### Generalization in Deep Networks

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## Deep neural networks

### Game playing



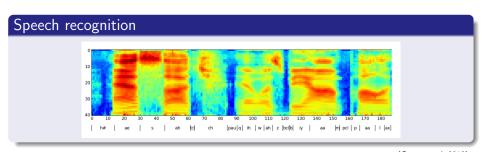
(Jung Yeon-Je/AFP/Getty Images)

## Deep neural networks



(Krizhevsky et al, 2012)

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(Graves et al, 2013)

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- Data generated by a probability distribution P on  $\mathcal{X} \times \{-1,1\}$ .
- Want to choose a function f such that  $P(f(x) \neq y)$  is small (near optimal).

### **Theorem** (Vapnik and Chervonenkis)

Suppose  $\mathcal{F} \subseteq \{-1,1\}^{\mathcal{X}}$ . For every prob distribution P on  $\mathcal{X} \times \{-1,1\}$ , with probability  $1-\delta$  over n iid examples  $(x_1,y_1),\ldots,(x_n,y_n)$ , every f in  $\mathcal{F}$  satisfies

$$P(f(x) \neq y) \leq \frac{1}{n} \left| \left\{ i : f(x_i) \neq y_i \right\} \right| + \left( \frac{c}{n} \left( \operatorname{VCdim}(\mathcal{F}) + \log(1/\delta) \right) \right)^{1/2}.$$

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- For neural networks, VC-dimension:
  - increases with number of parameters
  - · depends on nonlinearity and depth

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$$VCdim(\mathcal{F}) = \tilde{O}(p).$$

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Piecewise linear (ReLUs):

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$$VCdim(\mathcal{F}) = \tilde{O}(p^2k^2).$$

(Karpinsky and MacIntyre, 1994)

### Generalization in Neural Networks: Number of Parameters

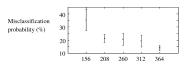
### NIPS 1996

#### **Experimental Results**

Neural networks with many parameters, trained on small data sets, sometimes generalize well.

Eg: Face recognition (Lawrence et al, 1996)

m=50 training patterns.



Number of weights Number of patterns

- What determines the statistical complexity of a deep network?
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• For large-margin classifiers, we should expect the fine-grained details of *f* to be less important.



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*n* training examples

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$$\Pr(\operatorname{sign}(f(X)) \neq Y)$$

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(Schapire, Freund, B., Lee, 1998)

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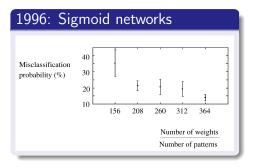
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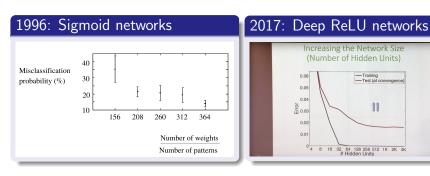
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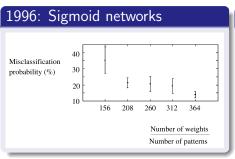


 Qualitative behavior explained by small weights theorem.

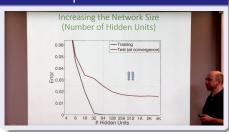


simons.berkeley.edu

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### 2017: Deep ReLU networks



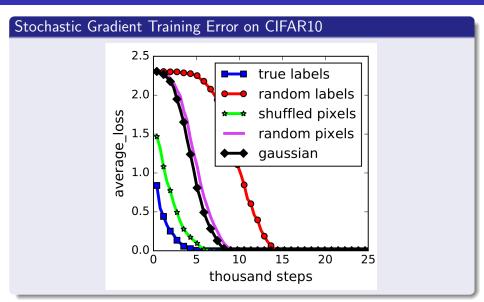
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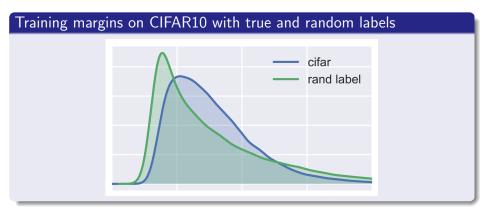
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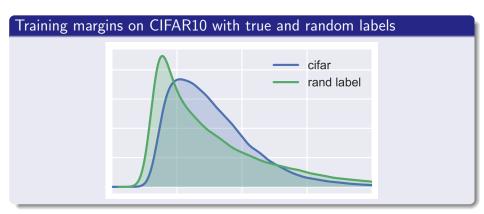
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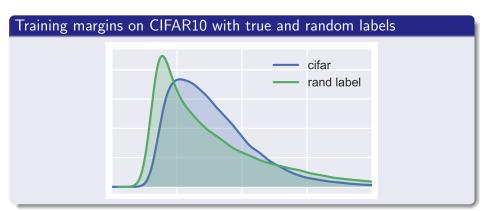
#### CIFAR10 6: frog 9: truck 9: truck 4: deer 1: automobile 2: bird 8: ship 3: cat 1: automobile 7: horse 4: deer 7: horse 2: bird 9: truck 9: truck 9: truck 3: cat 2: bird 6: frog



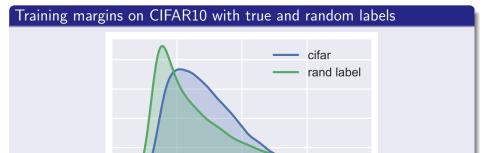




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- Need to account for the scale of the neural network functions.
- What is the appropriate notion of the size of these functions?

Spectrally-normalized margin bounds for neural networks. B., Dylan J. Foster, Matus Telgarsky, 2017. arXiv:1706.08498



Matus Telgarsky UIUC



Dylan Foster Cornell

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• Multiclass margin function for  $f: \mathcal{X} \to \mathbb{R}^m$ ,  $y \in \{1, \dots, m\}$ :

$$M(f(x),y) = f(x)_y - \max_{i \neq y} f(x)_i.$$

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Scale of 
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:  $R_A := \prod_{i=1}^L \|A_i\|_* \sqrt{\sum_{i=1}^L \frac{\|A_i\|_F}{\|A_i\|_*}}$ .

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$$\Pr(M(f_A(X),Y)\leq 0)\leq \frac{1}{n}\sum_{i=1}^n 1[M(f_A(X_i),Y_i)\leq \gamma]+\tilde{O}\left(\frac{rL}{\gamma\sqrt{n}}\right).$$

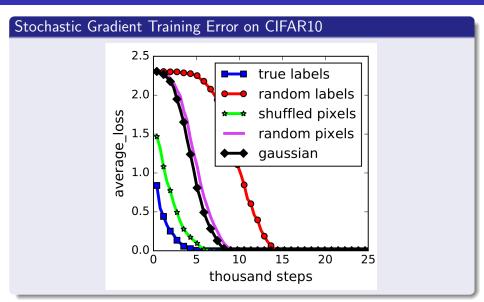
### Definitions

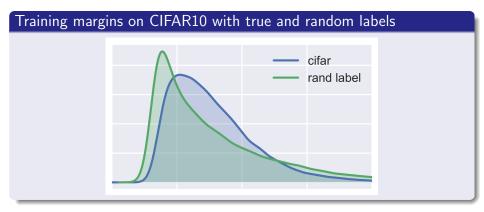
Network with L layers, parameters  $A_1, \ldots, A_L$ :

$$f_A(x) := \sigma_L(A_L\sigma_{L-1}(A_{L-1}\cdots\sigma_1(A_1x)\cdots)).$$

Scale of 
$$f_A$$
:  $R_A := \prod_{i=1}^L \|A_i\|_* \sqrt{\sum_{i=1}^L \frac{\|A_i\|_F}{\|A_i\|_*}}$ .

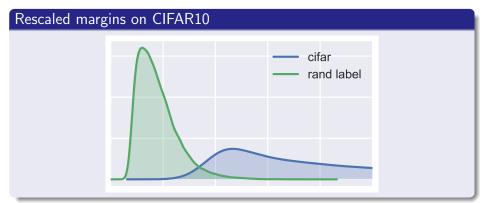
(Assume  $\sigma_i$  is 1-Lipschitz, inputs normalized.)





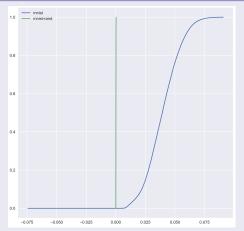
• How does this match the large margin explanation?

If we rescale the margins by  $R_A$  (the scale parameter):



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## Rescaled cumulative margins on MNIST



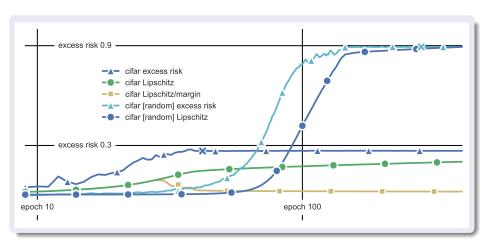
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- Interplay with optimization?

### Outline

- What determines the statistical complexity of a deep network?
  - VC theory: Number of parameters
  - Margins analysis: Size of parameters
  - Understanding generalization failures