Statistics 210B, Spring 1998 Class Notes

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Eigth Set of Notes

1 Application of linear programming

Density estimation with shape restrictions. (See Hengartner and Stark, 1995. Finite-sample confidence envelopes for shape-restricted densities, Ann. Stat., 23, 525-550.) Suppose we observe $\mathbf{X} = \{X_j\}_{j=1}^n$ i.i.d. F, where F is a distribution with a density f w.r.t. Lebesgue measure, $\sup \{F\} \subset \mathbf{R}^+$, and f is monotone decreasing on \mathbf{R}^+ . We seek a confidence interval for $f(x_0)$ for some $x_0 \geq 0$. Let F denote not only the distribution (measure), but also the cdf of the measure: $F(x) = F((-\infty, x])$. Let \mathcal{P} be the set of probability measures on \mathbf{R}^+ , and let \mathcal{Q} be the set of subprobability measures on \mathbf{R}^+ . For any measure $G \in \mathcal{Q}$, define the Kolmogorov-Smirnov (K-S) norm

$$\|G\| \equiv \sup_{x \in \mathbf{R}} |G((-\infty, x])| = \sup_{x \in \mathbf{R}} |G(x)|.$$
(1)

Let \hat{F}_n be the empirical measure corresponding to the cdf

$$\hat{F}_n(x) \equiv \frac{1}{n} \# \{ X_j \le x \},\tag{2}$$

and let

$$\chi = \chi_n(\alpha) = \sqrt{\frac{\ln \frac{2}{\alpha}}{2n}}.$$
(3)

Massart (The tight constant in the Dvoretsky-Kiefer-Wolfowitz inequality, Ann. Prob., 18, 1269-1283, 1990.) shows that for all n,

$$\mathbf{P}_F\left\{\|F - \hat{F}_n\| > \chi\right\} \le \alpha.$$
(4)

Define

$$D = D_{\chi}^{\zeta} \equiv \{ G \in \mathcal{Q} : -\chi \le \hat{F}_n(x) - G(x) \le \zeta, \ \forall x \in \mathbf{R} \},$$
(5)

and $D_{\chi} = D_{\chi}^{\chi}$. Because of Massart's result,

$$\mathbf{P}_F\{D_\chi \ni F\} \ge 1 - \alpha. \tag{6}$$

Let C be those measures in \mathcal{X} whose densities are monotone decreasing on \mathbb{R}^+ . Then

$$\mathbf{P}_F\{C \cap D_\chi \ni F\} \ge 1 - \alpha. \tag{7}$$

Consider a fixed functional $T: \mathcal{X} \to \mathbf{R}$. We have

$$\mathbf{P}_F\{\inf_{G\in C\cap D_{\chi}} T(G) \le T(F) \le \sup_{G\in C\cap D_{\chi}} T(G)\} \ge 1 - \alpha;$$
(8)

that is, if we set

$$T^{-}(\mathbf{X}) = \inf_{G \in C \cap D_{\chi}} T(G)$$
(9)

and

$$T^{+}(\mathbf{X}) = \sup_{G \in C \cap D_{\chi}} T(G), \tag{10}$$

the interval $[T^-, T^+]$ is a $1 - \alpha$ confidence interval for T(F). For that matter, let A be an arbitrary index set, and let $\{T_\alpha\}_{\alpha \in A}$ be an arbitrary collection of functionals on \mathcal{X} . Then

$$\mathbf{P}_{F}\{[T_{\alpha}^{-}(\mathbf{X}), T_{\alpha}^{+}(\mathbf{X})] \ni T_{\alpha}(F) \forall \alpha \in A\} \ge 1 - \alpha;$$
(11)

that is, the simultaneous coverage probability for any collection of confidence intervals derived from the set $C \cap D_{\chi}$ is at least $1 - \alpha$. (We shall discuss simultaneous confidence intervals and multiplicity in hypothesis tests in greater detail presently.) Take T(G) = g(y), the value of the density g of the measure G at the point y. Let $T^+ = T^+(y) = \sup_{G \in C \cap D_{\chi}} g(y)$ and $T^- = T^-(y) \inf_{G \in C \cap D_{\chi}} g(y)$. Finding T^+ and T^- are infinite-dimensional linear programming problems.

In terms of the densities g, the problem of finding T^- is

$$\inf\{g(y): g \text{ is monotone, and } \forall x \in \mathbf{R}^+, g(x) \ge 0, \text{ and } -\chi \le \int_0^x g(u)du - \hat{F}_n(x) \le \chi\}.$$
(12)

The constraints are linear inequalities in g, and the objective functional is linear in g. The unknown is infinite-dimensional, and there are an infinite number of constraints.

It happens that these problems can be reduced exactly to finite-dimensional linear programs. Notice that the maximum vertical distance between G(x) and $\hat{F}_n(x)$ must occur at one of the data X_j . With probability one, the data $\{X_j\}$ are distinct, and the smallest datum is greater than zero. Wlog assume that the data are ordered such that $0 \leq X_1 < X_2 < \cdots < X_n < \infty$. Let N denote the number of elements in the set $\{0, y\} \cup \{X_j\}_{j=1}^n$. With probability one, N is either n + 1 or n + 2. For $j = 1, \ldots, N$, let y_j be the *j*th smallest element in the set $\{0, y\} \cup \{X_j\}_{j=1}^n$. For any density g(x), define $\tilde{g}^+(x)$ to be the left-continuous piecewise average of g on the intervals determined by $\{y_j\}$:

$$\tilde{g}^{+}(x) = \sum_{j=1}^{N-1} \mathbb{1}_{x \in [y_j, y_{j+1})} \frac{1}{y_{j+1} - y_j} \int_{y_j}^{y_{j+1}} g(u) du.$$
(13)

Then $\tilde{g}(x)$ is the density of a subprobability measure. Let \tilde{G} be the corresponding measure. If g(x) is monotone decreasing, so is $\tilde{g}(x)$, and $\|\tilde{G} - \hat{F}_n\|_{KS} = \|G - \hat{F}_n\|_{KS}$.