

Beyond the black box: Flexible programming of hierarchical modeling algorithms for BUGS- based models using NIMBLE

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<http://r-nimble.org>

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What do we want to do with hierarchical models?

1. Core algorithms

- MCMC
- Sequential Monte Carlo
- Laplace approximation
- Importance sampling
- Variational Bayes

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2. Different flavors of algorithms

- Many flavors of MCMC
- Gaussian quadrature
- Monte Carlo expectation maximization (MCEM)
- Kalman Filter
- Auxiliary particle filter
- Posterior predictive simulation
- Posterior re-weighting
- Data cloning
- Bridge sampling (normalizing constants)
- YOUR FAVORITE HERE
- YOUR NEW IDEA HERE

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3. Idea combinations

- Particle MCMC
- Particle Filter with replenishment
- MCMC/Laplace approximation
- Dozens of ideas in recent JRSSB/JCGS issues

What can a practitioner do with hierarchical models?

Two basic software designs:

1. Typical R package = Model family + 1 or more algorithms
 - GLMMs: lme4, MCMCglmm
 - GAMMs: mgcv
 - spatial models: spBayes, INLA

What can a practitioner do with hierarchical models?

Two basic software designs:

1. Typical R package = Model family + 1 or more algorithms

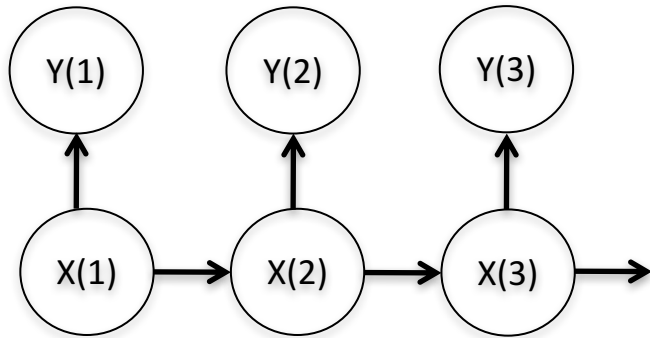
- GLMMs: lme4, MCMCglmm
- GAMMs: mgcv
- spatial models: spBayes, INLA

2. Flexible model + black box algorithm

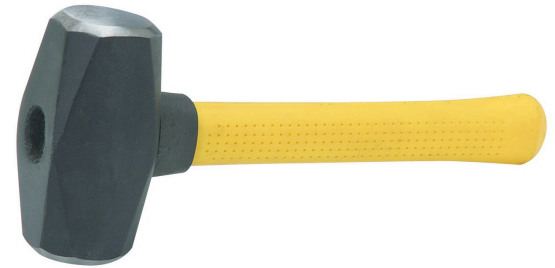
- BUGS: WinBUGS, OpenBUGS, JAGS
- PyMC
- INLA
- Stan

Existing software

Model



Algorithm

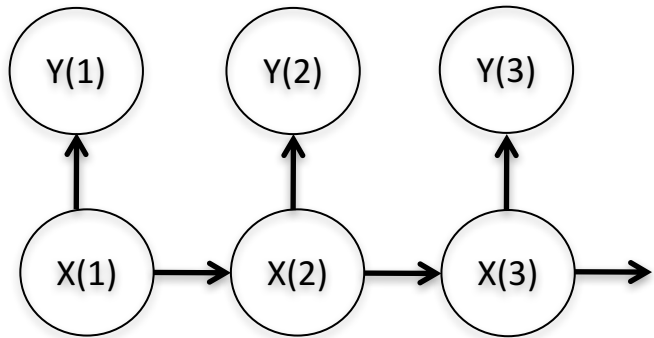


e.g., BUGS (WinBUGS, OpenBUGS, JAGS), INLA, Stan,
various R packages

NIMBLE: The Goal

Model

Algorithm language



+

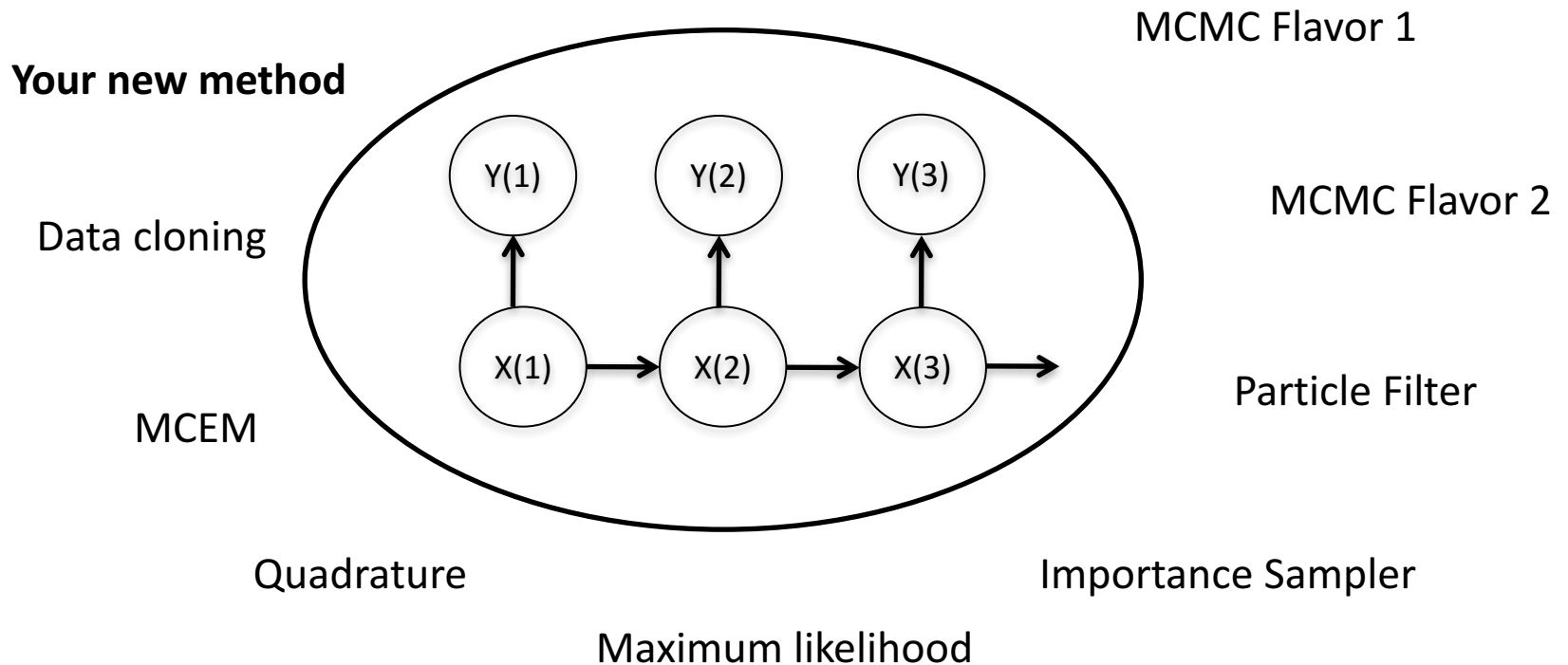


=



NIMBLE: extensible software for hierarchical models (r-nimble.org)

Divorcing Model Specification from Algorithm

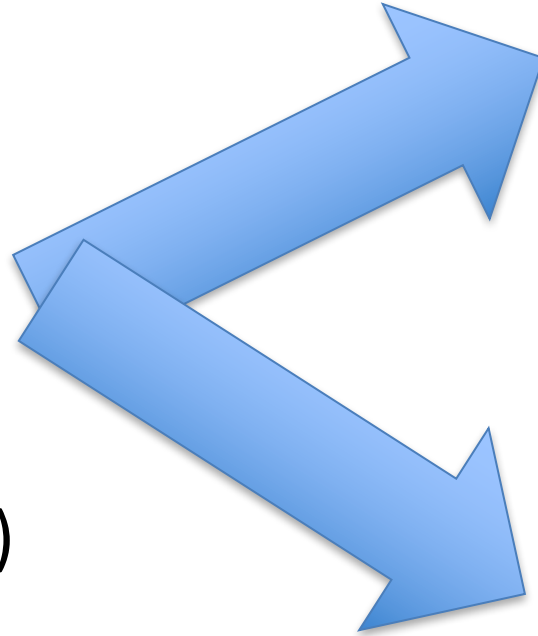


Goals

- Retaining BUGS compatibility
- Providing a variety of standard algorithms
- Allowing users to easily modify those algorithms
- **Allowing developers to add new algorithms (including modular combination of algorithms)**
- Allowing users to operate within R
- Providing speed via compilation to C++, with R wrappers

NIMBLE System Summary

statistical model
(BUGS code)
+
algorithm
(nimbleFunction)



R objects + R under the hood

R objects + C++ under the hood

- ✧ We generate C++ code,
- ✧ compile and load it,
- ✧ provide interface object.

NIMBLE

1. Model specification

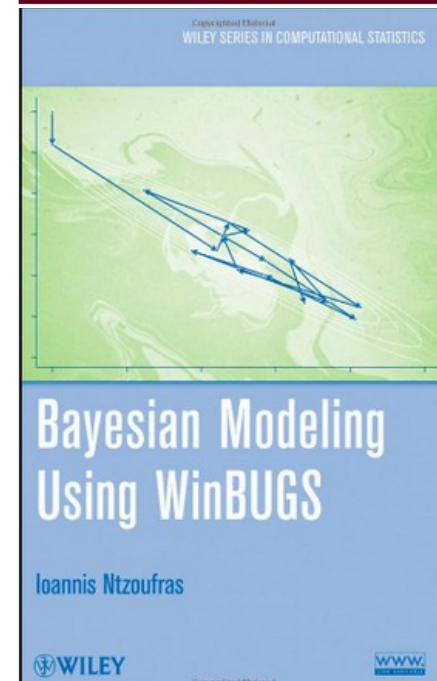
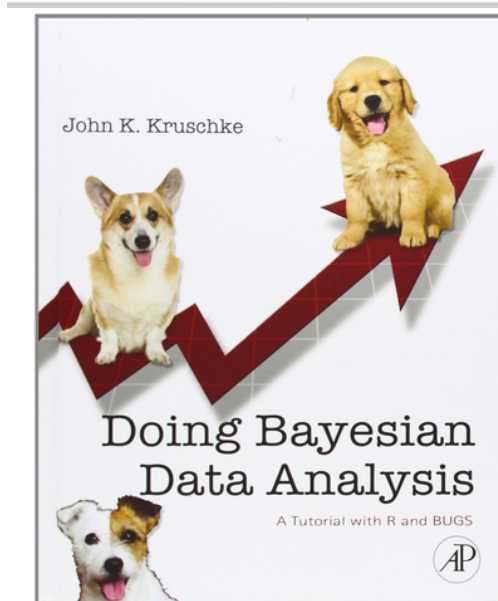
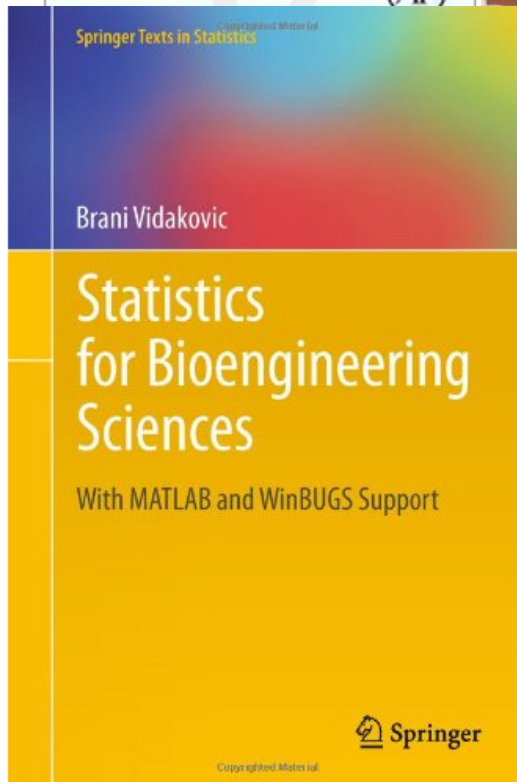
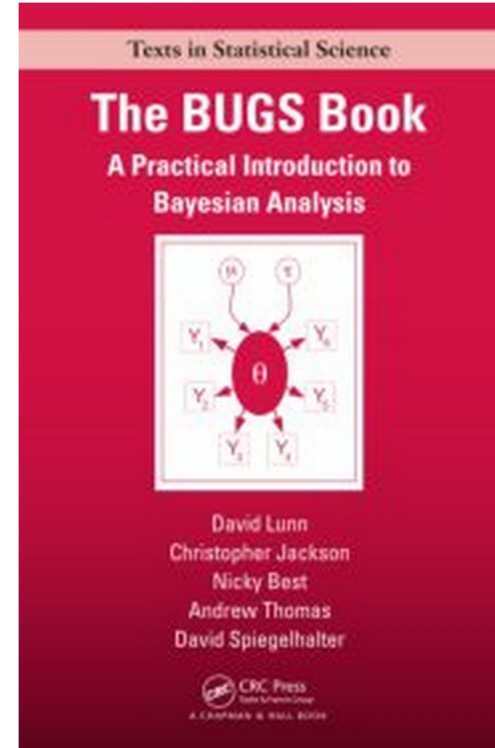
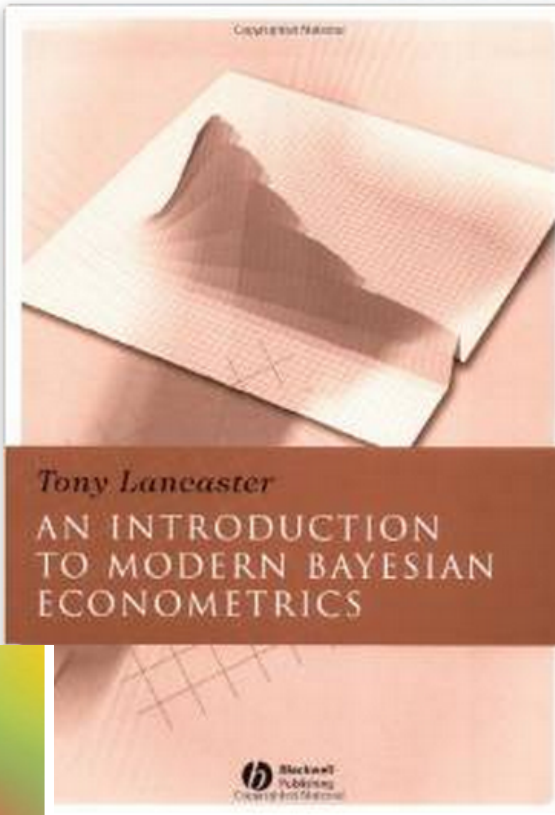
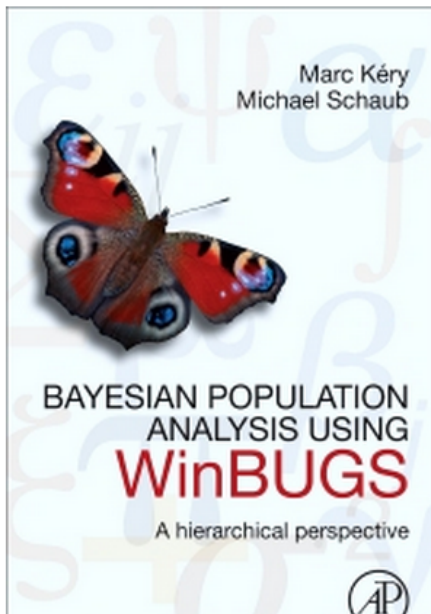
BUGS language → R/C++ model object

2. Algorithm library

MCMC, Particle Filter/Sequential MC, MCEM, etc.

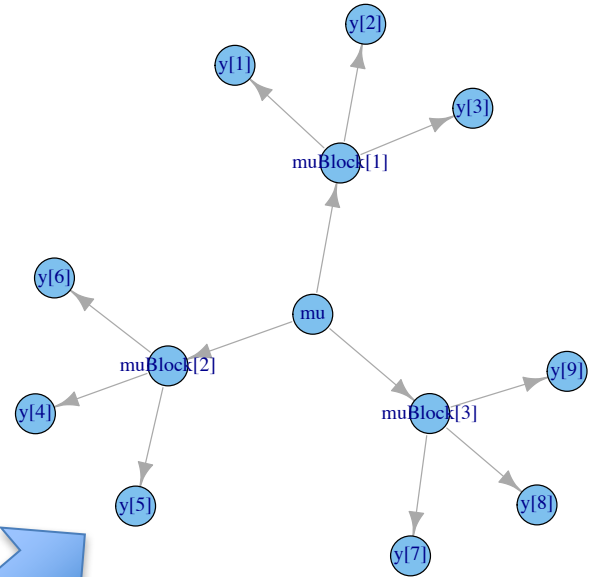
3. Algorithm specification

NIMBLE programming language within R → R/C++ algorithm object



User Experience: Creating a Model from BUGS

```
littersCode <- nimbleCode({
  for(j in 1:G) {
    for(l in 1:N) {
      r[i, j] ~ dbin(p[i, j], n[i, j]);
      p[i, j] ~ dbeta(a[j], b[j]);
    }
    mu[j] <- a[j]/(a[j] + b[j]);
    theta[j] <- 1.0/(a[j] + b[j]);
    a[j] ~ dgamma(1, 0.001);
    b[j] ~ dgamma(1, 0.001);
  }
})
```



1

Parse and process BUGS code.
Collect information in model object.

2

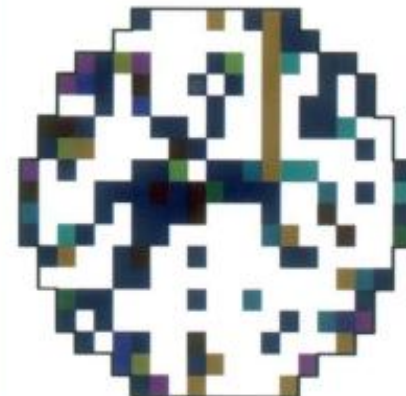
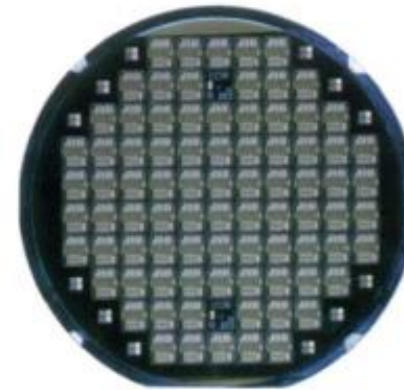
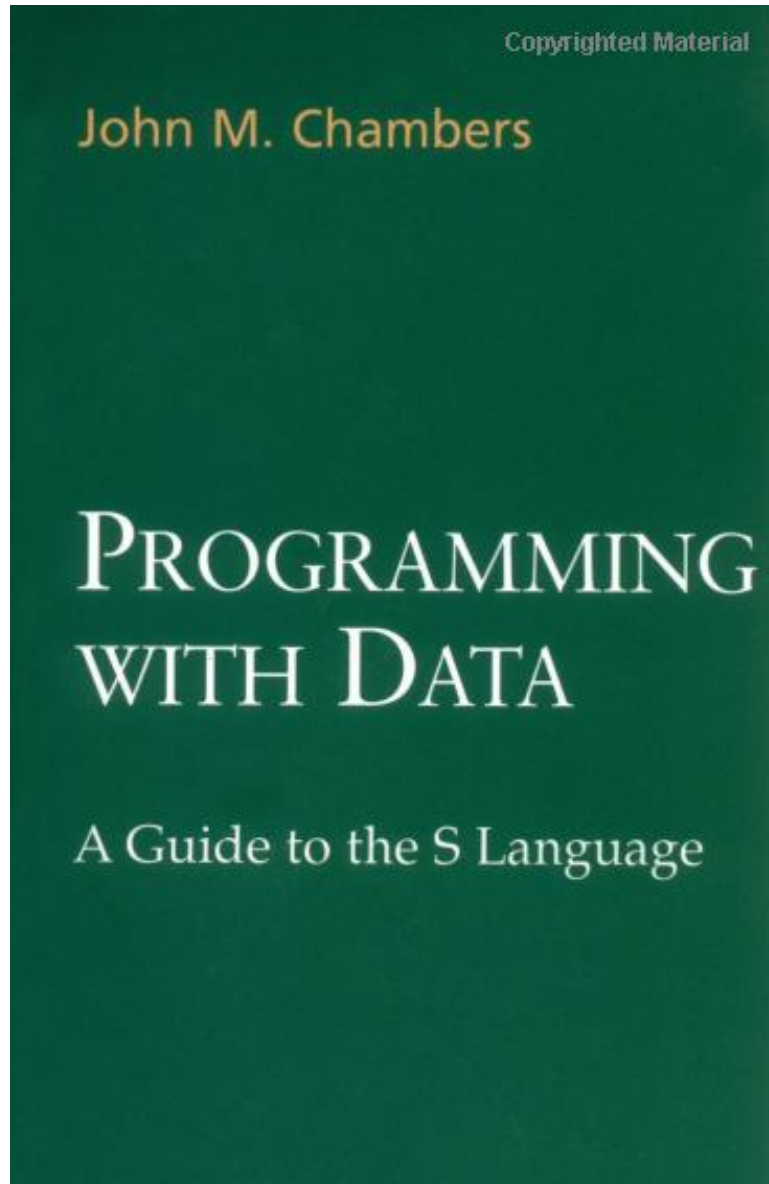
Use igraph plot method (we also use this to determine dependencies).

```
> littersModel <- nimbleModel(littersCode, constants = list(N = 16, G = 2), data = list(r = input$r))
> littersModel_cpp <- compileNimble(littersModel)
```

3

Provides variables and functions (calculate, simulate) for algorithms to use.

The Success of R



Programming with Models

You give NIMBLE:

```
littersCode <- nimbleCode( {  
  for(j in 1:G) {  
    for(l in 1:N) {  
      r[i, j] ~ dbin(p[i, j], n[i, j]);  
      p[i, j] ~ dbeta(a[j], b[j]);  
    }  
    mu[j] <- a[j]/(a[j] + b[j]);  
    theta[j] <- 1.0/(a[j] + b[j]);  
    a[j] ~ dgamma(1, 0.001);  
    b[j] ~ dgamma(1, 0.001); } )
```

You get this:

```
> littersModel$a[1] <- 5           # set values in model  
> simulate(littersModel, 'p')    # simulate from prior  
> p_deps <- littersModel$getDependencies('p') # model structure  
> calculate(littersModel, p_deps) # calculate probability density  
> getLogProb(pumpModel, 'r')
```

NIMBLE also extends BUGS: multiple parameterizations, named parameters, and user-defined distributions and functions.

User Experience: Specializing an Algorithm to a Model

```
littersModelCode <- modelCode({
  for(j in 1:G) {
    for(l in 1:N) {
      r[i, j] ~ dbin(p[i, j], n[i, j]);
      p[i, j] ~ dbeta(a[j], b[j]);
    }
    mu[j] <- a[j]/(a[j] + b[j]);
    theta[j] <- 1.0/(a[j] + b[j]);
    a[j] ~ dgamma(1, 0.001);
    b[j] ~ dgamma(1, 0.001);
  })
```

```
sampler_slice <- nimbleFunction(
  setup = function((model, mvSaved, control) {
    calcNodes <- model$getDependencies(control$targetNode)
    discrete <- model$getNodeInfo()[[control$targetNode]]$isDiscrete()
    [...snip...]
  })
  run = function() {
    u <- getLogProb(model, calcNodes) - rexp(1, 1)
    x0 <- model[[targetNode]]
    L <- x0 - runif(1, 0, 1) * width
    [...snip....]
  }
  ...
```

```
> littersMCMCconf <- configureMCMC(littersModel)
> littersMCMCconf$printSamplers()
[...snip...]
[3] RW sampler; targetNode: b[1], adaptive: TRUE, adaptInterval: 200, scale: 1
[4] RW sampler; targetNode: b[2], adaptive: TRUE, adaptInterval: 200, scale: 1
[5] conjugate_beta sampler; targetNode: p[1, 1], dependents_dbin: r[1, 1]
[6] conjugate_beta sampler; targetNode: p[1, 2], dependents_dbin: r[1, 2]
[...snip...]
> littersMCMCconf$addSampler('a[1]', 'slice', list(adaptInterval = 100))
> littersMCMCconf$addSampler('a[2]', 'slice', list(adaptInterval = 100))
> littersMCMCconf$addMonitors('theta')
> littersMCMC <- buildMCMC(littersMCMCspec)
> littersMCMC_Cpp <- compileNimble(littersMCMC, project = littersModel)
> littersMCMC_Cpp$run(20000)
```

User Experience: Specializing an Algorithm to a Model (2)

```
littersModelCode <- quote({  
  for(j in 1:G) {  
    for(l in 1:N) {  
      r[i, j] ~ dbin(p[i, j], n[i, j]);  
      p[i, j] ~ dbeta(a[j], b[j]);  
    }  
    mu[j] <- a[j]/(a[j] + b[j]);  
    theta[j] <- 1.0/(a[j] + b[j]);  
    a[j] ~ dgamma(1, 0.001);  
    b[j] ~ dgamma(1, 0.001);  
  })
```

```
buildMCEM <- nimbleFunction(  
  while(runtime(converged == 0)) {  
    ....  
    calculate(model, paramDepDetermNodes)  
    mcmcFun(mcmc.its, initialize = FALSE)  
    currentParamVals[1:nParamNodes] <- getValues(model,paramNodes)  
    op <- optim(currentParamVals, objFun, maximum = TRUE)  
    newParamVals <- op$maximum  
    .....  
  }
```

```
> littersMCEM <- buildMCEM(littersModel, latentNodes = 'p', mcmcControl = list(adaptInterval =  
50), boxConstraints = list( list('a', 'b'), limits = c(0, Inf))), buffer = 1e-6)  
> set.seed(0)  
> littersMCEM(maxit = 50, m1 = 500, m2 = 5000)
```

Modularity:

One can plug any MCMC sampler into the MCEM, with user control of the sampling strategy, in place of the default MCMC.

NIMBLE

1. Model specification

BUGS language → R/C++ model object

2. Algorithm library

MCMC, Particle Filter/Sequential MC, MCEM, etc.

3. Algorithm specification

NIMBLE programming language within R → R/C++ algorithm object

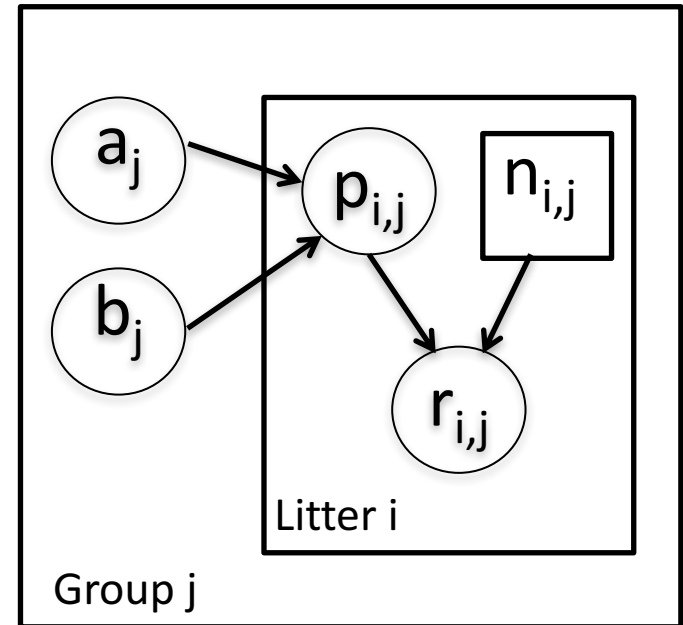
NIMBLE's algorithm library

- MCMC samplers:
 - Conjugate, adaptive Metropolis, adaptive blocked Metropolis, slice, elliptical slice sampler, particle MCMC, specialized samplers for particular distributions (Dirichlet, CAR)
 - Flexible choice of sampler for each parameter
 - User-specified blocks of parameters
 - Cross-validation, WAIC
- Sequential Monte Carlo (particle filters)
 - Various flavors
- MCEM
- Write your own

NIMBLE in Action: the Litters Example

Beta-binomial GLMM for clustered binary response data
Survival in two sets of 16 litters of pigs

```
littersModelCode <- nimbleCode({
  for(j in 1:2) {
    for(l in 1:16) {
      r[i, j] ~ dbin(p[i, j], n[i, j]);
      p[i, j] ~ dbeta(a[j], b[j]);
    }
    mu[j] <- a[j]/(a[j] + b[j]);
    theta[j] <- 1.0/(a[j] + b[j]);
    a[j] ~ dgamma(1, 0.001);
    b[j] ~ dgamma(1, 0.001);
  }
})
```

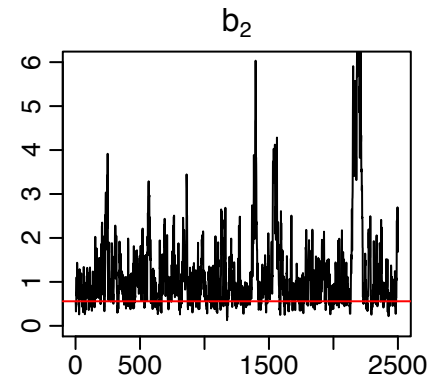
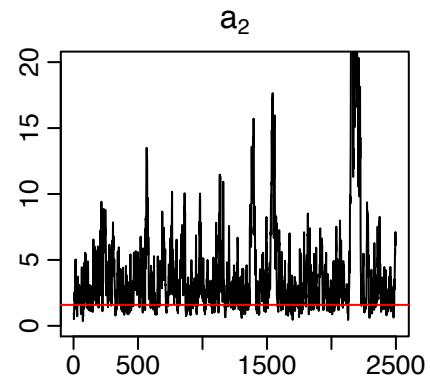
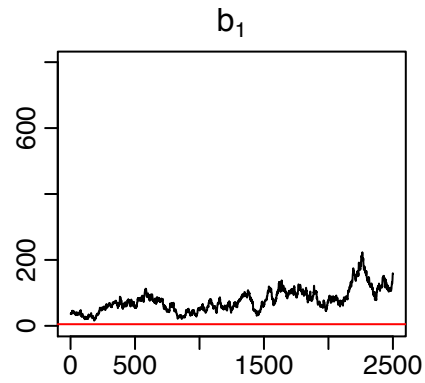
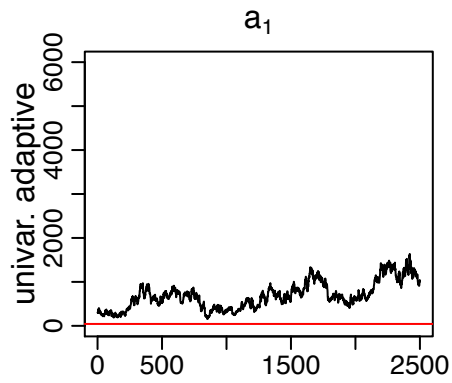


Challenges of the toy example:

- BUGS manual: “The estimates, particularly a_1 , a_2 suffer from extremely poor convergence, limited agreement with m.l.e.’s and considerable prior sensitivity. This appears to be due primarily to the parameterisation in terms of the highly related a_j and b_j , whereas direct sampling of μ_j and θ_j would be strongly preferable.”
- But that’s not all that’s going on. Consider the dependence between the p ’s and their a_j , b_j hyperparameters.
- And perhaps we want to do something other than MCMC.

Default MCMC: Gibbs + Metropolis

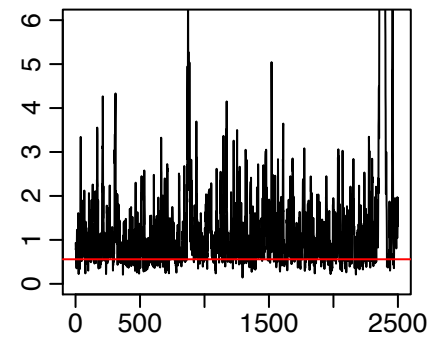
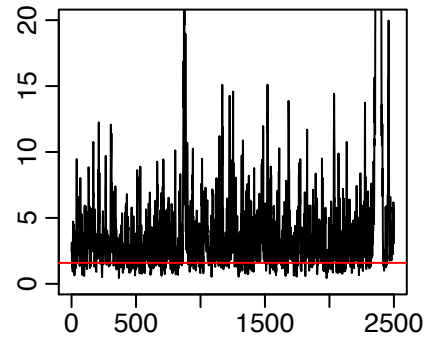
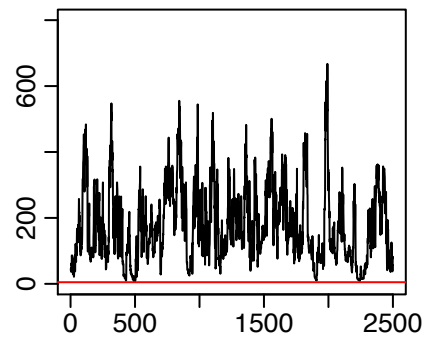
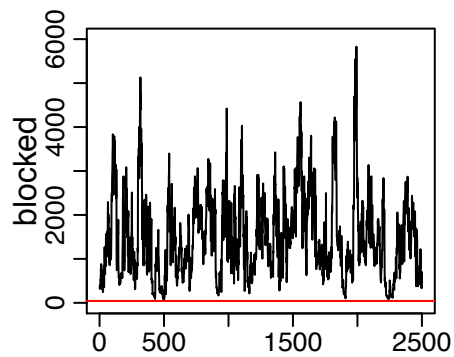
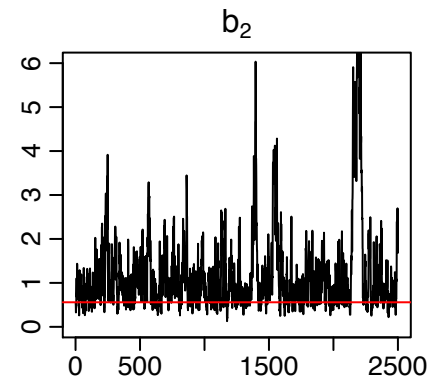
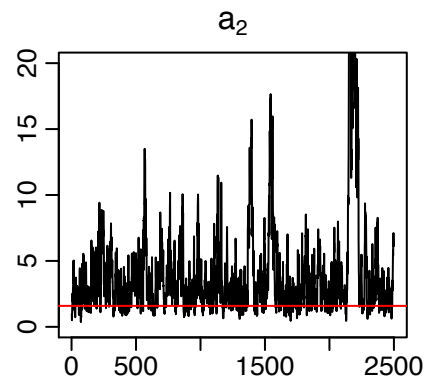
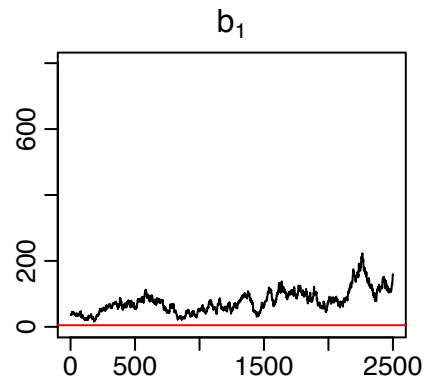
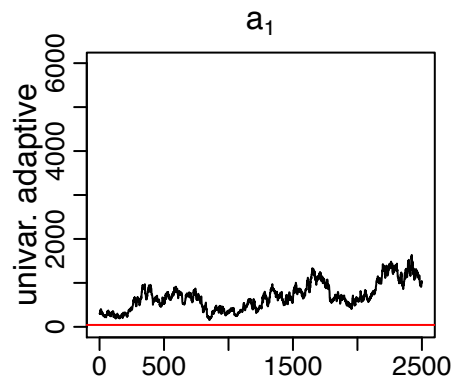
```
> littersMCMCspec <- configureMCMC(littersModel, list(adaptInterval = 100))  
> littersMCMC <- buildMCMC(littersMCMCspec)  
> littersMCMC_cpp <- compileNIMBLE(littersModel, project = littersModel)  
> littersMCMC_cpp$run(10000)
```



Red line is MLE

Blocked MCMC: Gibbs + Blocked Metropolis

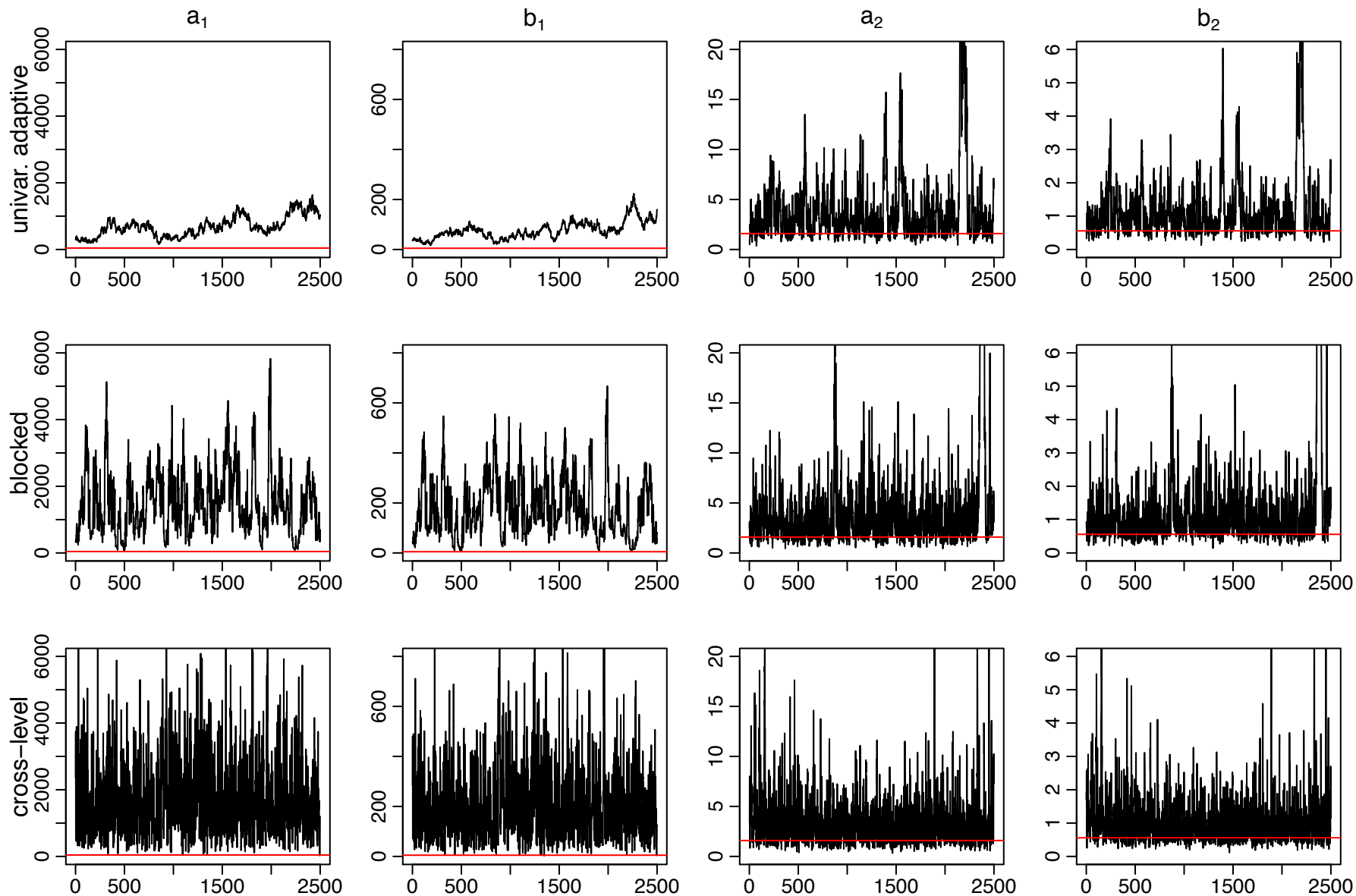
```
> littersMCMCspec2 <- configureMCMC(littersModel, list(adaptInterval = 100))
> littersMCMCspec2$addSampler(c('a[1]', 'b[1]'), 'RW_block', list(adaptInterval = 100))
> littersMCMCspec2$addSampler(c('a[2]', 'b[2]'), 'RW_block', list(adaptInterval = 100))
> littersMCMC2 <- buildMCMC(littersMCMCspec2)
> littersMCMC2_cpp <- compileNIMBLE(littersMCMC2, project = littersModel)
> littersMCMC2_cpp$run(10000)
```

Blocked MCMC: Gibbs + Cross-level Updaters

- Cross-level dependence is a key barrier in this and many other models.
- We wrote a new “cross-level” updater function using the NIMBLE DSL.
 - Blocked Metropolis random walk on a set of hyperparameters with conditional Gibbs updates on dependent nodes (provided they are in a conjugate relationship).
 - Equivalent to (analytically) integrating the dependent (latent) nodes out of the model.

```
> littersMCMCspec3 <- configureMCMC(littersModel, adaptInterval = 100)
> topNodes1 <- c('a[1]', 'b[1]')
> littersMCMCspec3$addSampler(topNodes1, 'crossLevel', list(adaptInterval = 100)
> topNodes2 <- c('a[2]', 'b[2]')
> littersMCMCspec3$addSampler(topNodes2, 'crossLevel', list(adaptInterval = 100)
> littersMCMC3 <- buildMCMC(littersMCMCspec3)
> littersMCMC3_cpp <- compileNIMBLE(littersMCMC3, project = littersModel)
> littersMCMC3_cpp$run(10000)
```



Litters MCMC: BUGS and JAGS

- Customized sampling possible in NIMBLE greatly improves performance.
- BUGS gives similar performance to the default NIMBLE MCMC
 - Be careful – values of `$sim.list` and `$sims.matrix` in R2WinBUGS output are randomly permuted
 - Mixing for `a2` and `b2` modestly better than default NIMBLE MCMC
- JAGS slice sampler gives similar performance as BUGS, but fails for some starting values with this (troublesome) parameterization
- NIMBLE provides user control and transparency.
 - NIMBLE is faster than JAGS on this example (if one ignores the compilation time), though not always.
 - Note: we're not out to build the best MCMC but rather a flexible framework for algorithms – we'd love to have someone else build a better default MCMC and distribute for use in our system.

NIMBLE

1. Model specification

BUGS language → R/C++ model object

2. Algorithm library

MCMC, Particle Filter/Sequential MC, MCEM, etc.

3. Algorithm specification

NIMBLE programming language within R → R/C++ algorithm object

NIMBLE: Programming With Models

We want:

- High-level processing (model structure) in R
- Low-level processing in C++

NIMBLE: Programming with Models

```
sampler_myRW <- nimbleFunction(  
  setup = function(model, mvSaved, targetNode, scale) {  
    calcNodes <- model$getNodeDependencies(targetNode)  
  },  
  run = function() {  
    model_lp_initial <- calculate(model, calcNodes)  
    proposal <- rnorm(1, model[[targetNode]], scale)  
    model[[targetNode]] <<- proposal  
    model_lp_proposed <- calculate(model, calcNodes)  
    log_MH_ratio <- model_lp_proposed - model_lp_initial  
  
    if(decide(log_MH_ratio)) jump <- TRUE  
    else jump <- FALSE  
    # .... Various bookkeeping operations ... #  })
```

2 kinds of
functions

NIMBLE: Programming with Models

```
sampler_myRW <- nimbleFunction(  
  setup = function(model, mvSaved, targetNode, scale) {  
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    model_lp_initial <- calculate(model, calcNodes)  
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    model[[targetNode]] <<- proposal  
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    log_MH_ratio <- model_lp_proposed - model_lp_initial  
  
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    else jump <- FALSE  
    # .... Various bookkeeping operations ... #  })
```

```
  },  
  run = function() {  
    model_lp_initial <- calculate(model, calcNodes)  
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    model[[targetNode]] <<- proposal  
    model_lp_proposed <- calculate(model, calcNodes)  
    log_MH_ratio <- model_lp_proposed - model_lp_initial  
  
    if(decide(log_MH_ratio)) jump <- TRUE  
    else jump <- FALSE  
    # .... Various bookkeeping operations ... #  })
```

query model
structure
ONCE

NIMBLE: Programming with Models

```
sampler_myRW <- nimbleFunction(  
  setup = function(model, mvSaved, targetNode, scale) {  
    calcNodes <- model$getNodeDependencies(targetNode)  
  },  
  run = function() {  
    model_lp_initial <- calculate(model, calcNodes)  
    proposal <- rnorm(1, model[[targetNode]], scale)  
    model[[targetNode]] <<- proposal  
    model_lp_proposed <- calculate(model, calcNodes)  
    log_MH_ratio <- model_lp_proposed - model_lp_initial  
  
    if(decide(log_MH_ratio)) jump <- TRUE  
    else jump <- FALSE  
    # .... Various bookkeeping operations ... #  })
```

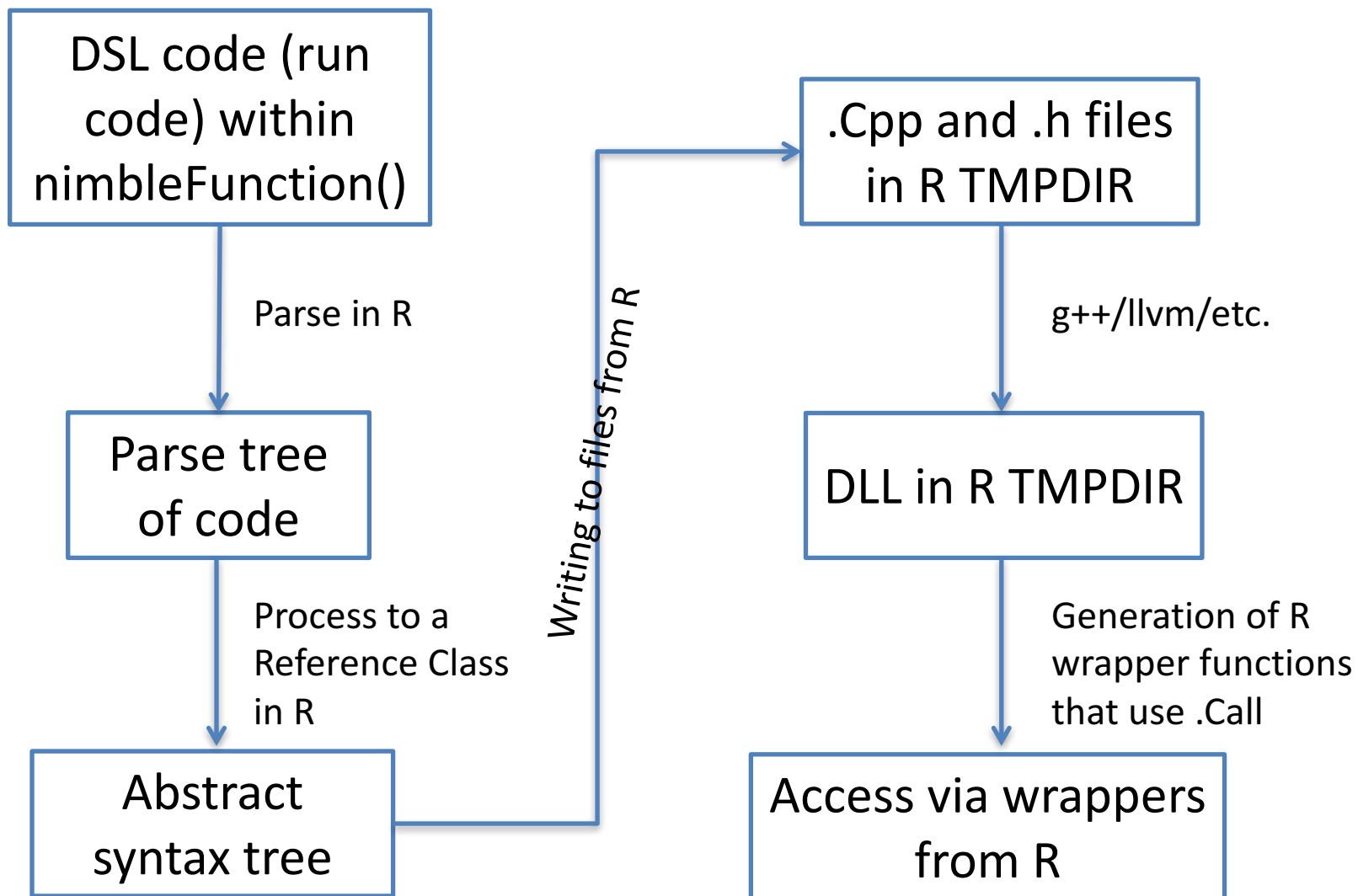
the actual
(generic)
algorithm

The NIMBLE compiler (run code)

Feature summary:

- R-like matrix algebra (using Eigen library)
- R-like indexing (e.g. `X[1:5,]`)
- Use of model variables and nodes
- Model calculate (`logProb`) and simulate functions
- Sequential integer iteration
- If-then-else, do-while
- Access to much of `Rmath.h` (e.g. distributions)
- Automatic R interface / wrapper
- Call out to your own C/C++ or back to R
- Many improvements / extensions planned

How an Algorithm is Processed in NIMBLE



Modular algorithms: particle MCMC

- Particle filter (SMC) approximates a posterior for latent states using a sample
- Traditionally used in state space models where the sample particles are propagated in time to approximate: $p(x_t | y_{1:t}, \theta)$

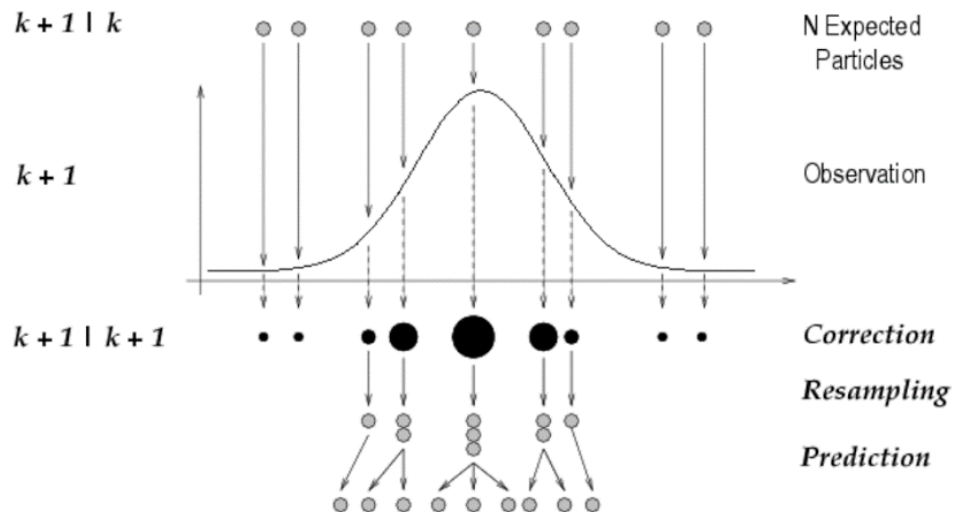


Figure 2: Particle filtering (from (Lehmann 2003))

- Weights from 'correction' step can be used to estimate $p(y_{1:t} | \theta)$
- Embed in MCMC to do approximate marginalization over $x_{1:t}$

Particle MCMC in NIMBLE

```
sampler_PMCMC <- nimbleFunction(  
  
  setup = function(model, mvSaved, target, control) {  
    ....  
    my_particleFilter <- buildAuxiliaryFilter(model, control$latents, control =  
list(saveAll = TRUE, smoothing = TRUE, lookahead = lookahead))  
    ....  
  },  
  run = function() {  
    ....  
    modelLP0 <- modelLL0 + calculate(model, target)  
    propValue <- rnorm(1, mean = model[[target]], sd = scale)  
    model[[target]] <<- propValue  
    modelLL1 <- my_particleFilter$run(m)  
    modelLP1 <- modelLL1 + calculate(model, target)  
    jump <- my_decideAndJump$run(modelLP1, modelLP0, 0, 0)  
    ....  
  })
```

Status of NIMBLE and Next Steps

- First release was June 2014 with regular releases since. Lots to do:
 - Improve the user interface and speed up compilation (in progress)
 - Scalability for large models (in progress)
 - Bayesian nonparametrics with Claudia Wehrhahn & Abel Rodriguez (UCSC) (in progress)
 - Refinement/extension of the DSL for algorithms (in progress)
 - e.g., automatic differentiation, parallelization
 - Additional algorithms written in NIMBLE DSL
 - e.g., normalizing constant calculation, Laplace approximations
- Interested?
 - Announcements: [nimble-announce](#) Google site
 - User support/discussion: [nimble-users](#) Google site
 - Write an algorithm using NIMBLE!
 - Help with development of NIMBLE: email nimble.stats@gmail.com or see github.com/nimble-dev

NIMBLE: What can I program?

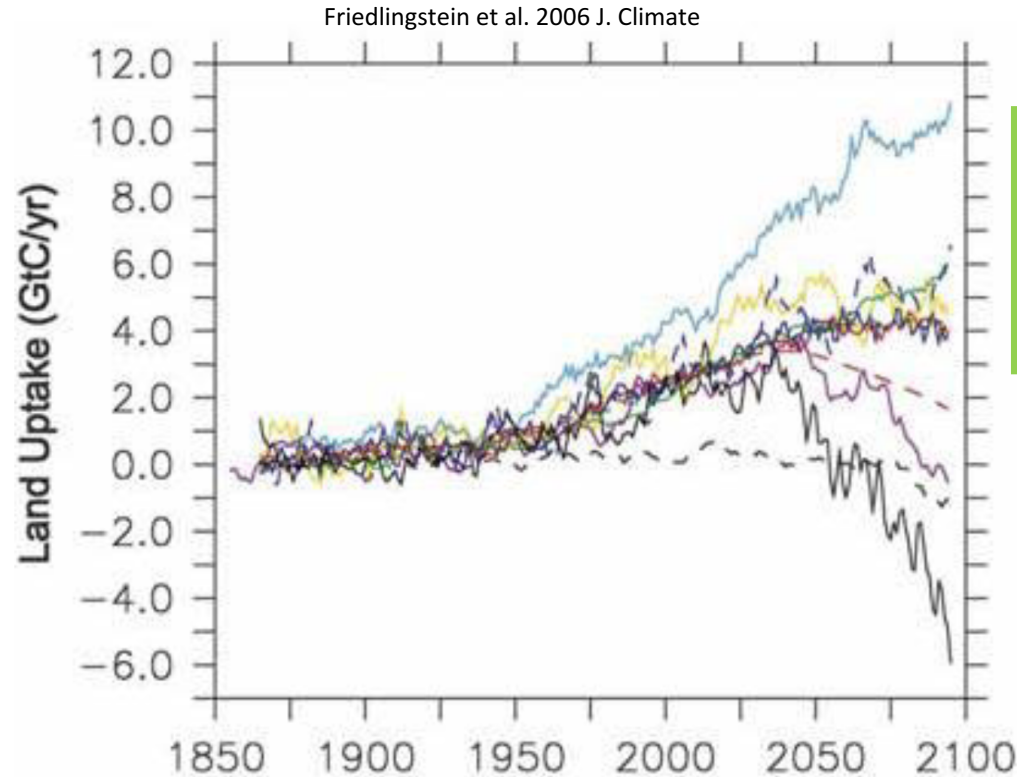
- Your own distribution for use in a model
- Your own function for use in a model
- Your own MCMC sampler for a variable in a model
- A new MCMC sampling algorithm for general use
- A new algorithm for hierarchical models
- An algorithm that composes other existing algorithms (e.g., MCMC-SMC combinations)

PaLEON Project

www3.nd.edu/~paleolab/paleonproject

Goal: Improve the predictive capacity of terrestrial ecosystem models

“This large variation among carbon-cycle models ... has been called ‘uncertainty’. I prefer to call it ‘ignorance’.”
- Prentice (2013) Grantham Institute



Critical issue: model parameterization and representation of decadal- to centennial-scale processes are poorly constrained by data

Approach: use historical and fossil data to estimate past vegetation and climate and use this information for model initialization, assessment, and improvement

PaLEON Statistical Applications

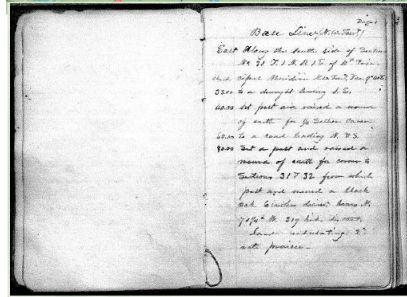
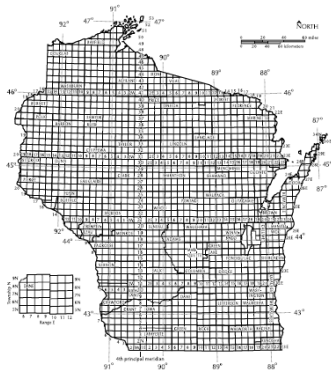
- Estimate spatially-varying composition and biomass of tree species from count and zero-inflated size data in year 1850
- Estimate temporal variations in temperature and precipitation over 2000 years from tree rings and lake/bog records
- Estimate tree composition spatially over 2000 years from fossil pollen in lake sediment cores
- Estimate biomass over time at a site from fossil pollen in lake sediment cores

Inferring Biomass from Pollen

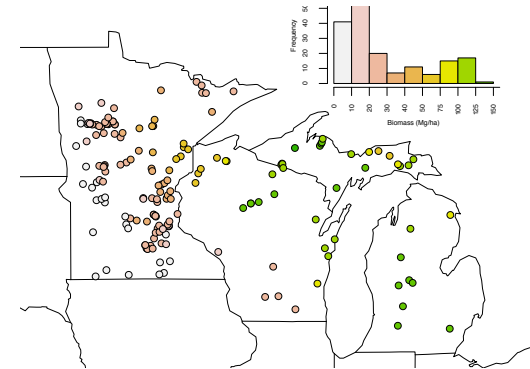
- Calibration with multiple spatial locations:
 - “Regress” multinomial counts on biomass
 - For each taxon, have proportion of the taxon be a smooth function of biomass using splines and parameters of Beta distributions:
 - $\alpha_k = \exp(Z(b)\beta_k)$
 - Estimate spline coefficients for each taxon
- Predict biomass over time at one location:
 - State space model for biomass over time
 - Fixed spline coefficients from calibration
 - Inverse problem (just Bayesian inference)
 - $\alpha_k = \exp(Z(\mathbf{b}_t)\beta_k)$

Predicting biomass from compositional data

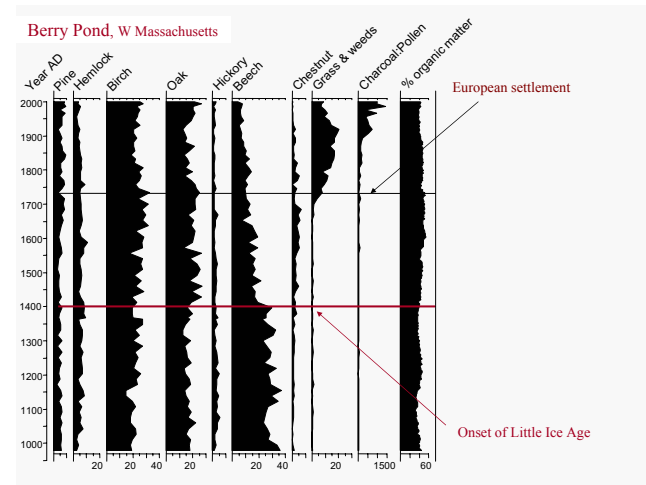
Calibration: at settlement time we have biomass estimates (based on survey data and a spatial model) and pollen composition (from sediment cores)



Biomass estimates at ponds



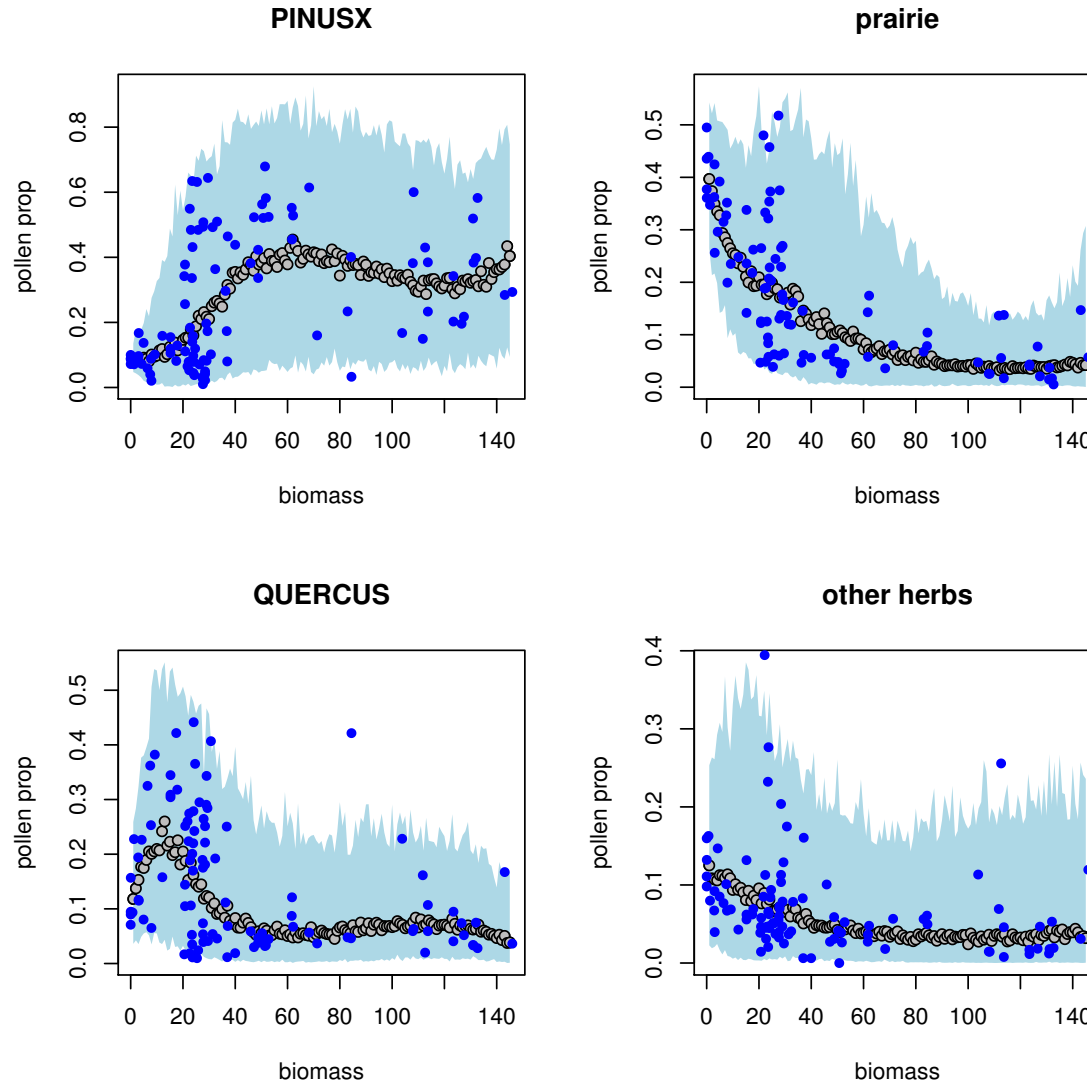
Prediction: based on calibration model and pollen composition over time, predict biomass



Calibration model

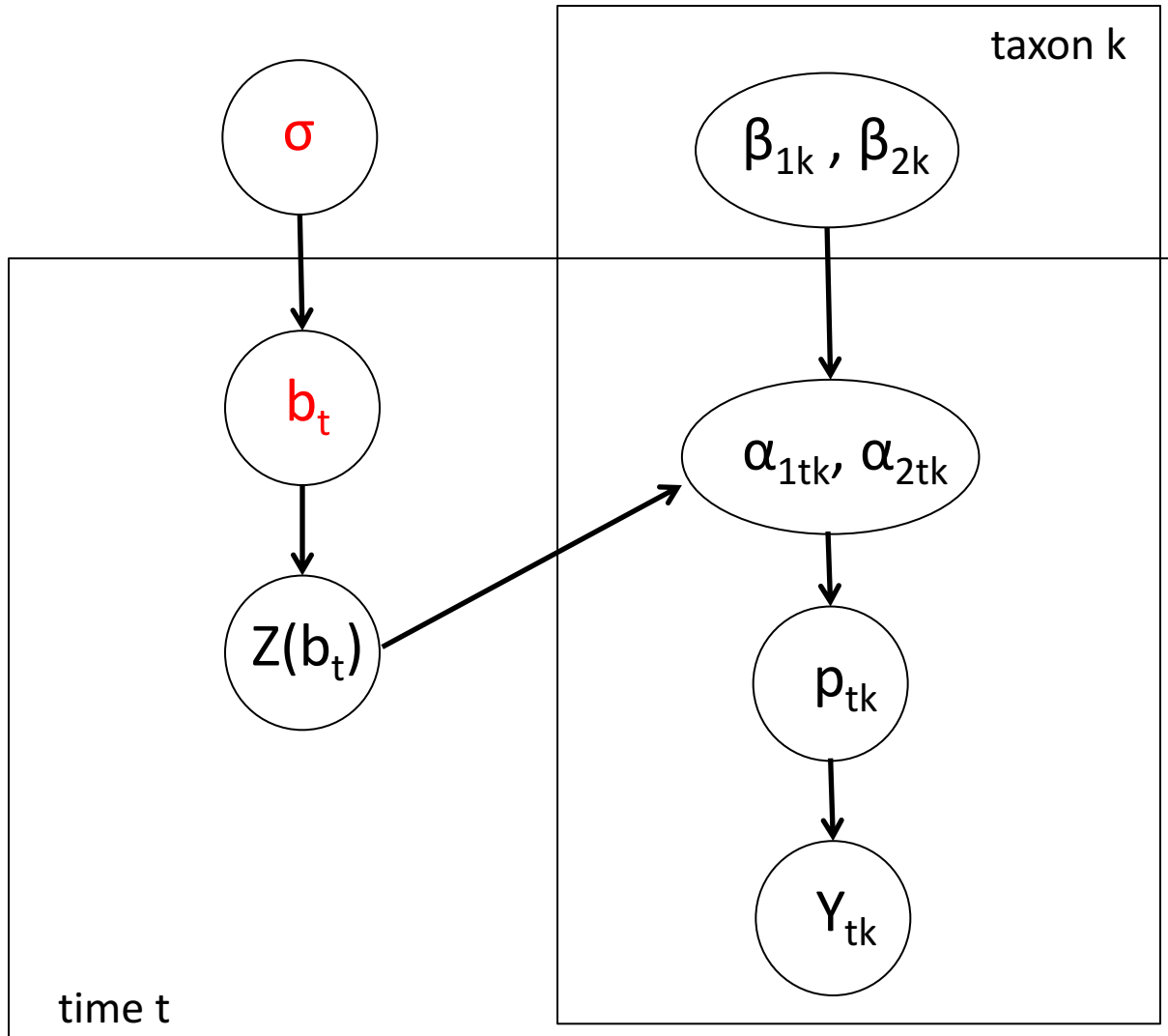
- Pollen proportion for each taxon determined by transformation of a flexible (spline) function of biomass
 - shape1 and shape2 parameters of beta distribution (stick-breaking prior for multinomial) are splines of biomass
 - Primary calibration parameters are spline coefficients
- Overdispersed multinomial likelihood for pollen counts given modeled proportions
- Fit in NIMBLE (could be fit in various other packages)

Calibration model fit



Mean and variability of modeled pollen proportions across ponds vary with biomass

Prediction Model



Prediction Model

```
for(t in 1:nTimes)
  Y[t, 1] ~ dbetabin(shape1[t, 1], shape2[t, 1], n[t])
  for(k in 2:(nTaxa-1)) {
    Y[t, k] ~ dbetabin(shape1[t, k], shape2[t, k], n[t]-sum(Y[t, 1:(k-1)]))
```

pollen likelihood

```
for(k in 1:nTaxa)
  for(t in 1:nTimes) {
    shape1[t, k] <- exp(Zb[t, 1:nKnots] %*% beta1[1:nKnots, k])
    shape2[t, k] <- exp(Zb[t, 1:nKnots] %*% beta2[1:nKnots, k])
  }
for(t in 1:nTimes)
  Zb[t, 1:nKnots] <- bspline(b[t], knots[1:nKnots])
```

latent predictor

```
for(t in 2:nTimes)
  b[t] ~ dGenPareto(3b[t-1]-3b[t-2]+b[t-3], sigma)
```

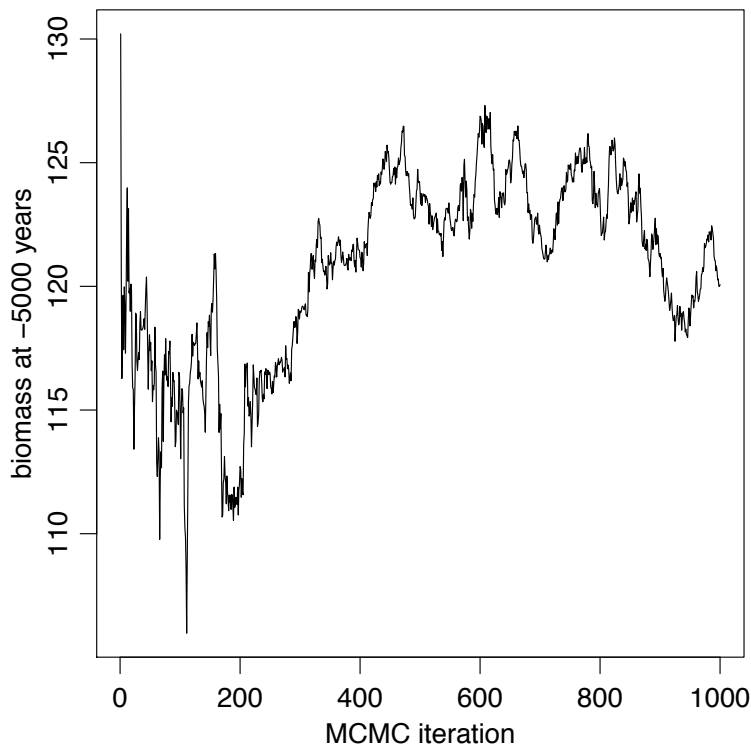
(nonstationary)
biomass evolution

```
sigma ~ dunif(0, 10) # Gelman (2006)
b[1] ~ dunif(0, 400)
```

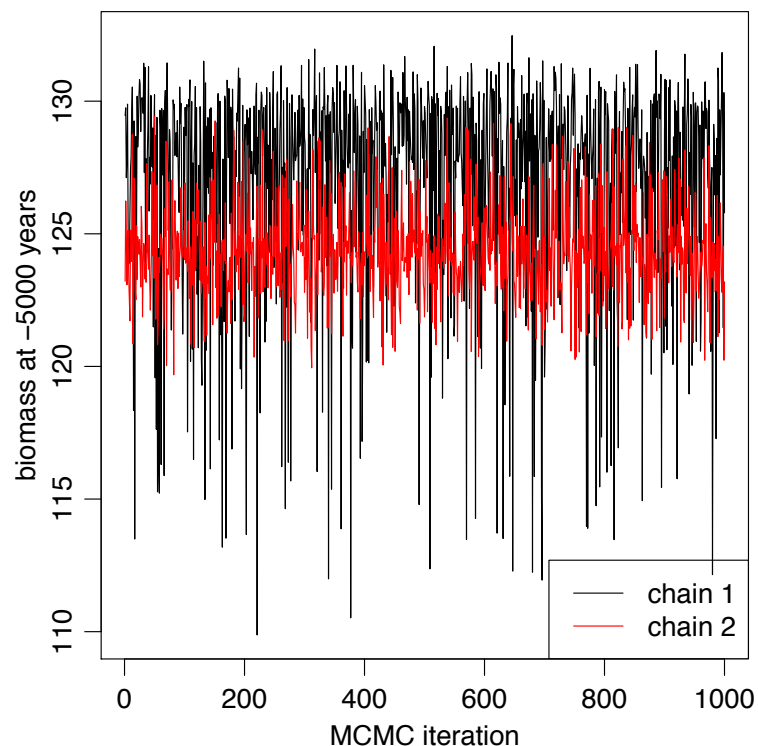
hyperpriors

MCMC performance

Mixing with data augmentation using default NIMBLE MCMC



Mixing in marginalized model using HMC in Stan



(recall non-differentiable spike at zero from generalized Pareto)

NIMBLE solution: customized MCMC sampler for $\{b[t-3], b[t-2], b[t-1], b[t], b[t+1], b[t+2], b[t+3]\}$, with a normal approximation to likelihood to generate good (quasi-conjugate) proposals.

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