin{aligned} \text{E}\{\gamma|Y\} &= \sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} X \text{E}\{\beta|Y\} \\ &= \sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} X \hat{\beta}_{\text{Bayes}} \\ &= \sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} X \hat{\beta}_{\text{GLS}} - \Delta \\ &= \sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} \hat{Y}_{\text{GLS}} - \Delta \end{aligned}$$

where

$$(29) \quad \Delta = K \Sigma^{-1} X (\tau^2 X' \Sigma^{-1} X + I_p)^{-1} \hat{\beta}_{\text{GLS}}.$$

For τ^2 large the term Δ is negligible, presenting $\hat{\gamma}$ as a mixture—with matrix weights—of Y and the GLS projection onto the column space of X .

Now $\text{cov}(\gamma|Y)$ may be computed by integrating out β but holding Y fixed:

$$(30) \quad \text{E}\{\text{cov}(\gamma|\beta, Y) \mid Y\} + \text{cov}\{\text{E}(\gamma|\beta, Y) \mid Y\}.$$

In the first term of (30), $\text{cov}(\gamma|\beta, Y) = \sigma^2 K \Sigma^{-1}$ and is constant, see (27). In the second term, $\text{E}(\gamma|\beta, Y)$ is by (26) equal to

$$\sigma^2 \Sigma^{-1} Y + K \Sigma^{-1} X \beta,$$

whose covariance given Y is

$$(31) \quad K \Sigma^{-1} X \text{cov}\{\beta|Y\} X' \Sigma^{-1} K.$$

But $\text{cov}\{\beta|Y\}$ was computed in Step 1, see (25); and (31) is

$$K \Sigma^{-1} X \left[\tau^2 (\tau^2 X' \Sigma^{-1} X + I_p)^{-1} \right] X' \Sigma^{-1} K \rightarrow K \Sigma^{-1} H_{\Sigma} K$$

as $\tau^2 \rightarrow \infty$. (By definition, $\Sigma = \sigma^2 I_n + K$, and $H_{\Sigma} = X(X' \Sigma^{-1} X)^{-1} X' \Sigma^{-1}$ is the GLS projection matrix relative to Σ .) Thus,

$$(32) \quad \text{cov}\{\gamma|Y\} = \sigma^2 \Sigma^{-1} K + K \Sigma^{-1} H_{\Sigma} K.$$

Note: We have to use $\text{cov}(\beta|Y)$ not $\text{cov}(\beta)$ in (31).

(33) Lemma. Let $\Sigma = \sigma^2 I_n + K$ and $H_{\Sigma} = X(X' \Sigma^{-1} X)^{-1} X' \Sigma^{-1}$.

- (a) $X' \Sigma^{-1} (I_n - H_{\Sigma}) = 0$.
- (b) $H_{\Sigma} \Sigma^{-1} (I_n - H_{\Sigma}) = 0$.
- (c) $(I_n - H) H_{\Sigma} = 0$.
- (d) $\Gamma K^{-1} = H_{\Sigma} + \sigma^2 \Sigma^{-1} (I_n - H_{\Sigma})$.
- (e) $\Gamma K^{-1} = \sigma^2 \Sigma^{-1} + K \Sigma^{-1} H_{\Sigma}$.
- (f) $\Gamma = \sigma^2 \Sigma^{-1} K + K \Sigma^{-1} H_{\Sigma} K$.

Proof. Claim (a) is easy and (b) follows on multiplying from the left by $X(X' X)^{-1}$. Claim (c) is easy. For (d), by (2a),

$$(34) \quad K \Gamma^{-1} = I_n + \sigma^{-2} K (I_n - H).$$

We have to prove

$$(35) \quad \left[I_n + \sigma^{-2} K (I_n - H) \right] \left[H_{\Sigma} + \sigma^2 \Sigma^{-1} (I_n - H_{\Sigma}) \right] = I_n.$$

By (c), the left side of (35) is

$$\begin{aligned}
H_\Sigma + \sigma^2 \Sigma^{-1} (I_n - H_\Sigma) + K \Sigma^{-1} (I_n - H_\Sigma) \\
&= H_\Sigma + (\sigma^2 I_n + K) \Sigma^{-1} (I_n - H_\Sigma) \\
&= H_\Sigma + \Sigma \Sigma^{-1} (I_n - H_\Sigma) = I_n.
\end{aligned}$$

This proves (35) and hence (d). Claim (e) follows from (d): the difference between the two right hand sides is 0, as one sees by collecting terms. For (f), multiply (e) on the right by K . QED

(36) Corollary. Let $\tau \rightarrow \infty$.

- (a) $E\{\gamma|Y\} \rightarrow \sigma^2(\sigma^2 I_p + K)^{-1} Y + K(\sigma^2 I_p + K)^{-1} \hat{Y}_{\text{gls}} = \Gamma K^{-1} Y$.
- (b) $\text{cov}\{\gamma|Y\} \rightarrow \Gamma$.

Proof. Claim (a). Convergence follows from (28), because $\Delta \rightarrow 0$. Then use (33e). Claim (b) is immediate from (32) and (33f). QED

This completes our first proof of (23).

Bayes, Goldberger and the Identity

Here is a more direct approach, with the same model and prior as in the previous section. We use (18) with $\zeta = \gamma$ and $\eta = \delta$. For the Bayesian, these are independent normal vectors with mean 0; furthermore,

$$(37) \quad C = \text{cov}(\zeta) = \text{cov}(\gamma) = \sigma^2 I_n + \tau^2 X X'$$

$$(38) \quad D = \text{cov}(\eta) = \text{cov}(\delta) = K.$$

Thus, $E\{\gamma|Y\} = M Y$ where $M = C(C + D)^{-1}$ so

$$(39) \quad M^{-1} = I_n + \sigma^{-2} K (I_n + \lambda X X')^{-1}$$

with $\lambda = \tau^2/\sigma^2$. We want $M^{-1} \rightarrow K \Gamma^{-1}$ as $\lambda \rightarrow \infty$, that is,

$$(40) \quad (I_n + \lambda X X')^{-1} \rightarrow I - H.$$

Of course, if $x \perp X$, then $(I_n + \lambda X X')x = x$ so $(I_n + \lambda X X')^{-1}x = x = (I - H)x$. Suppose now that x is in the column space of X , that is, $x = Xc$ where c is $p \times 1$. We must show

$$(41) \quad (I_n + \lambda X X')^{-1}x \rightarrow 0.$$

To prove (41), we use (22) twice, with $K = I_n$ and $\tau^2 = 1/\lambda$:

$$\begin{aligned}
\|(I_n + \lambda X X')^{-1} Xc\|^2 &= c' X' (I_n + \lambda X X')^{-2} Xc \\
&= c' (I_p + \lambda X' X)^{-1} X' (I_n + \lambda X X')^{-1} Xc \\
&= c' (I_p + \lambda X' X)^{-2} X' Xc \\
&= \lambda^{-2} c' (\lambda^{-2} I_p + X' X)^{-2} X' Xc \rightarrow 0.
\end{aligned}$$

The point of rigor: the function $A \rightarrow A^{-2}$ is continuous at $X'X$ not at XX' .

The covariance of γ given Y follows from (18b), indeed

$$\text{cov}\{\beta|Y\} = C(C + D)^{-1}D = MK;$$

But $M \rightarrow \Gamma K^{-1}$ as $\tau \rightarrow \infty$. This completes our second proof of (23).

References

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