

Introduction to Time Series Analysis. Lecture 17.

1. Review: Spectral distribution function, spectral density.
2. Rational spectra. Poles and zeros.
3. Examples.
4. Time-invariant linear filters
5. Frequency response

Review: Spectral density and spectral distribution function

If a time series $\{X_t\}$ has autocovariance γ satisfying $\sum_{h=-\infty}^{\infty} |\gamma(h)| < \infty$, then we define its **spectral density** as

$$f(\nu) = \sum_{h=-\infty}^{\infty} \gamma(h) e^{-2\pi i \nu h}$$

for $-\infty < \nu < \infty$. We have

$$\gamma(h) = \int_{-1/2}^{1/2} e^{2\pi i \nu h} f(\nu) d\nu = \int_{-1/2}^{1/2} e^{2\pi i \nu h} dF(\nu),$$

where $dF(\nu) = f(\nu) d\nu$.

f measures how the variance of X_t is distributed across the spectrum.

Review: Spectral density of a linear process

If X_t is a linear process, it can be written $X_t = \sum_{i=0}^{\infty} \psi_i W_{t-i} = \psi(B)W_t$.
Then

$$f(\nu) = \sigma_w^2 |\psi(e^{-2\pi i\nu})|^2.$$

That is, the spectral density $f(\nu)$ of a linear process measures the modulus of the ψ (MA(∞)) polynomial at the point $e^{2\pi i\nu}$ on the unit circle.

Spectral density of a linear process

For an ARMA(p,q), $\psi(B) = \theta(B)/\phi(B)$, so

$$\begin{aligned} f(\nu) &= \sigma_w^2 \frac{\theta(e^{-2\pi i\nu})\theta(e^{2\pi i\nu})}{\phi(e^{-2\pi i\nu})\phi(e^{2\pi i\nu})} \\ &= \sigma_w^2 \left| \frac{\theta(e^{-2\pi i\nu})}{\phi(e^{-2\pi i\nu})} \right|^2. \end{aligned}$$

This is known as a *rational spectrum*.

Rational spectra

Consider the factorization of θ and ϕ as

$$\begin{aligned}\theta(z) &= \theta_q (z - z_1)(z - z_2) \cdots (z - z_q) \\ \phi(z) &= \phi_p (z - p_1)(z - p_2) \cdots (z - p_p),\end{aligned}$$

where z_1, \dots, z_q and p_1, \dots, p_p are called the *zeros* and *poles*.

$$\begin{aligned}f(\nu) &= \sigma_w^2 \left| \frac{\theta_q \prod_{j=1}^q (e^{-2\pi i\nu} - z_j)}{\phi_p \prod_{j=1}^p (e^{-2\pi i\nu} - p_j)} \right|^2 \\ &= \sigma_w^2 \frac{\theta_q^2 \prod_{j=1}^q |e^{-2\pi i\nu} - z_j|^2}{\phi_p^2 \prod_{j=1}^p |e^{-2\pi i\nu} - p_j|^2}.\end{aligned}$$

Rational spectra

$$f(\nu) = \sigma_w^2 \frac{\theta_q^2 \prod_{j=1}^q |e^{-2\pi i\nu} - z_j|^2}{\phi_p^2 \prod_{j=1}^p |e^{-2\pi i\nu} - p_j|^2}.$$

As ν varies from 0 to $1/2$, $e^{-2\pi i\nu}$ moves clockwise around the unit circle from 1 to $e^{-\pi i} = -1$.

And the value of $f(\nu)$ goes up as this point moves closer to (further from) the poles p_j (zeros z_j).

Example: ARMA

Recall AR(1): $\phi(z) = 1 - \phi_1 z$. The pole is at $1/\phi_1$. If $\phi_1 > 0$, the pole is to the right of 1, so the spectral density decreases as ν moves away from 0. If $\phi_1 < 0$, the pole is to the left of -1 , so the spectral density is at its maximum when $\nu = 0.5$.

Recall MA(1): $\theta(z) = 1 + \theta_1 z$. The zero is at $-1/\theta_1$. If $\theta_1 > 0$, the zero is to the left of -1 , so the spectral density decreases as ν moves towards -1 . If $\theta_1 < 0$, the zero is to the right of 1, so the spectral density is at its minimum when $\nu = 0$.

Example: AR(2)

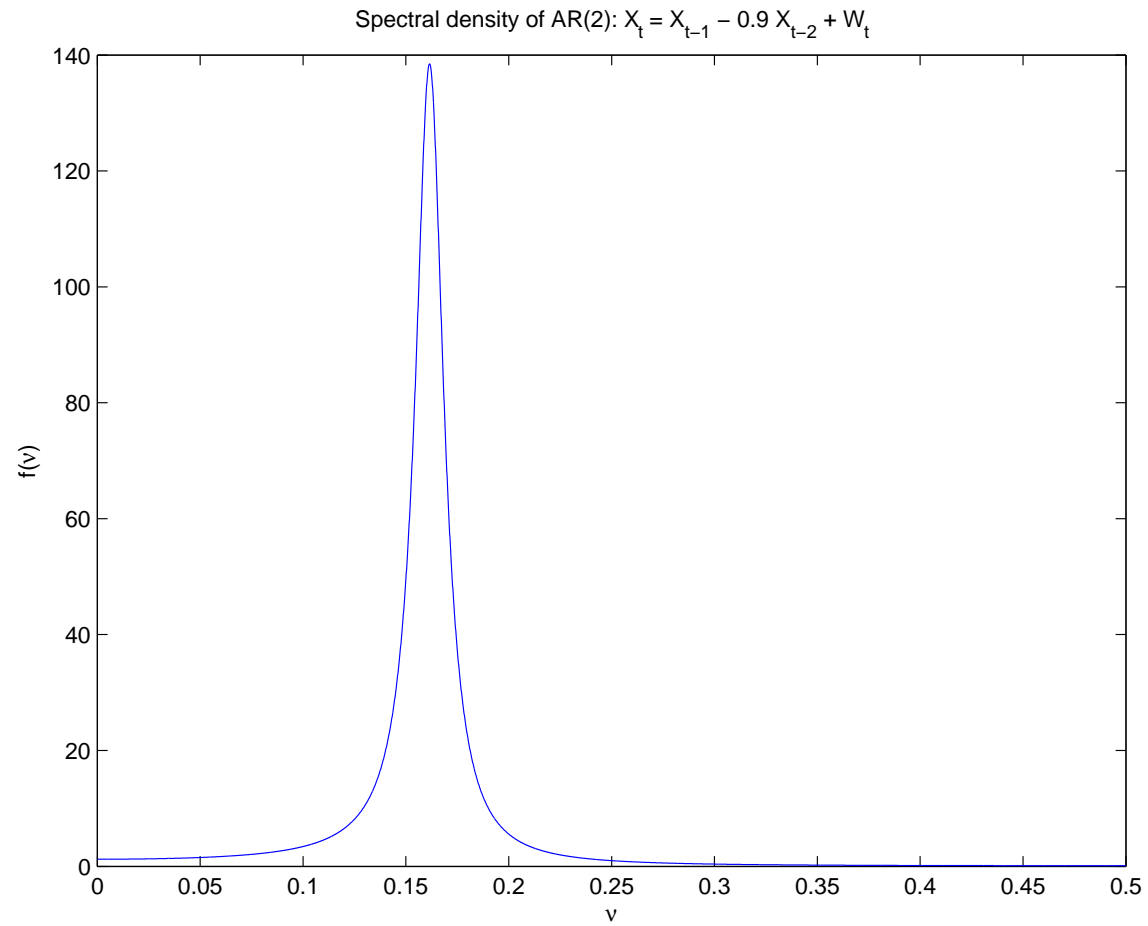
Consider $X_t = \phi_1 X_{t-1} + \phi_2 X_{t-2} + W_t$. Example 4.6 in the text considers this model with $\phi_1 = 1$, $\phi_2 = -0.9$, and $\sigma_w^2 = 1$. In this case, the poles are at $p_1, p_2 \approx 0.5555 \pm i0.8958 \approx 1.054e^{\pm i1.01567} \approx 1.054e^{\pm 2\pi i0.16165}$.

Thus, we have

$$f(\nu) = \frac{\sigma_w^2}{\phi_2^2 |e^{-2\pi i\nu} - p_1|^2 |e^{-2\pi i\nu} - p_2|^2},$$

and this gets very peaked when $e^{-2\pi i\nu}$ passes near $1.054e^{-2\pi i0.16165}$.

Example: AR(2)



Example: Seasonal ARMA

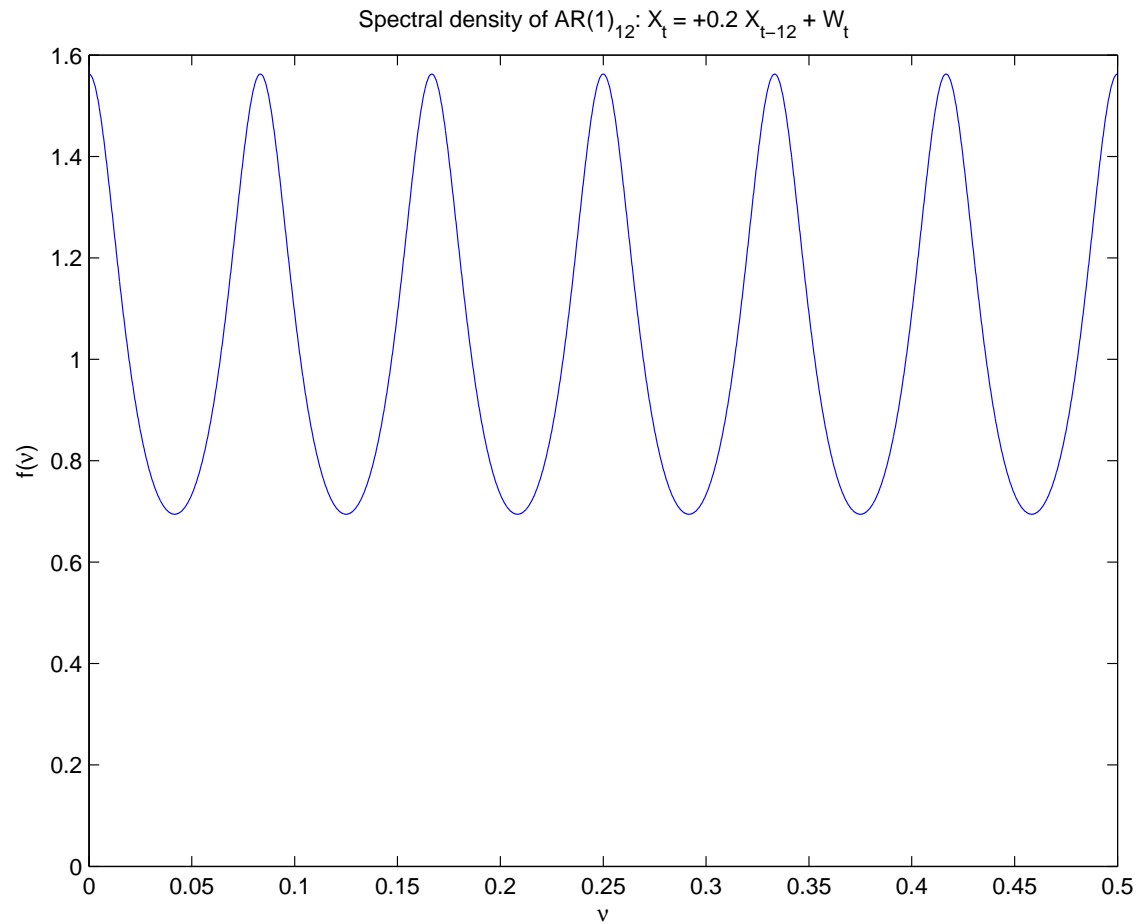
Consider $X_t = \Phi_1 X_{t-12} + W_t$.

$$\psi(B) = \frac{1}{1 - \Phi_1 B^{12}},$$

$$\begin{aligned} f(\nu) &= \sigma_w^2 \frac{1}{(1 - \Phi_1 e^{-2\pi i 12\nu})(1 - \Phi_1 e^{2\pi i 12\nu})} \\ &= \sigma_w^2 \frac{1}{1 - 2\Phi_1 \cos(24\pi\nu) + \Phi_1^2}. \end{aligned}$$

Notice that $f(\nu)$ is periodic with period $1/12$.

Example: Seasonal ARMA



Example: Seasonal ARMA

Another view:

$$1 - \Phi_1 z^{12} = 0 \quad \Leftrightarrow \quad z = r e^{i\theta},$$

$$\text{with} \quad r = |\Phi_1|^{-1/12}, \quad e^{i12\theta} = e^{-i \arg(\Phi_1)}.$$

For $\Phi_1 > 0$, the twelve poles are at $|\Phi_1|^{-1/12} e^{ik\pi/6}$ for $k = 0, \pm 1, \dots, \pm 5, 6$.

So the spectral density gets peaked as $e^{-2\pi i\nu}$ passes near $|\Phi_1|^{-1/12} \times \{1, e^{-i\pi/6}, e^{-i\pi/3}, e^{-i\pi/2}, e^{-i2\pi/3}, e^{-i5\pi/6}, -1\}$.

Example: Multiplicative seasonal ARMA

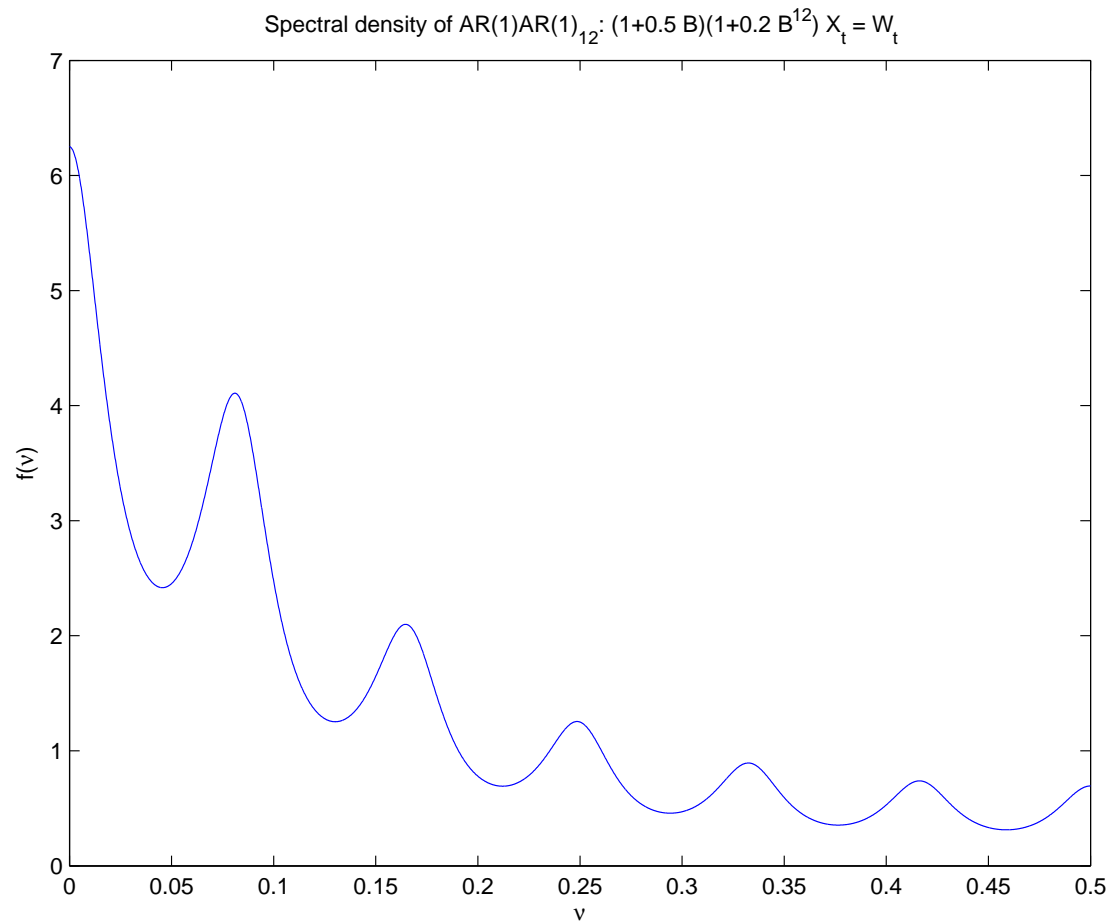
Consider $(1 - \Phi_1 B^{12})(1 - \phi_1 B)X_t = W_t$.

$$f(\nu) = \sigma_w^2 \frac{1}{(1 - 2\Phi_1 \cos(24\pi\nu) + \Phi_1^2)(1 - 2\phi_1 \cos(2\pi\nu) + \phi_1^2)}.$$

This is a scaled product of the AR(1) spectrum and the (periodic) AR(1)₁₂ spectrum.

The AR(1)₁₂ poles give peaks when $e^{-2\pi i\nu}$ is at one of the 12th roots of 1; the AR(1) poles give a peak near $e^{-2\pi i\nu} = 1$.

Example: Multiplicative seasonal ARMA



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Time-invariant linear filters

A filter is an operator; given a time series $\{X_t\}$, it maps to a time series $\{Y_t\}$. We can think of a linear process $X_t = \sum_{j=0}^{\infty} \psi_j W_{t-j}$ as the output of a *causal linear filter* with a white noise input.

A time series $\{Y_t\}$ is the output of a linear filter $A = \{a_{t,j} : t, j \in \mathbb{Z}\}$ with input $\{X_t\}$ if

$$Y_t = \sum_{j=-\infty}^{\infty} a_{t,j} X_j.$$

If $a_{t,t-j}$ is independent of t ($a_{t,t-j} = \psi_j$), then we say that the filter is *time-invariant*.

If $\psi_j = 0$ for $j < 0$, we say the filter ψ is *causal*.

We'll see that the name 'filter' arises from the frequency domain viewpoint.

Time-invariant linear filters: Examples

1. $Y_t = X_{-t}$ is linear, but not time-invariant.
2. $Y_t = \frac{1}{3}(X_{t-1} + X_t + X_{t+1})$ is linear, time-invariant, but not causal:

$$\psi_j = \begin{cases} \frac{1}{3} & \text{if } |j| \leq 1, \\ 0 & \text{otherwise.} \end{cases}$$

3. For polynomials $\phi(B), \theta(B)$ with roots outside the unit circle, $\psi(B) = \theta(B)/\phi(B)$ is a linear, time-invariant, causal filter.

Time-invariant linear filters

The operation

$$\sum_{j=-\infty}^{\infty} \psi_j X_{t-j}$$

is called the *convolution* of X with ψ .

Time-invariant linear filters

The sequence ψ is also called the *impulse response*, since the output $\{Y_t\}$ of the linear filter in response to a *unit impulse*,

$$X_t = \begin{cases} 1 & \text{if } t = 0, \\ 0 & \text{otherwise,} \end{cases}$$

is

$$Y_t = \psi(B)X_t = \sum_{j=-\infty}^{\infty} \psi_j X_{t-j} = \psi_t.$$

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Frequency response of a time-invariant linear filter

Suppose that $\{X_t\}$ has spectral density $f_x(\nu)$ and ψ is *stable*, that is, $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$. Then $Y_t = \psi(B)X_t$ has spectral density

$$f_y(\nu) = |\psi(e^{2\pi i\nu})|^2 f_x(\nu).$$

The function $\nu \mapsto \psi(e^{2\pi i\nu})$ (the polynomial $\psi(z)$ evaluated on the unit circle) is known as the *frequency response* or *transfer function* of the linear filter.

The squared modulus, $\nu \mapsto |\psi(e^{2\pi i\nu})|^2$ is known as the *power transfer function* of the filter.

Frequency response of a time-invariant linear filter

For stable ψ , $Y_t = \psi(B)X_t$ has spectral density

$$f_y(\nu) = |\psi(e^{2\pi i\nu})|^2 f_x(\nu).$$

We have seen that a linear process, $Y_t = \psi(B)W_t$, is a special case, since $f_y(\nu) = |\psi(e^{2\pi i\nu})|^2 \sigma_w^2 = |\psi(e^{2\pi i\nu})|^2 f_w(\nu)$.

When we pass a time series $\{X_t\}$ through a linear filter, the spectral density is multiplied, frequency-by-frequency, by the squared modulus of the frequency response $\nu \mapsto |\psi(e^{2\pi i\nu})|^2$.

This is a version of the equality $\text{Var}(aX) = a^2 \text{Var}(X)$, but the equality is true for the component of the variance at every frequency.

This is also the origin of the name ‘filter.’

Frequency response of a filter: Details

Why is $f_y(\nu) = |\psi(e^{2\pi i\nu})|^2 f_x(\nu)$? First,

$$\begin{aligned} \gamma_y(h) &= \mathbf{E} \left[\sum_{j=-\infty}^{\infty} \psi_j X_{t-j} \sum_{k=-\infty}^{\infty} \psi_k X_{t+h-k} \right] \\ &= \sum_{j=-\infty}^{\infty} \psi_j \sum_{k=-\infty}^{\infty} \psi_k \mathbf{E} [X_{t+h-k} X_{t-j}] \\ &= \sum_{j=-\infty}^{\infty} \psi_j \sum_{k=-\infty}^{\infty} \psi_k \gamma_x(h + j - k) = \sum_{j=-\infty}^{\infty} \psi_j \sum_{l=-\infty}^{\infty} \psi_{h+j-l} \gamma_x(l). \end{aligned}$$

It is easy to check that $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$ and $\sum_{h=-\infty}^{\infty} |\gamma_x(h)| < \infty$ imply that $\sum_{h=-\infty}^{\infty} |\gamma_y(h)| < \infty$. Thus, the spectral density of y is defined.

Frequency response of a filter: Details

$$\begin{aligned} f_y(\nu) &= \sum_{h=-\infty}^{\infty} \gamma(h) e^{-2\pi i \nu h} \\ &= \sum_{h=-\infty}^{\infty} \sum_{j=-\infty}^{\infty} \psi_j \sum_{l=-\infty}^{\infty} \psi_{h+j-l} \gamma_x(l) e^{-2\pi i \nu h} \\ &= \sum_{j=-\infty}^{\infty} \psi_j e^{2\pi i \nu j} \sum_{l=-\infty}^{\infty} \gamma_x(l) e^{-2\pi i \nu l} \sum_{h=-\infty}^{\infty} \psi_{h+j-l} e^{-2\pi i \nu (h+j-l)} \\ &= \psi(e^{2\pi i \nu j}) f_x(\nu) \sum_{h=-\infty}^{\infty} \psi_h e^{-2\pi i \nu h} \\ &= |\psi(e^{2\pi i \nu j})|^2 f_x(\nu). \end{aligned}$$

Frequency response: Examples

For a linear process $Y_t = \psi(B)W_t$, $f_y(\nu) = |\psi(e^{2\pi i\nu})|^2 \sigma_w^2$.

For an ARMA model, $\psi(B) = \theta(B)/\phi(B)$, so $\{Y_t\}$ has the rational spectrum

$$\begin{aligned} f_y(\nu) &= \sigma_w^2 \left| \frac{\theta(e^{-2\pi i\nu})}{\phi(e^{-2\pi i\nu})} \right|^2 \\ &= \sigma_w^2 \frac{\theta_q^2 \prod_{j=1}^q |e^{-2\pi i\nu} - z_j|^2}{\phi_p^2 \prod_{j=1}^p |e^{-2\pi i\nu} - p_j|^2}, \end{aligned}$$

where p_j and z_j are the poles and zeros of the rational function $z \mapsto \theta(z)/\phi(z)$.

Frequency response: Examples

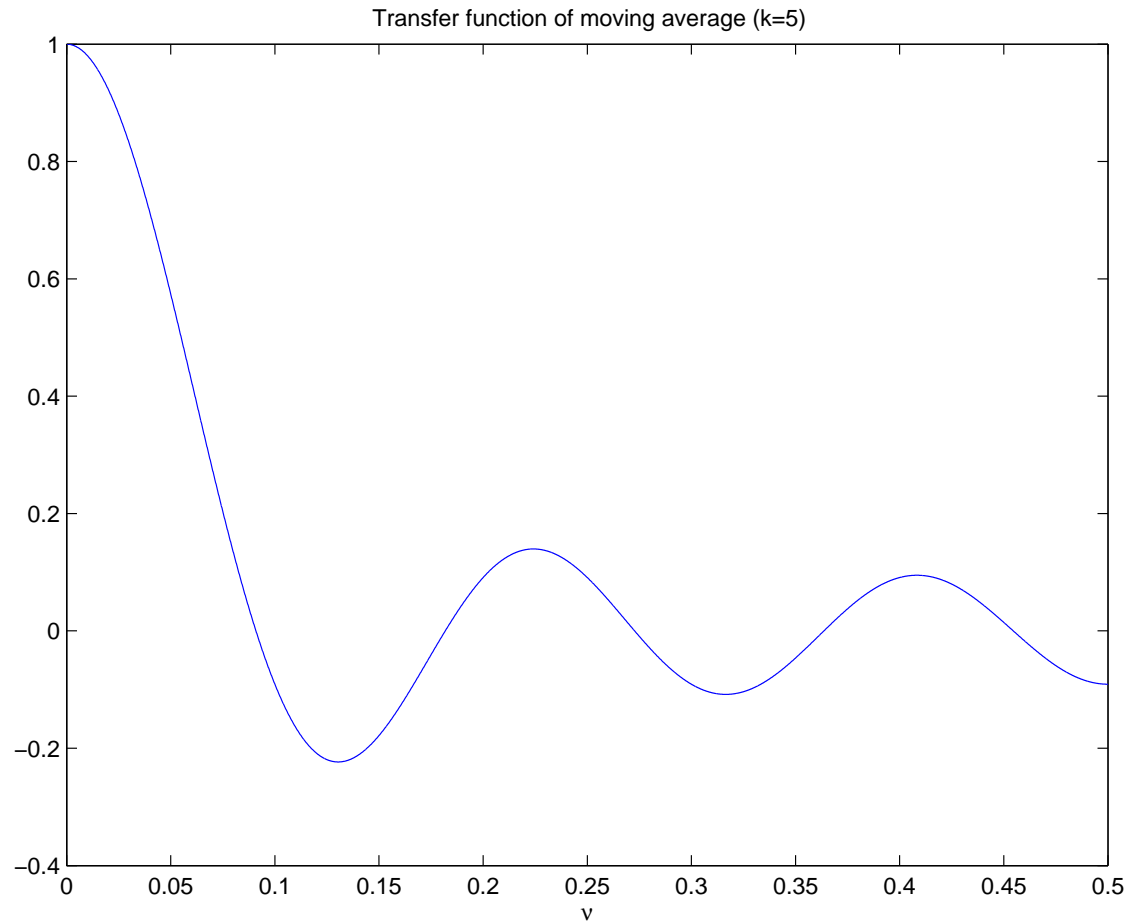
Consider the moving average

$$Y_t = \frac{1}{2k+1} \sum_{j=-k}^k X_{t-j}.$$

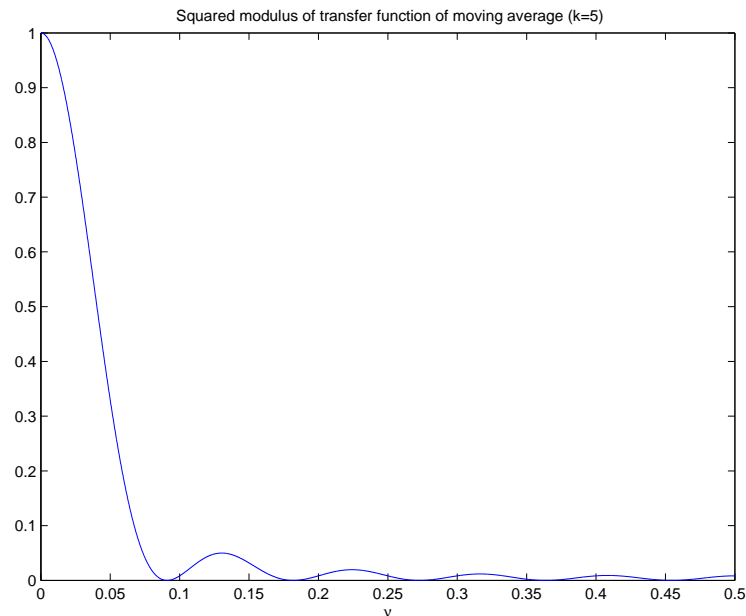
This is a time invariant linear filter (but it is not causal). Its transfer function is the Dirichlet kernel

$$\begin{aligned} \psi(e^{-2\pi i\nu}) &= D_k(2\pi\nu) = \frac{1}{2k+1} \sum_{j=-k}^k e^{-2\pi i j \nu} \\ &= \begin{cases} 1 & \text{if } \nu = 0, \\ \frac{\sin(2\pi(k+1/2)\nu)}{(2k+1)\sin(\pi\nu)} & \text{otherwise.} \end{cases} \end{aligned}$$

Example: Moving average



Example: Moving average



This is a *low-pass filter*: It preserves low frequencies and diminishes high frequencies. It is often used to estimate a monotonic trend component of a series.

Example: Differencing

Consider the first difference

$$Y_t = (1 - B)X_t.$$

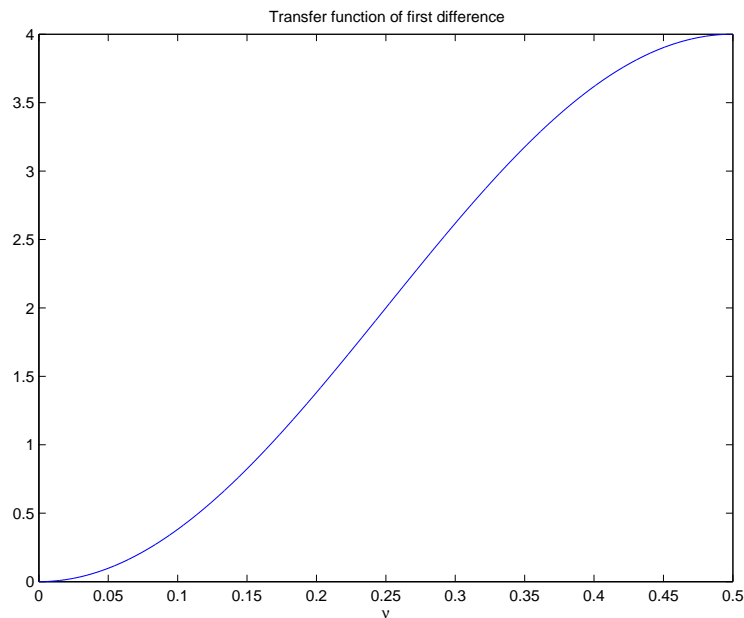
This is a time invariant, causal, linear filter.

Its transfer function is

$$\psi(e^{-2\pi i\nu}) = 1 - e^{-2\pi i\nu},$$

so
$$|\psi(e^{-2\pi i\nu})|^2 = 2(1 - \cos(2\pi\nu)).$$

Example: Differencing



This is a *high-pass filter*: It preserves high frequencies and diminishes low frequencies. It is often used to eliminate a trend component of a series.

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