

# Stat 260/CS 294-102. Learning in Sequential Decision Problems.

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## 1. More contextual bandits.

- Recall: Bandits with expert advice.
- Infinite comparison classes.
  - Examples: parameterized policies.
  - Finite approximations:  $\epsilon$ -covers and Exp4.
  - Constructing  $\epsilon$ -covers:
    - (a) Lipschitz, bounded parameterization.
    - (b)  $\Pi$  with bounded VC-dimension.

## Recall: Contextual bandits

At each round:

- See  $X_t \in \mathcal{X}$ .
- Choose  $I_t \in \mathcal{A}$ ,  $\mathcal{A} = \{1, \dots, k\}$ .
- Receive reward  $Y_{I_t, t} \in \mathbb{R}$ .

Stochastic/adversarial model for  $(X, Y) \in \mathcal{X} \times \mathbb{R}^{\mathcal{A}}$ .

Pseudo-regret:

$$\bar{R}_n = \sup_{\pi \in \Pi} \mathbb{E} \sum_{t=1}^n Y_{\pi(X_t), t} - \mathbb{E} \sum_{t=1}^n Y_{I_t, t}.$$

where  $\Pi$  is *comparison class* of policies  $\pi : \mathcal{X} \rightarrow \mathcal{A}$ .

## Recall: Bandits with expert advice

Repeated game:

1. Adversary chooses rewards  $(y_{1,t}, \dots, y_{k,t})$ .
2. Adversary presents expert advice  $\xi_t^1, \dots, \xi_t^N \in \Delta_k$ .
3. Strategy chooses the distribution of  $I_t$ .
4. Strategy receives reward  $y_{I_t,t}$ .

## Recall: Exp4

### Strategy Exp4

set  $q_1$  uniform on  $\{1, \dots, N\}$ .

for  $t = 1, 2, \dots, n$ , observe  $\xi_t^1, \dots, \xi_t^N \in \Delta_k$ ;

choose  $I_t \sim p_t$ , where  $p_{i,t} = \mathbb{E}_{J \sim q_t} \xi_{i,t}^J$ ; observe  $\ell_{I_t,t}$ .

$$\tilde{\ell}_{i,t} = \frac{\ell_{i,t}}{p_{i,t}} \mathbf{1}[I_t = i], \quad \tilde{y}_{j,t} = \mathbb{E}_{I \sim \xi_t^j} \tilde{\ell}_{I,t},$$

$$\tilde{Y}_{j,t} = \sum_{s=1}^t \tilde{y}_{j,s}, \quad q_{j,t+1} = \frac{\exp(-\eta \tilde{Y}_{j,t})}{\sum_{i=1}^N \exp(-\eta \tilde{Y}_{i,t})}.$$

## Recall: Exp4

**Theorem:** Regret of Exp4:

$$\eta = \sqrt{\frac{2 \log N}{nk}}, \quad \bar{R}_n \leq \sqrt{2nk \log N}.$$

$$\eta = \sqrt{\frac{\log N}{tk}}, \quad \bar{R}_n \leq 2\sqrt{nk \log N}.$$

## Infinite comparison classes

More interesting cases allow the comparison class  $\Pi$  to be infinite. For instance, for  $\mathcal{X} \subseteq \mathbb{R}^d$ , we might consider linear threshold functions,

$$\pi(x) = \arg \max_{j \in \{1, \dots, k\}} x' \theta_j,$$

where  $\theta_1, \dots, \theta_k$  are parameter vectors. Or linear threshold functions defined in terms of features of  $x$  and  $j \in \mathcal{A}$ ,

$$\pi(x) = \arg \max_{j \in \mathcal{A}} \phi(x, j)' \theta.$$

Or a probabilistic version,  $\pi : \mathcal{X} \rightarrow \Delta_{\mathcal{A}}$ ,

$$\pi(j|x) = \frac{\exp(\phi(x, j)' \theta)}{\sum_i \exp(\phi(x, i)' \theta)}.$$

(Or decision trees, or ...)

## Infinite comparison classes

Exp4 cannot be applied to an infinite  $\Pi$  for computational (can't maintain the  $q_t$  distribution) and statistical ( $\log |\Pi| = \infty$ ) reasons.

But the cardinality of  $\Pi$  might not capture its complexity. A smaller class might be essentially the same. Consider the following approach:

1. Construct a finite approximation  $\hat{\Pi}$  to  $\Pi$ .
2. Use Exp4 on  $\hat{\Pi}$ .

## Infinite comparison classes

Consider an i.i.d. stochastic model:  $(X_t, Y_t) \sim P$ .

Suppose the approximation is such that, for every  $\pi \in \Pi$ , there is a  $\hat{\pi} \in \Pi$  with

$$\Pr(\pi(X_t) \neq \hat{\pi}(X_t)) \leq \epsilon,$$

then for  $Y \in [0, 1]$ ,

$$\mathbb{E} |Y_{\pi(X_t), t} - Y_{\hat{\pi}(X_t), t}| \leq \epsilon.$$

## Infinite comparison classes

$$\begin{aligned}
 \bar{R}_n(\Pi) &= \sup_{\pi \in \Pi} \mathbb{E} \sum_{t=1}^n Y_{\pi(X_t),t} - \mathbb{E} \sum_{t=1}^n Y_{I_t,t} \\
 &= \sup_{\pi \in \Pi} \mathbb{E} \sum_{t=1}^n Y_{\pi(X_t),t} - \sup_{\hat{\pi} \in \hat{\Pi}} \mathbb{E} \sum_{t=1}^n Y_{\hat{\pi}(X_t),t} \\
 &\quad + \sup_{\hat{\pi} \in \hat{\Pi}} \mathbb{E} \sum_{t=1}^n Y_{\hat{\pi}(X_t),t} - \mathbb{E} \sum_{t=1}^n Y_{I_t,t} \\
 &= \sup_{\pi \in \Pi} \inf_{\hat{\pi} \in \hat{\Pi}} \mathbb{E} \sum_{t=1}^n (Y_{\pi(X_t),t} - Y_{\hat{\pi}(X_t),t}) \\
 &\quad + \sup_{\hat{\pi} \in \hat{\Pi}} \mathbb{E} \sum_{t=1}^n Y_{\hat{\pi}(X_t),t} - \mathbb{E} \sum_{t=1}^n Y_{I_t,t} \\
 &\leq n\epsilon + \bar{R}_n(\hat{\Pi}).
 \end{aligned}$$

## Infinite comparison classes

A set  $\hat{\Pi}$  that can  $\epsilon$ -approximate  $\Pi$  in this way is called an  $\epsilon$ -cover of  $\Pi$  in the pseudometric

$$\rho(\hat{\pi}, \pi) = \Pr(\pi(X_t) \neq \hat{\pi}(X_t)).$$

The cardinality of the smallest  $\epsilon$ -cover of  $\Pi$  is called its  $\epsilon$ -covering number, and denoted  $\mathcal{N}_{\Pi}(\epsilon)$ .

## Infinite comparison classes

**Theorem:** Under the i.i.d. stochastic model:  $(X_t, Y_t) \sim P$ , strategy Exp4 on the class  $\hat{\Pi}$ , which is a minimal  $\epsilon$ -cover of  $\Pi$ , where  $\epsilon$  is chosen to minimize

$$\epsilon + \sqrt{\frac{2k \log \mathcal{N}_{\Pi}(\epsilon)}{n}},$$

gives pseudo-regret

$$\bar{R}_n \leq n \min_{\epsilon \geq 0} \left( \epsilon + \sqrt{\frac{2k \log \mathcal{N}_{\Pi}(\epsilon)}{n}} \right).$$

## Infinite comparison classes

How could we construct an  $\epsilon$ -cover  $\hat{\Pi}$  of  $\Pi$ ?

If  $\Pi$  is a parametric class,  $\Pi = \{\pi_\theta : \theta \in \Theta\}$ , where, for all  $x \in \mathcal{X}$ , the map  $\theta \rightarrow \pi_\theta(x)$  is a Lipschitz map:  $\rho(\pi_\theta, \pi_{\theta'}) \leq c \|\theta - \theta'\|$ , and  $\Theta$  is compact, then we can construct an  $(\epsilon/c)$ -cover  $\hat{\Theta}$  of  $\Theta$ , and define

$$\hat{\Pi} = \left\{ \pi_{\hat{\theta}} : \hat{\theta} \in \hat{\Theta} \right\}.$$

(For instance, consider the parameterized class

$$\pi_\theta(j|x) = \frac{\exp(\phi(x, j)' \theta)}{\sum_i \exp(\phi(x, i)' \theta)}$$

with bounded features  $\phi$  and bounded parameters  $\theta$ .)

## Infinite comparison classes

Another example: Suppose that the *shattering coefficient*

$$S_{\Pi}(n) := \max_{x_1, \dots, x_n \in \mathcal{X}} |\{(\pi(x_1), \dots, \pi(x_n)) : \pi \in \Pi\}|$$

grows slowly with  $n$  (much slower than exponential in  $n$ ). Then we can use that to build a small cover.

High level idea:

1. Gather some data  $X_1, \dots, X_m$  (making arbitrary decisions  $I_t$ ),
2. Construct  $\hat{\Pi}$  containing one representative for each element of  $\{(\pi(X_1), \dots, \pi(X_m)) : \pi \in \Pi\}$ . (So that  $|\hat{\Pi}| \leq S_{\Pi}(m)$ .)
3. Use Exp4 with  $\hat{\Pi}$ .

## **Infinite comparison classes**

**Theorem:** Under the i.i.d. stochastic model:  $(X_t, Y_t) \sim P$ , with probability  $1 - \delta$ , the  $\hat{\Pi}$  constructed in this way is an  $\epsilon$ -cover for  $\Pi$  of size no more than  $S_{\Pi}(m)$ , for

$$\epsilon = \frac{2}{m} \log_2 \left( \frac{2S_{\Pi}(2m)^2}{\delta} \right).$$

Thus, the pseudo-regret of this strategy satisfies

$$\bar{R}_n \leq m + (n - m)\delta + (n - m)\epsilon + \sqrt{2(n - m)k \log(S_{\Pi}(m))}.$$

If  $S_{\Pi}(m) = O((m/d)^d)$ , setting  $m = \sqrt{nd \log(n/d)}$  and  $\delta = m/n$  gives

$$\bar{R}_n = O \left( \sqrt{nk d \log \frac{n}{d}} \right).$$

## Infinite comparison classes

A symmetrization idea due to Vapnik and Chervonenkis, plus a simple counting argument shows that  $\hat{\Pi}$  is an  $\epsilon$ -cover:

**Lemma:** Given i.i.d. data  $D_n = \{X_1, \dots, X_n\}$ , and a set  $\mathcal{E}$  of events in  $\mathcal{X}$ ,

$$P^n (\exists E \in \mathcal{E}, D \cap E = \emptyset, P(E) \geq \epsilon) \leq 2S_{\mathcal{E}}(2n)2^{-\epsilon n/2},$$

where  $S_{\mathcal{E}}(n)$  is the shattering coefficient of  $\{1_E : E \in \mathcal{E}\}$ .

Defining  $\mathcal{E} = \{\{x : \pi(x) = \hat{\pi}(x)\} : (\pi, \hat{\pi}) \in \Pi^2\}$ , we have, with probability at least  $1 - \delta$  over  $D_m$ , the initial  $m$ -sample, for every  $\pi \in \Pi$  there is a  $\hat{\pi} \in \hat{\Pi}$  (the one that equals  $\pi$  on  $D_m$ ) with  $\Pr(\pi(X) \neq \hat{\pi}(X)) \leq \epsilon$ , that is,  $\hat{\Pi}$  is an  $\epsilon$ -cover for  $\Pi$ .

## Infinite comparison classes

When does  $S_{\Pi}(n)$  grow slowly with  $n$ ?

**Definition:** A class  $\Pi \subseteq \{0, 1\}^{\mathcal{X}}$  **shatters**  $\{x_1, \dots, x_d\} \subseteq \mathcal{X}$  means that  $|\Pi(x_1^d)| = 2^d$ .

The Vapnik-Chervonenkis dimension of  $\Pi$  is

$$\begin{aligned} d_{VC}(\Pi) &= \max \{d : \text{some } x_1, \dots, x_d \in \mathcal{X} \text{ is shattered by } \Pi\} \\ &= \max \{d : S_{\Pi}(d) = 2^d\}. \end{aligned}$$

## Vapnik-Chervonenkis dimension: “Sauer’s Lemma”

**Theorem:** [Vapnik-Chervonenkis]  $d_{VC}(F) \leq d$  implies

$$S_{\Pi}(n) \leq \sum_{i=0}^d \binom{n}{i}.$$

If  $n \geq d$ , the latter sum is no more than  $\left(\frac{en}{d}\right)^d$ .

So the VC-dimension is a single integer summary of the shatter coefficients: either it is finite, and  $S_{\Pi}(n) = O(n^d)$ , or  $S_{\Pi}(n) = 2^n$ . No other growth is possible.

$$S_{\Pi}(n) \begin{cases} = 2^n & \text{if } n \leq d, \\ \leq (e/d)^d n^d & \text{if } n > d. \end{cases}$$

## Vapnik-Chervonenkis dimension: “Sauer’s Lemma”

Stronger than this: finiteness of the VC-dimension is necessary. If the VC-dimension is infinite, then there are distributions for which competing with  $\Pi$ , even in the full information case, is impossible: for every strategy, there is a probability distribution such that with high probability, the regret grows linearly.

(And it’s the same story for  $k$ -valued functions, modulo  $\log k$  factors.)

## VC-dimension bounds for parameterized families

Consider a parameterized class of  $k$ -valued functions,

$$\Pi = \{x \mapsto f(x, \theta) : \theta \in \mathbb{R}^p\},$$

where  $f : \mathbb{R}^m \times \mathbb{R}^p \rightarrow \{1, \dots, k\}$ .

Suppose that  $f$  can be computed using no more than  $t$  operations of the following kinds:

1. arithmetic ( $+$ ,  $-$ ,  $\times$ ,  $/$ ),
2. comparisons ( $>$ ,  $=$ ,  $<$ ),
3. output a constant in  $\{1, \dots, k\}$

**Theorem:**  $d_{VC}(F) = O(pt \log k)$ .

(And a similar story applies, with a worse dependence on  $t$ , if we include the exponential function in the set of operations.)

## Summary: Infinite comparison classes

Competing with infinite  $\Pi \subseteq \{1, \dots, k\}^{\mathcal{X}}$ :

- If we want to compete with an infinite  $\Pi$  for all distributions on  $\mathcal{X} \times [0, 1]^k$ ,  $S_{\Pi}(n)$  must have polynomial growth, say  $O(n^d)$ .
- We can use i.i.d. data to build an  $\epsilon$ -cover of  $\Pi$  of size  $O(S_{\Pi}(n)) = O(n^d)$ .
- Running Exp4 with this class of experts gives regret

$$\bar{R}_n = O\left(\sqrt{nk d \log n}\right).$$

- The drawback is *computational*:  $S_{\Pi}(n)$  is polynomial in  $n$ , but exponential in the dimension  $d$ . For example, for

$$\pi(x) = \arg \max_{j \in \mathcal{A}} \phi(x, j)' \theta,$$

the computation grows exponentially with the number of features.